







High-precision Power Analysis Through Sensing Technology

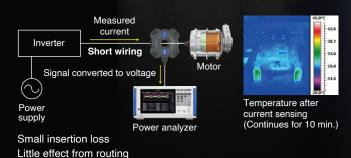
Superior affinity between power analyzers and current sensors

Hioki develops both power analyzers and current sensors. Advanced sensing technology is a prerequisite for accurate power analysis. Given the high affinity between current sensors and power analyzers, precise power analysis is possible.

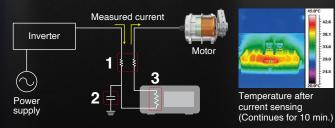


The current sensor method is an approach to making measurements that closely resemble the actual operating environment

Measurement example using the current sensor method



Measurement example using the direct wiring method

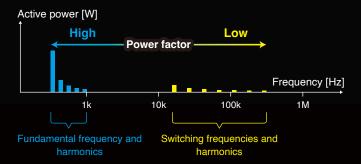


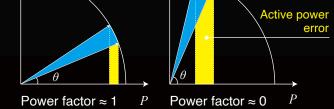
- 1 Wiring resistance loss due to long routing
- 2 Leakage current loss due to capacitive coupling
- 3 Instrument loss due to shunt resistance

Phase error

Important points in evaluating high-efficiency inverters

When evaluating the power conversion efficiency of an inverter, the inverter's input and output power are measured, and its efficiency is calculated. PWM (pulse width modulated) inverter output, which has been widely used in recent years, contains the fundamental and its harmonic, the switching frequencies, and its harmonic component. Since switching frequencies are high, current sensors that can measure over a wide bandwidth are needed for the measurement process.





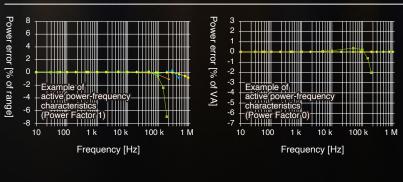
Active power spectogram for an inverter's output power.

The ability to measure low-powerfactor, high-frequency components is essential.

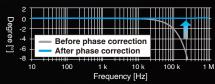
At low power factors, phase error has a significant effect on power error. **Phase accuracy of current sensor is important.**



Current sensor with defined phase accuracy can accurately measure power



HIOKI specifies the phase accuracy of current sensors for more accurate power measurement. By correcting the phase characteristics of the current sensor with a power analyzer, low power factor power can be accurately measured down to higher frequencies.

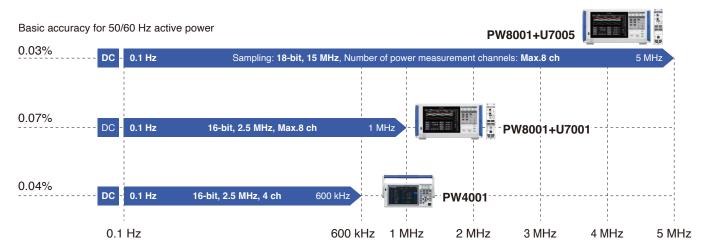


→ PW8001+U7005 (1500 V/50 A range)→ PW8001+U7001 (1500 V/50 A range)

→ PW4001 (1500 V/50 A range) → PW3390 (150 V/50 A range)

Example of the phase correction for the CT6904A AC/DC current sensor

Power analyzer lineup



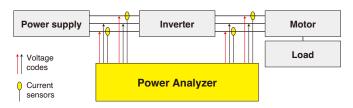
Measurement frequency band

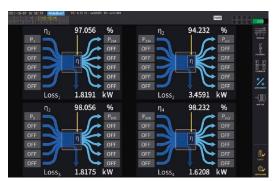
Applications

Power conversion efficiency evaluation of inverters

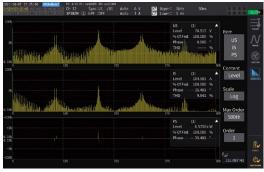


Measure input and output power for power conversion devices like inverters and calculate efficiency and loss.





Efficiency and loss calculations (PW8001)



Harmonic analysis of the 500th-order (PW8001)

Detect power conversion efficiency and loss

| Number of power measurement channels | | |
|--------------------------------------|--|--|
| PW8001 | Up to 8 channels (specified at time of purchase) | |
| PW4001 | 4 ch | |

| Efficiency and loss calculations | | |
|----------------------------------|---|--|
| PW8001 | Max.4 each for efficiency and loss (with Auto mode) | |
| PW4001 | Max.4 each for efficiency and loss (with Auto mode) | |

The PW8001's Auto mode automatically switches calculation formulas depending on the direction of power flow.

| Accuracy for active power* | DC | 50 Hz/60 Hz | 10 kHz |
|----------------------------|------------------|------------------|------------------|
| PW8001+U7005 | ±(0.02% + 0.03%) | ±(0.01% + 0.02%) | ±(0.05% + 0.05%) |
| PW8001+U7001 | ±(0.02% + 0.05%) | ±(0.02% + 0.05%) | ±(0.2% + 0.05%) |
| PW4001 | ±(0.03% + 0.01%) | ±(0.03% + 0.01%) | ±(0.2% + 0.05%) |

^{*±(%} of reading + % of range)

Harmonics measurement

| | Synchronization frequency range | Maximum analysis order |
|--------------|---------------------------------|---------------------------|
| PW8001+U7005 | 0.1 Hz to 1.5 MHz | 500th |
| PW8001+U7001 | 0.1 Hz to 1 MHz | 500th |
| PW4001 | 0.1 Hz to 600 kHz | 500th |

The instrument can perform harmonic analysis for each channel's voltage, current, and active power and display the results. The PW8001 and PW4001 can analyze harmonics for individual channels, and they can simultaneously measure harmonics in multiple circuits at different frequencies.

Common-mode rejection ratio (CMRR)

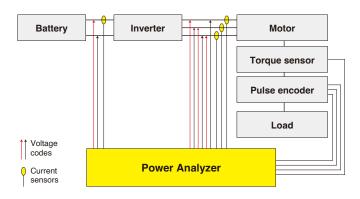
| | 50 Hz/60 Hz | 100 kHz |
|--------------|-------------------|-------------------|
| PW8001+U7005 | 120 dB or greater | 110 dB or greater |
| PW8001+U7001 | 100 dB or greater | 80 dB typical |
| PW4001 | 80 dB or greater | - |

When evaluating an equipment that produces noise, such as an inverter, it is essential to consider how effectively the device can withstand noise.

Evaluation of inverters and motors



Efficiency and loss can be calculated from the power on the input and output sides of inverters and motors. Torque meter and pulse encoder signals can be input to the power analyzer to simultaneously analyze and record the motor's torque, rotation speed, and mechanical output.



Motor analysis

| Number of motors that can be simultaneously analyzed | | |
|--|---------------|--|
| PW8001 | Max. 4 motors | |
| PW4001 | Max. 2 motors | |

Input signals from a torque meter and pulse encoder to analyze motor torque, speed, rotational direction, and electrical angle.

| user-defined calculations (used when calculating motor parameters) | | |
|--|-------------------------------|--|
| PW8001 | Up to 20 equations can be set | |
| PW4001 | Up to 20 equations can be set | |

Set calculation formulas as desired and display the results in real time. Calculate Ld and Lq motor parameters from electrical angle measurements.

| Correction of torque meter measurement error | | |
|--|--|--|
| PW8001 | Zero correction, nonlinear correction*, friction correction* | |
| PW4001 | Zero correction, nonlinear correction*, friction correction* | |

*Enter the calibration values and points for compensating the sensor's error to calibrate the torque meter's value.

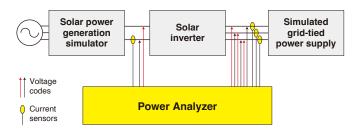
CAN or CAN FD communication

| PW8001 | Measured data can be converterd to CAN format and |
|--------|---|
| | output (output function) |
| PW4001 | ·Measured data can be converted to CAN format and |
| | output (output function) |
| | CAN data and measured data can be saved |
| | simultaneously (input function) |

Solar inverter efficiency measurements



Measure a solar inverter's input and output power and calculate efficiency and loss. Evaluate power generation systems that require measuring high voltages and multiple circuits, such as a multi-string solar inverter.



Maximum input voltage

| PW8001+U7005 | 1000 V AC/DC, ±2000 V peak |
|--------------|------------------------------------|
| PW8001+U7001 | 1000 V AC, 1500 V DC, ±2000 V peak |
| PW4001 | 1000 V AC, 1500 V DC, ±2000 V peak |

Use the VT1005 (option) to measure voltages of up to 5000 V with a power analyzer.

IEC standard compliant harmonic and flicker measurement

| | IEC harmonics measurement | IEC Flicker Measurement |
|--------|------------------------------|----------------------------|
| PW8001 | Yes | Yes |
| PW4001 | - | - |

Measure harmonics in compliance with the IEC 61000-4-7 standard and flicker in compliance with the IEC 61000-4-15 standard.

Multi-string solar inverters evaluation

| Optical link interface | | |
|------------------------|-------------------------------|--|
| PW8001 | Analysis of up to 16 channels | |
| PW4001 | - | |

Connect two power analyzers with the optical link interface to aggregate and analyze measured data on one instrument.

Power analyzer lineup

| Model | | PW8001+U7005 PW8001+U7001 | | PW4001 | | |
|----------------------|--|--|---|---|--|--|
| | Applications | For measurement of SiC and GaN inverters and reactor/transformer loss For measurement of high-efficiency IGBT inverters and solar inverters | | For portability and high accuracy | | |
| acy | Basic accuracy for 50/60 Hz power*1 | ±(0.01% + 0.02%) | ±(0.02% + 0.05%) | ±(0.03% + 0.01%) | | |
| Basic accuracy | Accuracy for DC power*1 | ±(0.02% + 0.03%) | ±(0.02% + 0.05%) | ±(0.03% + 0.01%) | | |
| | Accuracy for 10 kHz power*1 | ±(0.05% + 0.05%) | ±(0.2% + 0.05%) | ±(0.2% + 0.05%) | | |
| ag | Accuracy for 50 kHz power*1 | ±(0.15% + 0.05%) | ±(0.4% + 0.1%) | ±(0.4% + 0.1%) | | |
| | Measurement frequency band | DC, 0.1 Hz to 5 MHz | DC, 0.1 Hz to 1 MHz | DC, 0.1 Hz to 600kHz | | |
| | Number of power measurement channels | 1 to 8 ch specify U7001 or U7005 when pl | 4 channels | | | |
| | Voltage, current ADC sampling | 18-bit, 15 MHz | 16-bit, 2.5 MHz | 16-bit, 2,5 MHz | | |
| | Voltage range | 6 V, 15 V, 30 V, 60 V, 150 | 6 V, 15 V, 30 V, 60 V, 150 V, 300 V, 600 V, 1500 V | | | |
| Measurement | Current range | 40 mA to 2000 A*2 | probe1: 40 mA to 2000 A*2 probe2: 100 mV, 200 mV, 500 mV, 1 V, 2 V, 5 V | 40 mA to 8000 A*2 | | |
| | Data update rate | 1 ms, 10 ms, 5 | 50 ms, 200 ms | 1 ms, 10 ms, 50 ms, 200 ms | | |
| | Common-mode rejection ratio (CMRR) | 50/60 Hz: 120 dB or greater 100 kHz: 110 dB or greater | 50/60 Hz: 100 dB or greater 100 kHz: 80 dB typical | 50 Hz/60 Hz: 80 dB or greater | | |
| | Temperature coefficient | 0.019 | %/°C | 0.005 %/°C | | |
| | Voltage input method | Photoisolated input, resistor voltage division | Isolated input, resistor voltage division | Isolated input, resistor voltage division | | |
| | Current input method | Isolated input froi | m current sensor | Isolated input from current sensor | | |
| | External current sensor input | Yes (ME15W) | Yes (ME15W) | | | |
| Currentinput | Power supplied to external current sensor | Ye | Yes | | | |
| Curr | Current sensor phase shift calculation | Yes (i | Yes (auto) | | | |
| Voltage input | Maximum input voltage | 1000 V, ±2000 V peak | 1000 V AC, 1500 V DC, ±2000 V peak | 1000 V AC, 1500 V DC, ±2000 V peak | | |
| | Maximum rated line-to-ground voltage | 600 V CAT III 1000 V CAT II | 600 V AC/1000 V DC CAT III 1000 V AC/1500 V DC CAT II | AC 600 V/DC 1000 V CAT III AC 1000 V/DC 1500 V CAT II | | |
| | Efficiency and loss calculations | Ye (Max.4 each for efficie | Yes (Max.4 each for efficiency and loss) | | | |
| | Motor analysis Number of channels Input format | Ye: Max. 4 Analog DC, fre | Yes*4 Maximum 2 motors Analog DC, frequency, pulse | | | |
| = | Torque meter correction | Zero correction, nonlinear c | Zero correction, nonlinear correction, friction correction | | | |
| Analysis/calculation | Harmonics measurement | Yes (8, for each channel) | Yes (8, for each channel) | Yes (4 for each channel) | | |
| calcı | Max. analysis order Synchronization frequency range | 500th 0.1 Hz to 1.5 MHz | 500th 0.1 Hz to 1 MHz | 500th 0.1 Hz to 600 kHz | | |
| ysis/ | IEC harmonics measurement | Ye | - | | | |
| Ana | IEC flicker measurement | | Yes | | | |
| | FFT spectrum analysis | Yes (DC to 4 MHz) | _ | | | |
| | User-defined calculations | Yes (Be to 4 (VIII 12) | Yes | | | |
| | Delta conversion | Yes (Δ- | Yes (Δ-Y, Y-Δ) | | | |
| | D/A output | Yes*4 (waveform outpu | Yes*416ch (waveform output, analog output) | | | |
| ay | Display | 10.1" WVGA T | | 10.1" WVGA TFT color LCD | | |
| Display | Touch screen | Ye | es | Yes | | |
| _ | External storage media | USB | USB 3.0 | | | |
| | LAN (100BASE-TX, 1000BASE-T) | Ye | Yes | | | |
| | GP-IB | Ye | - | | | |
| ace | RS-232C | Yes (maximum | - | | | |
| Interface | External control | Yes (maximum | Yes | | | |
| | | | | | | |
| | Synchronization of multiple instruments | Yes (up to 4 | Yes (up to 8 instruments) | | | |
| | Optical link | Yes | - | | | |
| | CAN or CAN FD | Yes | Yes | | | |
| Dir | nensions, weight (W×H×D) | 430 mm × 221 (16.93 in.× 8.70 14 kg (49 | in. × 14.21 in.), | 361 mm× 176 mm × 135 mm (14.21 in.× 6.93 in.× 5.31 in.) 4.6 kg (162.26 oz.) | | |
| | | | · · | , , | | |

Model No. (Order code)

PW8001

| Model | Number of channels | Motor analysis | Waveform and D/A output | CAN or CAN FD interface | Optical link interface |
|-----------|---|----------------|-------------------------|-------------------------|---------------------------|
| PW8001-01 | 1 to 8 channels, | - | - | - | - |
| PW8001-02 | specify U7001 or U7005 | - | Yes | - | - |
| PW8001-03 | when placing an order | - | - | Yes | - |
| PW8001-04 | (mixed available) | - | - | - | Yes |
| PW8001-05 | USBC Sharpenanan Vite Addition | - Yes - | | - | Yes |
| PW8001-06 | | - | - | Yes | Yes |
| PW8001-11 | 5 con 1 con | Yes | - | - | - |
| PW8001-12 | CALLET CALLET | Yes | Yes | - | - |
| PW8001-13 | 2 | Yes | - | Yes | - |
| PW8001-14 | | Yes | - | - | Yes |
| PW8001-15 | U7001 U7005 | Yes | Yes | - | Yes |
| PW8001-16 | 0.000 | Yes | - | Yes | Yes |

PW4001

| Model Number of channels | | Motor analysis | Waveform and D/A output | CAN or CAN FD interface | DC power supply operation | |
|--------------------------|------|----------------|----------------------------|-------------------------|---------------------------|--|
| PW4001-01 | 4 ch | - | - | Yes | - | |
| PW4001-02 | 4 ch | - | Yes | Yes | - | |
| PW4001-03 | 4 ch | Yes | - | Yes | - | |
| PW4001-04 | 4 ch | - | - | Yes | Yes | |
| PW4001-05 | 4 ch | Yes | Yes | Yes | Yes | |







PW8001-15 Four U7001 units installed Four U7005 units installed





PW4001

Current sensor lineup

| Model | Appearance | Rated current | Maximum peak current | Frequency range | Amplitude accuracy 50 Hz/ 60 Hz | Diameter of measurable conductors | Cable length | Automatic phase correction ¹ | Operating temperature | |
|-------------------------|--------------------------|----------------------|-------------------------------|--------------------------------|---------------------------------------|-----------------------------------|---|---|------------------------------------|--|
| Pass-through | Pass-through types | | | | | | | | | |
| CT6862-05 | | 50 Arms | ±141 A peak | DC to 1 MHz | ±0.05 % rdg ±0.01 % f.s. | φ 24 mm (0.94 in.) | 3 m (9.84 ft.) | - | -30°C to 85°C -22°F to 185°F | |
| CT6872 CT6872-01 | | 50 Arms | ±200 A peak | DC to 10 MHz | ±0.03 % rdg ±0.007 % f.s. | φ 24 mm (0.94 in.) | 3 m (9.84 ft.) 10 m (32.81 ft) | Yes | -40°C to 85°C -40°F to 185°F | |
| CT6863-05 | | 200 Arms | ±565 A peak | DC to 500 kHz | ±0.05 % rdg ±0.01 % f.s. | φ 24 mm (0.94 in.) | 3 m (9.84 ft.) | - | -30°C to 85°C -22°F to 185°F | |
| CT6873 CT6873-01 | | 200 Arms | ±350 A peak ² | DC to 10 MHz | ±0.03 % rdg ±0.007 % f.s. | φ 24 mm (0.94 in.) | 3 m (9.84 ft.) 10 m (32.81 ft) | Yes | -40°C to 85°C -40°F to 185°F | |
| CT6875A CT6875A-1 | | 500 Arms | ±1500 A peak ² | DC to 2 MHz DC to 1.5 MHz | 0.04 % rdg ±0.008 % f.s. | φ 36 mm (1.42 in.) | 3 m (9.84 ft.) 10 m (32.81 ft) | Yes | -40°C to 85°C -40°F to 185°F | |
| CT6904A CT6904A-1 | | 500 Arms | ±1000 A peak ² | DC to 4 MHz DC to 2 MHz | ±0.02 % rdg ±0.007 % f.s. | ф32 mm (1.26 in.) | 3 m (9.84 ft.) 10 m (32.81 ft) | Yes | -10°C to 50°C 14°F to 122°F | |
| CT6904A-2 CT6904A-3 | | 800 Arms | ±1200 A peak ⁻² | DC to 4 MHz DC to 2 MHz | ±0.025 % rdg ±0.009 % f.s. | ф32 mm (1.26 in.) | 3 m (9.84 ft.) 10 m (32.81 ft) | Yes | -10°C to 50°C 14°F to 122°F | |
| CT6876A CT6876A-1 | | 1000 Arms | ±1800 A peak ⁻² | DC to 1.5 MHz DC to 1.2 MHz | 0.04 % rdg ±0.008 % f.s. | φ 36 mm (1.42 in.) | 3 m (9.84 ft.) 10 m (32.81 ft) | Yes | -40°C to 85°C -40°F to 185°F | |
| CT6877A CT6877A-1 | Q | 2000 Arms | ±3200 A peak ² | DC to 1 MHz | 0.04 % rdg ±0.008 % f.s. | ф80 mm (3.15 in.) | 3 m (9.84 ft.) 10 m (32.81 ft) | Yes | -40°C to 85°C -40°F to 185°F | |
| Clamp types | | | | | | | | | | |
| CT6830 | NEW | 2 Arms | ±4.3 A peak | DC to 100 kHz | ±0.3 % rdg ±0.05 % f.s. | φ5 mm (0.20 in.) | 4 m, 20 cm ⁻⁴ (13.12 ft., 7.87 in.) | Yes | -40°C to 85°C (-40°F to 185°F) | |
| CT6831 | NEW | 20 Arms | ±43 A peak | DC to 100 kHz | ±0.3 % rdg ±0.01 % f.s. | φ5 mm (0.20 in.) | 4 m, 20 cm ⁻⁴ (13.12 ft., 7.87 in.) | Yes | -40°C to 85°C (-40°F to 185°F) | |
| CT6833 CT6833-01 | NEW | 200 Arms | ±600 A peak | DC ~ 50 kHz | ±0.07% rdg ±0.007% f.s. | φ 20 mm (0.79 in.) | 5 m(16.40 ft.) 10 m(32.81 ft.) | Yes | -40 °C ~ 85 °C (-40°F to 185°F) | |
| CT6834 CT6834-01 | NEW | 500 Arms | ±800 A peak | DC ~ 50 kHz | ±0.07% rdg ±0.007% f.s. | φ 20 mm (0.79 in.) | 5 m(16.40 ft.) 10 m(32.81 ft.) | Yes | -40 °C ~ 85 °C (-40°F to 185°F) | |
| 9272-05 | 91 | 20 Arms, 200 Arms | ±71 Apeak, ±430 Apeak | 1 Hz to 100 kHz | ±0.3 % rdg ±0.01 % f.s. | φ46 mm (1.81 in.) | 3 m (9.84 ft.) | - | 0°C to 50°C 32°F to 122°F | |
| CT6841A | | 20 Arms | ±60 A peak ² | DC to 2 MHz | ±0.2 % rdg ±0.01 % f.s. | ф20 mm (0.79 in.) | 3 m (9.84 ft.) | Yes | -40°C to 85°C -40°F to 185°F | |
| CT6843A | 1 | 200 Arms | ±600 A peak ² | DC to 700 kHz | ±0.2 % rdg ±0.01 % f.s. | ф20 mm (0.79 in.) | 3 m (9.84 ft.) | Yes | -40°C to 85°C -40°F to 185°F | |
| CT6844A | 1 | 500 Arms | ±800 A peak ² | DC to 500 kHz | ±0.2 % rdg ±0.01 % f.s. | ф20 mm (0.79 in.) | 3 m (9.84 ft.) | Yes | -40°C to 85°C -40°F to 185°F | |
| CT6845A | 4 | 500 Arms | ±1500 A peak ² | DC to 200 kHz | ±0.2 % rdg ±0.01 % f.s. | ф50 mm (1.97 in.) | 3 m (9.84 ft.) | Yes | -40°C to 85°C -40°F to 185°F | |
| CT6846A | 4 | 1000 Arms | ±1900 A peak ⁻² | DC to 100 kHz | ±0.2 % rdg ±0.01 % f.s. | ф50 mm (1.97 in.) | 3 m (9.84 ft.) | Yes | -40°C to 85°C -40°F to 185°F | |
| Direct-wired types | | | | | | | | | | |
| PW9100A-3 ⁻³ | - in in in | 50 Arms | ±200 A peak ² | DC to 3.5 MHz | ±0.02 % rdg ±0.005 % f.s. | M6 screw terminals | 3 ch | Yes | 0°C to 40°C 32°F to 104°F | |
| PW9100A-4 ⁻³ | indicated and the second | 50 Arms | ±200 A peak ⁻² | DC to 3.5 MHz | ±0.02 % rdg ±0.005 % f.s. | M6 screw terminals | 4 ch | Yes | 0°C to 40°C 32°F to 104°F | |

^{*1:} When using PW8001 *2: Within 20 ms and 40°C (104°F) or less *3: Special specification PW9100A with a rated current of 5A can also be ordered.

*4: Between sensor to multiplexer, Between multiplexer to output connector



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