BT4560-50 BT4560-60



Instruction Manual

BATTERY IMPEDANCE METER



Check for the latest edition and other language versions.





Read carefully before use. Keep for future reference.

Safety Information ▶ p.3

Troubleshooting

▶ p.131

Names and Functions of Parts ▶ p.14

p.14 Error display and remedy

▶ p.135

Basic Measurement

▶ p.23

ΕN

600688380

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Appx.

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Introduction

Thank you for purchasing the HIOKI BT4560-50, BT4560-60 Battery Impedance Meter. To obtain maximum performance from the instrument, please read this manual first, and keep it handy for future reference.

Information on download site

For details on the product application, the update file for the instrument, and the instruction manual, please check Hioki's website:



An ISO file is a CD or DVD image file. When double-clicked, it will be recognized as a drive and become available for use.



Product registration

Register your product in order to receive important product information. https://www.hioki.com/global/support/myhioki/registration



Refer to the following instruction manuals according to your application.

Name of the instruction manual	Format
Instruction Manual (this manual)	Hard copy
Communications Command Instruction Manual	PDF (Download)

Trademarks

Excel, Microsoft Edge and Windows are trademarks of the Microsoft group of companies.

Verifying Package Contents

When you receive the instrument, inspect it carefully to ensure that no damage occurred during shipping.

In particular, check the accessories, panel switches, and connectors. If damage is evident, or if it fails to operate according to the specifications, contact your authorized Hioki distributor or reseller. Confirm that these contents are provided.

BT4560-50, BT4560-60 Battery Impedance Meter	Zero Adjustment Board
□ Power Cord	 Instruction Manual Please visit Hioki's website to check for versions
	in other language.
USB Cable (A-B type)	The USB driver, application software, and communications command instruction manual can be downloaded from Hioki's website. See "Information on download site" (p. 1)

Options (p. A12)

The options listed below are available for the instrument. To order an option, please contact yourauthorized Hioki distributor or reseller. Options are subject to change. Please check Hioki's website for the latestinformation.

L2002 Clip Type Probe

L2003 Pin Type Probe

Z2005 Temperature Sensor

9637 RS-232C Cable (9pin-9pin/1.8 m)

9642 LAN Cable(Straight-to-cross conversion connector included, 5 m)

SW1001 Switch Mainframe

(SW9002 Multiplexer Module and L2004 Connection Cable are required separately)

(SW9002 Switch Mainframe

Cable are required separately)

Safety Information

This instrument is designed to conform to IEC 61010 Safety Standards, and has been thoroughly tested for safety prior to shipment. However, using the instrument in a way not described in this manual may negate the provided safety features.

Before using the instrument, be certain to carefully read the following safety notes.

M DANGER



Mishandling during use could result in injury or death, as well as damage to the instrument. Be certain that you understand the instructions and precautions in the manual before use.

MARNING



With regard to the electricity supply, there are risks of electric shock, heat generation, fire, and arc discharge due to short circuits. If persons unfamiliar with electricity measuring instrument are to use the instrument, another person familiar with such instruments must supervise operations.

Notation

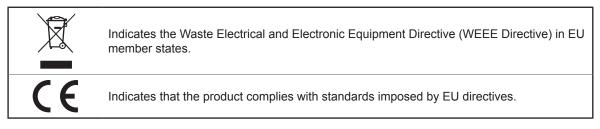
In this manual, the risk seriousness and the hazard levels are classified as follows.

<u> </u>	Indicates an imminently hazardous situation that will result in death or serious injury to the operator.	
WARNING Indicates a potentially hazardous situation that may result in death or serious injute the operator.		
⚠ CAUTION	Indicates a potentially hazardous situation that may result in minor or moderate injury to the operator or damage to the instrument or malfunction.	
IMPORTANT	Indicates information related to the operation of the instrument or maintenance tasks with which the operators must be fully familiar.	
A	Indicates a high voltage hazard. If a particular safety check is not performed or the instrument is mishandled, this may give rise to a hazardous situation; the operator may receive an electric shock, may get burnt or may even be fatally injured.	
\Diamond	Indicates prohibited actions.	
0	Indicates the action which must be performed.	
*	* Additional information is presented below.	
[]	Setting items and names on the screen are indicated in brackets [].	
SET (Bold character)	Bold characters within the text indicate operating key labels.	

Symbols on the instrument

\triangle	Indicates cautions and hazards. When the symbol is printed on the instrument, refer to a corresponding topic in the Instruction Manual.
	Indicates the ON side of the power switch.
0	Indicates the OFF side of the power switch.
4	Indicates a grounding terminal.
===	Indicates DC (Direct Current).
\sim	Indicates AC (Alternating Current).

Symbols for various standards



Accuracy

We define measurement tolerances in terms of rdg. (reading) and dgt. (digit) values, with the following meanings:

rdg.	(Reading or displayed value) The value currently being measured and indicated on the measuring instrument.
dgt.	(Resolution) The smallest displayable unit on a digital measuring instrument, i.e., the input value that causes the digital display to show a "1" as the least-significant digit.

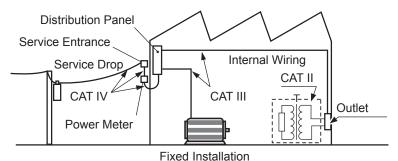
Measurement categories

To ensure safe operation of measurement instruments, IEC 61010 establishes safety standards for various electrical environments, categorized as CAT II to CAT IV, and called measurement categories.

DANGER



- Using a measuring instrument in an environment designated with a highernumbered category than that for which the instrument is rated could result in a severe accident, and must be carefully avoided.
- Using a measuring instrument without categories in an environment designated with the CAT II to CAT IV category could result in a severe accident, and must be carefully avoided.
- CAT II: When directly measuring the electrical outlet receptacles of the primary electrical circuits in equipment connected to an AC electrical outlet by a power cord (portable tools, household appliances, etc.).
- CAT III: When measuring the primary electrical circuits of heavy equipment (fixed installations) connected directly to the distribution panel, and feeders from the distribution panel to outlets.
- CAT IV: When measuring the circuit from the service drop to the service entrance, and to the power meter and primary overcurrent protection device (distribution panel).



Operating Precautions

Follow these precautions to ensure safe operation and to obtain the full benefits of the various functions. Use of the instrument should confirm not only to its specifications, but also to the specifications of all accessories, options, and other equipment in use.

DANGER



This instrument carries a maximum electric current up to 1.5 A to the measuring object. Do not measure the primary battery. Doing so may cause damage to the measuring object.



Battery may cause ignition and damage due to overcharge/over discharge. Be certain in managing battery voltage when measuring.

MARNING

If the measurement probe or the instrument is damaged, there is a risk of electric shock. Before using the instrument, perform the following inspection.



- Before using the instrument, check that the coating of the measurement probes are neither ripped nor torn and that no metal parts of connection cord are exposed. Using the instrument under such conditions could result in electrocution. Replace the measurement probes with those specified by our company.
- Before using the instrument for the first time, verify that it operates normally to ensure that no damage occurred during storage or shipping. If you find any damage, contact your authorized Hioki distributor or reseller.

Instrument installation

Installing the instrument in inappropriate locations may cause a malfunction of instrument or may give rise to an accident. Avoid the following locations.

For details on the operating temperature and humidity, see the specifications p. 129.

MARNING

- · Exposed to direct sunlight or high temperature
- · Exposed to corrosive or combustible gases
- · Exposed to water, oil, chemicals, or solvents



- Exposed to high humidity or condensation
- · Exposed to a strong electromagnetic field or electrostatic charge
- Exposed to high quantities of dust particles
- Near induction heating systems (such as high-frequency induction heating systems and IH cooking equipment)
- · Susceptible to vibration

Installation

To prevent overheating, be sure to leave the specified clearances around the instrument.

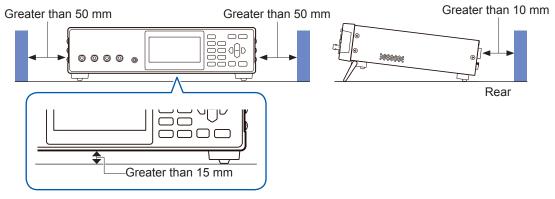
A CAUTION





Ventilation holes for heat radiation are provided on the side, bottom and rear panels
of the instrument. Leave sufficient space around the ventilation holes and install
the instrument with the holes unobstructed. Installation of the instrument with the
ventilation holes obstructed may cause a malfunction or fire.

Unplugging the power cord kills power to the instrument. Be sure to provide enough unobstructed space to unplug the power cord immediately in an emergency.



"Raising/closing the stand" (p. 15)

Handling the instrument

M DANGER



To avoid electric shock, do not remove the instrument's case. The internal components of the instrument carry high voltages and may become very hot during operation.

A CAUTION



- Do not place the instrument on an unstable table or an inclined place. Dropping or knocking down the instrument can cause injury or damage to the instrument.
- To avoid damage to the instrument, protect it from physical shock when transporting and handling. Be especially careful to avoid physical shock from dropping.

This instrument complies with EN 61326 Class A. This instrument may cause interference if used in residential areas. Such use must be avoided unless the user takes special measures to reduce electromagnetic emissions to prevent interference to the reception of radio and television broadcasts.

Before connecting the power cord

MARNING



- Before turning the instrument on, make sure the supply voltage matches that indicated on its power connector. Connection to an improper supply voltage may damage the instrument and present an electrical hazard.
- To avoid electrical accidents and to maintain the safety specifications of this instrument, connect the power cord provided only to a 3-contact (two-conductor + ground) outlet.

A CAUTION



- To avoid damaging the power cord, grasp the plug, not the cord, when unplugging it from the power outlet.
- Avoid using an uninterruptible power supply (UPS) or DC/AC inverter with rectangular wave or pseudo-sine-wave output to power the instrument. Doing so may damage the instrument.

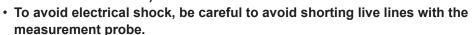
IMPORTANT

- · Turn off the power before disconnecting the power cord.
- Use only the specified power cord. Using a non-specified cord may result in incorrect measurements due to poor connection or other reasons.

Before connecting measurement probe/temperature sensor

M DANGER

- To avoid electrical hazards and damage to the instrument, do not apply voltage exceeding the rated maximum to the input terminals.
- The maximum rated voltage to earth of the SOURCE-H terminal and the SENSE-H terminal is ±5 V DC. The maximum rated voltage to earth of the SOURCE-L terminal and the SENSE-L terminal is 0 V DC. Attempting to measure voltages exceeding this level with respect to ground could damage the instrument and result in personal injury. (Do not apply voltage to earth since the SOURCE-L terminal and SENSE-L terminal where pseudo earthing is provided in the internal circuit.)



• To avoid electrical shock, do not exceed the every rating shown on either the instrument or each measurement probe, whichever is worse.

⚠ WARNING



To avoid injury or damage to the instrument, do not attempt to measure AC voltage, or DC voltage exceeding 5 V DC.

A CAUTION

- To avoid damage to the instrument, do not apply voltage or current to temperature sensor terminal.
- To prevent cable damage, do not step on cables or pinch them between other objects. Do not bend or pull on cables at their base.



- The sensor used in the temperature sensor is a thin, precision platinum film. Be aware that excessive voltage pulses or static discharges can destroy the film.
- Avoid subjecting the temperature sensor tip to physical shock, and avoid sharp bends in the sensor. These may damage the probe or break a wire.
- When measuring high temperatures, do not let the temperature sensor exceed the specified temperature range.



 When disconnecting the BNC connector, be sure to release the lock before pulling off the connector. Forcibly pulling the connector without releasing the lock, or pulling on the cable, can damage the connector.

Releasing the lock

1

2





Use only the specified measurement probe and the temperature sensor. Using a non-specified one when measuring may result in incorrect measurements due to poor connection or other reasons.

Before connecting the communication cable

MARNING

- Always turn both devices OFF when connecting and disconnecting an interface connector. Otherwise, an electric shock accident may occur.
- After connecting, be sure to tighten the screws. When the mounting screws
 are not firmly tightened, the input module may not perform to specifications, or
 may even fail.



- To avoid electric shock or damage to the equipment, always observe the following precautions when connecting to connectors.
- · Be careful to avoid exceeding the ratings of connectors .
- During operation, a wire becoming dislocated and contacting another conductive object can be serious hazard. Use screws to secure RS-232C.

A CAUTION

- The USB, RS-232C and LAN are not insulated to the ground (earth). Grounding
 (earthing) for the instrument and the controller must be wired as the common earth.
 Different earthing may cause a voltage potential difference between the GNDs of the
 instrument and the controller. Connecting the communication cable under condition
 that there is a voltage potential difference may cause a malfunction and/or a failure.
 When different earthing is required, connecting instruments and devices must be
 isolated.
- To avoid damage, do not disconnect the communications cable while the instrument is sending or receiving data.



- Use a common ground for both the instrument and the computer. Using different
 ground circuits will result in a potential difference between the instrument's ground
 and the computer's ground. If the communications cable is connected while such a
 potential difference exists, it may result in equipment malfunction or failure.
- Before connecting or disconnecting any communications cable, always turn off the instrument and the computer. Failure to do so could result in equipment malfunction or damage.
- After connecting the communications cable, tighten the screws on the connector securely. Failure to secure the connector could result in equipment malfunction or damage.

Before switching the current sink (NPN) and the current source (PNP)

A CAUTION



You must not operate the EXT.I/O MODE changing over switch (NPN/PNP) during Power-ON status of the instrument.



Set the NPN/PNP based on devices that are externally connected.

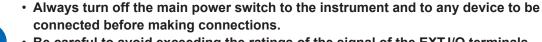
Before connecting the EXT.I/O terminals

MARNING



The EXT.I/O of the instrument cannot be applied to from an external power. Do
not apply external power to the instrument. (The ISO_5V terminal of the EXT I/O
connector is a 5 V (NPN)/-5 V (PNP) power output.)

To avoid electric shock or damage to the instrument, always observe the following precautions when connecting to the connector.





Be careful to avoid exceeding the ratings of the signal of the EXT.I/O terminals.
 (p. 121)

During operation, a wire becoming dislocated and contacting another conductive object can be serious hazard. Use screws to secure the external connectors.

Precautions during shipment

When shipping the instrument, observe the following. Hioki cannot be responsible for damage that occurs during shipment.

A CAUTION



During shipment of the instrument, handle it carefully so that it is not damaged due to a vibration or shock.

1 Overview

1.1 Product Overview and Features

The BT4560 is a variable-frequency impedance meter.

This instrument is equipped with a highly accurate voltmeter and a temperature measurement function, and optimal for quality control of batteries.

This instrument has the circuit configuration with high noise immunity, and thus, can provide stable measurement even at production sites.

What can the instrument BT4560 measure?

- The instrument can measure the internal impedance of a battery using the AC four-terminal method. (Frequency: 0.01 Hz to 1050 Hz or 0.01 Hz to 10 kHz, Minimum resolution: 0.1 $\mu\Omega$)
- This instrument can also measure the DC voltage (the electromotive force of the battery) simultaneously.
- (Resolution: 10 μV, Measurement accuracy: ±0.0035% rdg.±5 dgt.)
- In addition, temperature measurement, which is important for battery control, can be performed. (Temperature measurement accuracy: ±0.5°C)

What is the difference between the instrument BT4560 and the existing battery impedance instruments?

- The instrument has a simple structure, which does not need a loading device. It is not necessary to configure a system.
- This is a compact instrument and measurement can be performed without other instruments or devices.

Can the instrument BT4560 be used at production lines or sites?

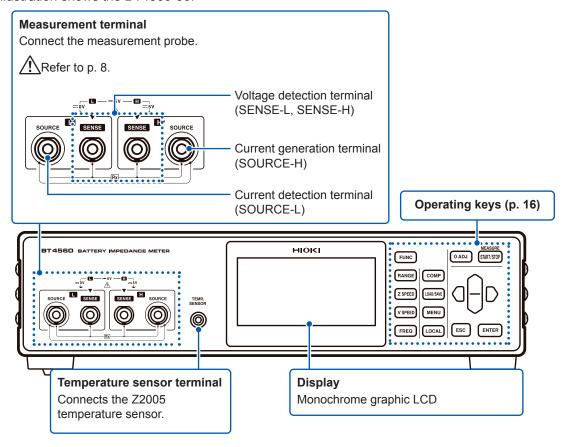
- Optional measurement probes can be extended up to a maximum of 4 m, corresponding to an operating environment.
- This can provide highly accurate measurement with a measurement configuration that resists the influences of external noise and contact resistance.
- The built-in comparator function can perform quality judgment of batteries.
- PLC control using the EXT. I/O is possible.
- Using the accompanying application software installed in a personal computer connected to the instrument can continuously measure internal impedance with a measurement frequency between 0.01 Hz and 1050 Hz or between 0.01 Hz and 10 kHz at the required points in time.
- This instrument is able to draw Cole-Cole plots*. (Uses application software.)
 - Refer to "Appx. 14 Creating Cole-Cole Plots Using PC Application Softwares" (p. A24)
- * The Cole-Cole plot is a plot of the frequency characteristics of battery impedance in which the horizontal axis represents the real part of impedance and the vertical axis represents the imaginary part of impedance. This plot is used to evaluate the internal resistance of the battery.

Can the instrument BT4560 analyze the internal resistance of batteries?

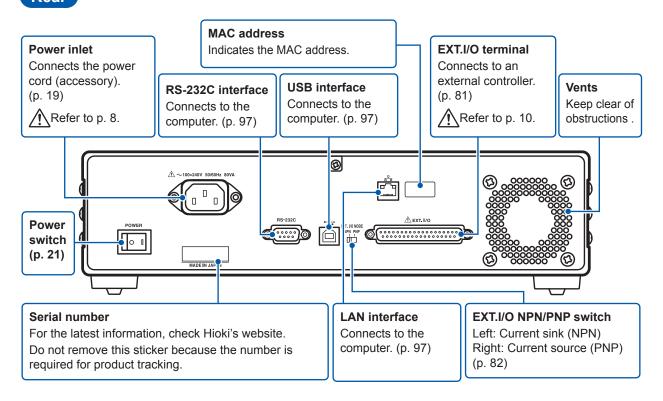
1.2 Names and Functions of Parts

Front

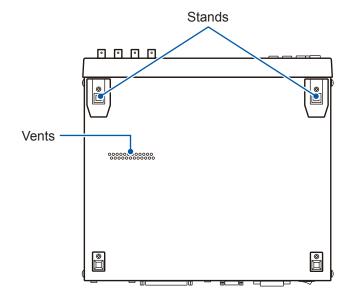
The illustration shows the BT4560-50.



Rear

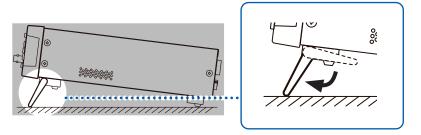


Bottom panel



Side

Raising/closing the stand

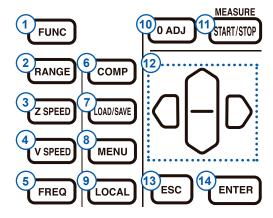


A CAUTION



Do not apply heavy downward pressure with the stand extended. The stand could be damaged.

Operating keys



	Key	Description	
1	FUNC	Selects the measurement function (combination of the voltage measurement and the impedance measurement).	
2	RANGE	Sets the measurement range.	
3	Z SPEED	Sets the measurement speed of impedance.	
4	V SPEED	Sets the measurement speed of voltage.	
5	FREQ	Sets the measurement frequency of impedance.	
6	СОМР	Sets the power switch of ON-OFF and the upper and lower limit values ,etc. of the comparator.	
7	LOAD/SAVE	Saves and reads the measurement conditions.	
8	MENU	Sets each of the functions (Trigger, Sample delay, Self-calibration, etc.).	
9	LOCAL	Releases the remote state and enables key operation.	
10	0 ADJ	Performs the zero adjustment.	
11)	MEASURE START/STOP	Starts and stops the measurement.	
12		Moves setting items and digits. Changes numerical values.	
13	ESC	Cancels the settings being set. Erases a display message.	
14	ENTER	Confirms the setting.	

1.3 Screen Configuration and Operation

The instrument is configured with the measurement screen and each setting screen.

Measurement screen

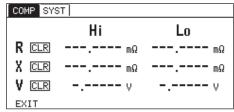


Settings screen

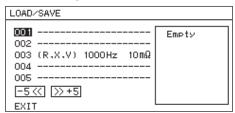
FREQ Measurement frequency setting screen

1000.00 Hz

Comparator setting screen



LOAD/SAVE Panel load/panel save screen



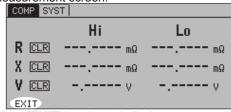
Menu settings screen

MEAS SYST TEST INFO	
SAMPLING DELAY	1.0 waves
AVERAGE	1
TRIGGER SOURCE	EXT
V SELF CALIBRATION	MANUAL
ZERO CROSS STOP	ON
SLOPE CORRECTION	OFF
VOLTAGE LIMIT	OFF
EXIT	

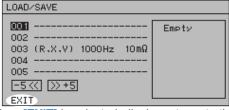
0 ADJ Zero adjustment setting screen



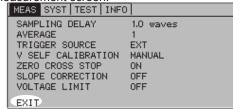
When **[EXIT]** is selected, display returns to the measurement screen.



When **[EXIT]** is selected, display returns to the measurement screen.



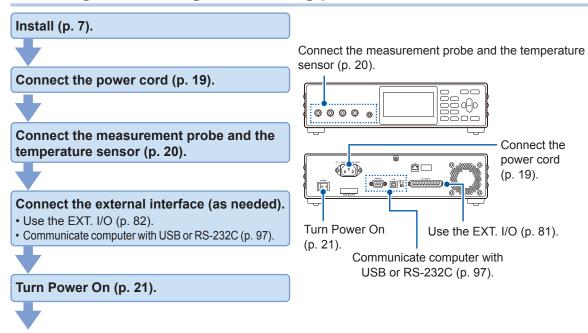
When **[EXIT]** is selected, display returns to the measurement screen.



1.4 Measurement Flow

Be sure to refer to "Operating Precautions" (p. 6) before using the instrument.

Installing, connecting, and turning power on



Setting the instrument (p. 23)

Set the measurement conditions (as needed).

- Basic setting (p. 23)
- Setting basic conditions for customization (p. 39)
- Setting system related items (p. 65)
- Initial setting table (p. 78)

Performing the zero adjustment

Make the measurement probes short-circuit with the zero adjustment board (p. 28).



Perform zero adjustment (p. 28).



Starting the measurement

Connect the measurement probe to the object being measured.



(For EXT trigger, start the measurement by pressing the **START/STOP** key.)

Check the measurement values.

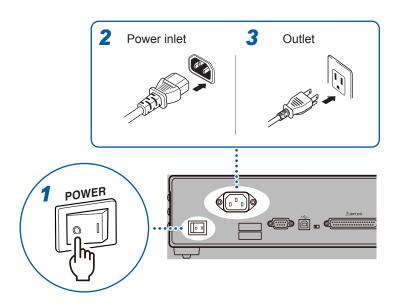


Ending

Turn Power Off (p. 21).

2 Preparation

2.1 Connecting the Power Cord

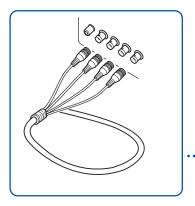


- 1 Check that the power switch (rear) of the instrument is OFF (○).
- 2 Check that the power voltage is in the range indicated on the rear, and then connect the power cord to the power inlet.
- Connect the plug of the power cord into an outlet.

2.2 Connecting the Measurement Probe and Temperature Sensor (Optional)

The measurement probe and the temperature sensor are optional. (p. A12)

Connect the four-terminal cable to the instrument



Connect the SENSE and SOURCE connectors of the probe to the measurement terminals with the same indication on the instrument. (p. 14)

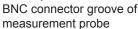
Black cables - Terminals on the L side of the instrument Red cables - Terminals on the H side of the instrument



Connection method

- 1 Check the orientation of the groove in the BNC connector and ensure that it fits into the connector guide of the instrument side.
- Align the groove in the BNC connector along the connector guide of the instrument, and insert the BNC connector into the instrument connector.
- **3** Turn the BNC connector to the right and lock it.

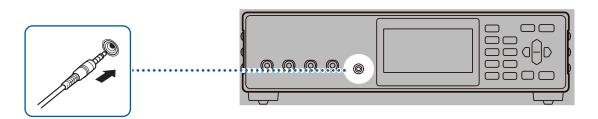






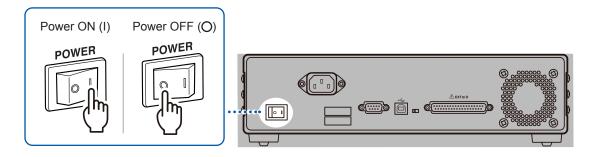


Connect the temperature sensor to the instrument



2.3 Turning the Power ON or OFF

Turn the power on or off using the power switch on the rear.



2.4 Inspection Before Use

Before using the instrument, verify that it operates normally to ensure that no damage occurred during storage or shipping. If you find any damage, contact your authorized Hioki distributor or reseller.

Verifying the instrument and the peripheral devices

Inspection items	Countermeasures
Is the power cord insulation torn, or is any metal exposed?	Do not use the instrument if damage is found, as electric shock or short-circuit accidents could result. Contact your authorized Hioki distributor or reseller.
Is the insulation of the measurement probe or the connection cords torn, or is any metal exposed?	When any damage is found, it may cause electrical shock. If this happens, replace the measurement probe or connection cords with ones specified by Hioki.
Is the instrument damaged?	When any damage is found, it may cause electrical shock. Do not use the instrument, and then request repair.

Verifying when turning the power on

Inspection items	Countermeasures
When the power is turned on, does the fan rotate and does "BT4560-50" or "BT4560-60" or the "Version number" appear on the display?	If the fan does not rotate, or if "BT4560-50" or "BT4560-60" or the "Version number" is not displayed, the device may be malfunctioning. Please request repair. HIOKI BT4560-50 or BATTERY IMPEDANCE METER Version 1.00 Version
After the self-test, is the measurement screen displayed?	If the screen does not display, the instrument may have be malfunctioning internally. Request repairs.

3

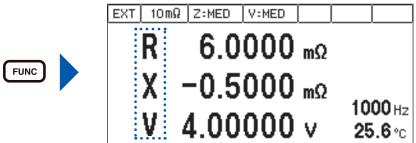
Basic Measurement

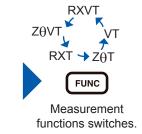
3.1 Selecting the Measurement Functions

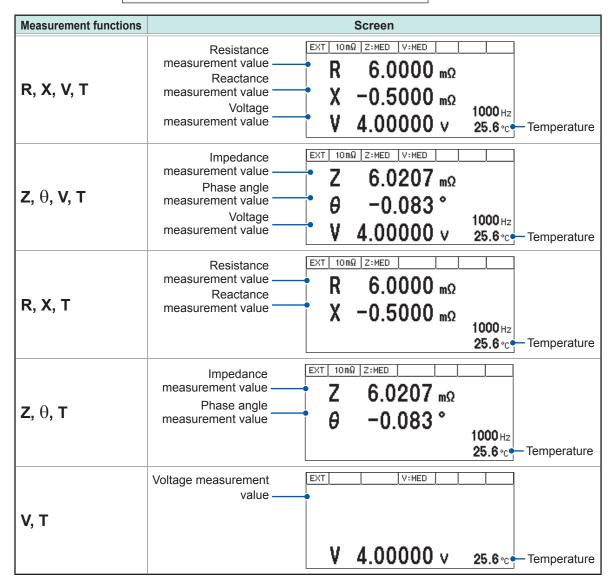
Set the measurement functions.

Parameters	Measurement items	Parameters	Measurement items
Z	Impedance	X	Reactance
θ	Phase angle	V	Voltage
R	Resistance	Т	Temperature

By pressing Func (FUNC) the measurement functions are switched. For the selectable functions, refer to Table below.







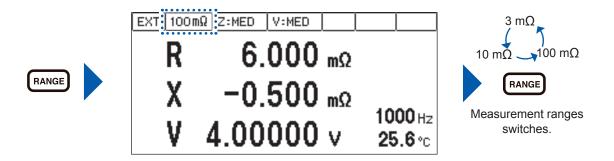
3.2 Selecting the Measurement Range

Set the measurement range of impedance (3 m Ω , 10 m Ω , 100 m Ω).

The voltage and the temperature have a single range respectively. Thus, setting is not necessary. Use the measurement range of impedance when the impedance measurement value exceeds the present range or when changing the measurement accuracy.

When the functions (V, T) are selected, setting cannot be performed.

By pressing (RANGE) the measurement ranges are switched.



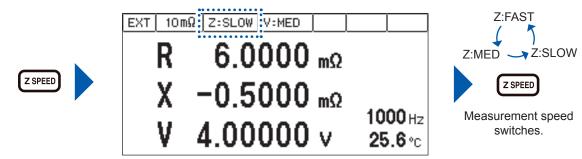
3.3 Setting the Measurement Speed

Set the measurement speed (FAST, MED, SLOW) in the impedance measurement and the voltage measurement.

The slower the measurement speed is, the more accurate are the results.

Set the measurement speed of impedance measurement (Z)

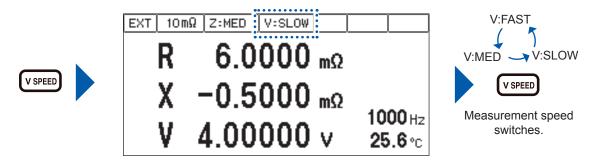
By pressing (Z SPEED) the measurement speed in the impedance measurement is switched.



Setting Items Contents		
Z:FAST	When the high speed measurement is performed, set this item.	
Z:MED	When the normal speed measurement is performed, set this item.	
Z:SLOW	Z:SLOW When the high accurate measurement is performed, set this item.	

Set the measurement speed in the voltage measurement (V)

By pressing (V SPEED) the measurement speed in the voltage measurement is switched.



Setting Items	Contents	
V:FAST	When the high speed measurement is performed, set this item.	
V:MED	When the normal speed measurement is performed, set this item.	
V:SLOW When the high accurate measurement is performed, set this item.		

When the measurement frequency is 1.01 kHz or higher, the measurement speed setting does not affect the measurement frequency.

3.4 Setting the Measurement Frequency

Setting the measurement frequency. BT4560-50 : 0.01 Hz to 1050 Hz BT4560-60 : 0.01 Hz to 10 kHz

1 P

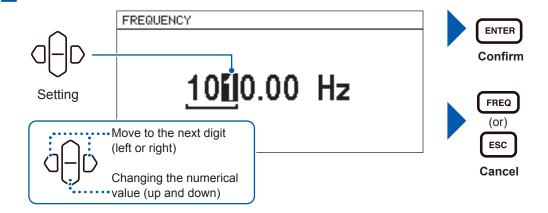
Press (FREQ). (Measurement frequency setting screen appears.)

The selected digit is displayed in reverse black and white, with a bar under the digit enabled to be set.

FREQUENCY

1000.00 Hz

Digits enabled to be set Set the measurement frequency.



Disabled digits will be set to zero automatically.

The display will automatically change to zero as setting the digits is disabled.

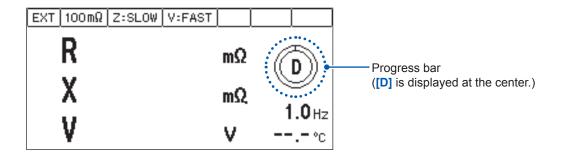


When the measurement time is long (Display of the Progress Bar)

When the impedance measurement time is long (more than approx. 1 second), the progress bar is displayed on the right side of the measuring screen which is in operation.

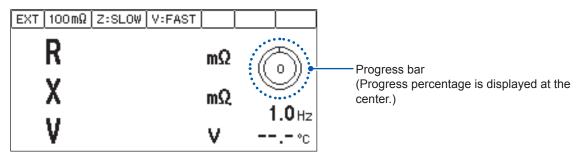
During sample delay (p. 40)

[D] is displayed at the center of the progress bar.

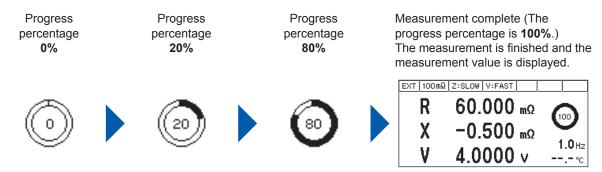


During impedance measurement

Percentage of measurement progress is displayed at the center of the progress bar.

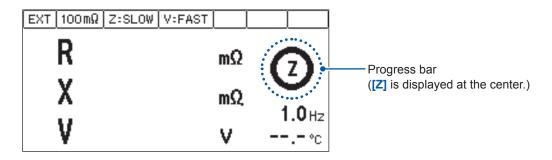


Transition of the progress percentage



During the detection of zero cross stop (When zero cross stop is ON) (p. 49)

[Z] is displayed at the center of the progress bar.



3.5 Performing the Zero Adjustment

Remove the residual components due to offset and the measurement environment. Be sure to perform the zero adjustment before the impedance measurement and the voltage measurement.

Performing the zero adjustment

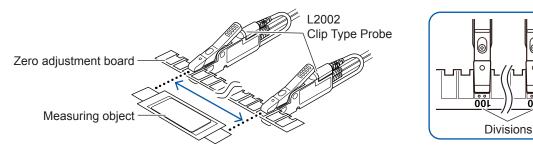
performing the zero adjustment.

Placing the measurement probe (Example: L2002)

- 1 Place the measurement probe in the same condition as the measurement is performed.

 The zero residual volume differs due to the condition of the measurement probe (length, shape, and location).

 Thus, place the measurement probe in the same condition as the actual measurement is performed, before
- 2 Prepare the zero adjustment board (accessory).
- 3 Place the probes with a space the same length as the width of the actual measuring object.
 Clip a pattern on the zero adjustment board, with the same number of divisions for both HIGH and LOW.



Clip the L2002 so that the pin at the end of the L2002 securely enters the two holes (through holes) on the zero adjustment board. If the pin is not in the hole, an error is displayed and proper zero adjustment cannot be performed

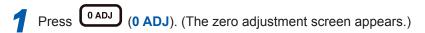
Refer to "Error display and remedy" (p. 135)

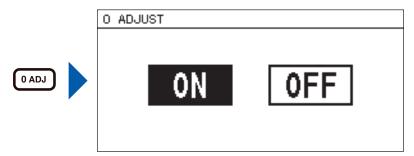
Setting the zero adjustment

There are two methods of the zero adjustment, the spot zero adjustment (SPOT) and the all zero adjustment (ALL).

Spot zero adjustment (SPOT)	The zero adjustments for the range and the frequency that are presently set, and the voltage measurement are performed. The time required differs according to the frequency. The lower the frequency, the longer it takes to set (Reference: approx. 350 s for 0.1 Hz, approx. 45 s for 1 Hz). When setting at a different range and/or frequency, zero adjustment will be invalid.	
All zero adjustment (ALL)	The zero adjustments for the range that is presently set, and the full range of the frequency, and the voltage measurement are performed. Even if the measurement frequency is changed, the zero adjustment is effective. However, when the range is changed, the zero adjustment is not effective.	

- When the zero adjustment is effective, the indicator of 0 ADJ appears on the measurement screen.
- After performing the zero adjustment, even if the zero adjustment becomes ineffective, the zero adjustment will become effective when returning to the conditions that the zero adjustment was performed.
- With the 0ADJ_SPOT of the EXT.I/O and 0ADJ_ALL terminals, performing can be done.

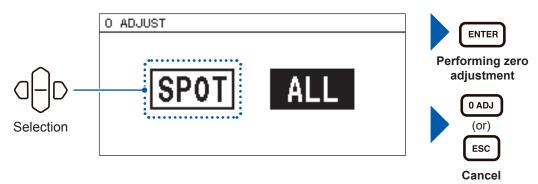




2 Select [ON].



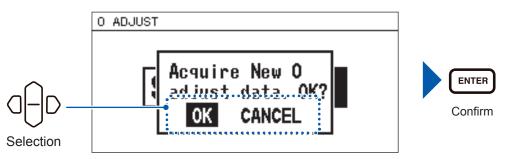
3 Select [SPOT] or [ALL].



When selecting [ALL], the confirmation window opens.

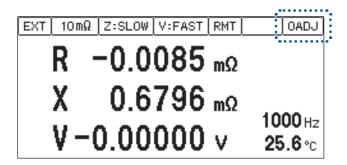
OK: Performing all zero adjustment

CANCEL: Returns to the measurement screen without execution.



After the zero adjustment is normally performed, the screen will go back to the measurement screen

(When the zero adjustment is effective, 0 ADJ appears at the upper right on the measurement screen.)



When the zero adjustment is not normally performed

When [0 ADJUST ERROR] appears, the proper adjustment is not performed.

Check the short-circuit method of the measurement probe and perform the zero adjustment with a proper method so that the zero adjustment data values come within the range given in the table below.



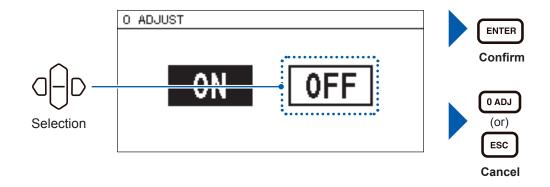
Impedance measurement	R	х		
3 mΩ range	BT4560-50: -0.1000 m Ω to 0.1000 m Ω BT4560-60: -1.5000 m Ω to 1.5000 m Ω	-1.5000 m Ω to 1.5000 m Ω		
10 mΩ range	BT4560-50: -0.3000 m Ω to 0.3000 m Ω BT4560-60: -3.0000 m Ω to 3.0000 m Ω			
100 mΩ range	Common: -3.000 m Ω to 3.000 m Ω	-1.500 m Ω to 1.500 m Ω		
Voltage measurement				
-0.10000 V to 0.10000 V				

In the frequency range from 1.06 kHz to 10.00 kHz, error judgment for reactance based on the table above is not performed.

Disabling zero adjustment

Select [OFF] on the zero adjustment screen.

(When [OFF] is selected, zero adjustment will be disabled. To enable, perform zero adjustment again.)



When measuring while changing the measurement range

If measured as below, zero adjustment will not be necessary every time the range is changed.

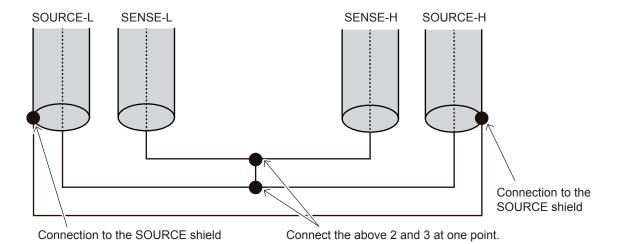
- 1. Perform zero adjustment at $3 \text{ m}\Omega$ range.
- 2. Save the current condition by panel saving function (p. 60). (Zero adjustment data of the current range will be saved.)
- 3. Change the range to 10 m Ω and perform zero adjustment.
- 4. Save the current condition by panel saving function (p. 60).
- 5. Change the range to $100 \text{ m}\Omega$ and perform zero adjustment. 6. Save the current condition by panel saving function (p. 60).
- 7. Read the condition of the range used by panel saving function (p. 60), and then measure.

Connection when performing the zero adjustment

If the zero adjustment board is used, the connection will be as below.

Perform zero adjustment with the same connection when making your own measurement probe (refer to "Appx. 3 Cautions When Making Your Own Measurement Probe" (p. A4)).

- Connect the shields of SOURCE-H and SOURCE-L. (Connected by the return cable)
- Connect SENSE-H and SENSE-L.
- Connect SOURCE-H and SOURCE-L.
- Connect the above 2 and 3 lines at one point.



3.6 Checking the Measurement Results

Detecting the measurement abnormality (p. 135)

When the measurement is not normally performed, the indication expressing the measurement abnormality appears on the screen, and the ERR signal from the EXT.I/O is output.

Contact error

When the resistance value is greater between SOURCE-H and SENSE-H, or between SENSE-L and SOURCE-L, the contact error appears. The possible causes are listed below.

- The measurement probe is not connected to the measuring object.
- The probe is broken.
- The contact resistance or the wiring resistance are large due to frictional wear and dirt of the probe.
- The circuit protection fuse is broken.

The guideline in the contact error detection

Place for abnormality	Target resistance value for abnormality detection			Measurement	Error indication	
detection	3 mΩ range	10 mΩ range	100 mΩ range	abnormality type	Error indication	
SOURCE-H and SENSE-H	10 Ω	15 Ω	50 Ω	H Contact error	CONTACT ERROR H	
SOURCE-L and SENSE-L	10 Ω	15 Ω	50 Ω	L Contact error	CONTACT ERROR L	

- The resistance values indicate the guideline, which are not strictly defined.
- The capacitance of the measurement probe is greater than 20 nF, the measurement abnormality may not be detected
- For functions V and T, target resistance value for abnormality detection will be the same resistance value as 100 m Ω range.

Over-voltage input error (indication: OVER VOLTAGE)

When the voltage of the measuring object exceeds the measurable range, OVER VOLTAGE appears.

The measurable voltage range is -5.10000 V to 5.10000 V.

It may be displayed SENSE-H and SOURCE-H short-circuit, and SENSE-L and SOURCE-L short-circuit state.

Voltage limit error (Indication: OVER V LIMIT)

When the voltage of the measuring object exceeds the voltage limit setting range, LIMIT VOLTAGE appears.

For the setting method of the voltage limit, refer to "4.6 Preventing the Overcharge due to Measurement Signal (Voltage Limit Function)" (p. 47).

It may be displayed SENSE-H and SOURCE-H short-circuit, and SENSE-L and SOURCE-L short-circuit state.

Measurement current abnormality (Indication: -----)

This indication appears when the measurement current does not flow normally. The possible causes are listed below.

- The contact resistance or the wiring resistance are large due to frictional wear and dirt of the probe.
- The resistance of the measuring object is remarkably large to the range (Example: when 1 $k\Omega$ is selected).
- When wiring is wrongly connected to a battery.
- When wiring is connected to a battery that is grounded.

The guide line in the abnormality detection of the measurement current

Place for abnormality detection	Target resis	Measurement abnormality	Indi-		
detection	3 mΩ range	range 10 m Ω range 100 m Ω range		type	cation
SOURCE-H	1.5 Ω to 4.0 Ω	5 Ω to 12 Ω	50 Ω to 55 Ω	Measurement current abnormality	
SOURCE-L	1.5 Ω	4.5 Ω	45 Ω	Measurement current abnormality	

The resistance values indicate the guideline, which are not strictly defined. The detected value of SOURCE-H changes based on the voltage of the measuring object.

Impedance measurement error due to voltage drift (Indication: VOLTAGE DRIFT)

The voltage of the measuring object considerably fluctuates during the measurement. When the difference between voltage values at the start and at the end of measurement is 10 mV or more, the difference is detected as an error.

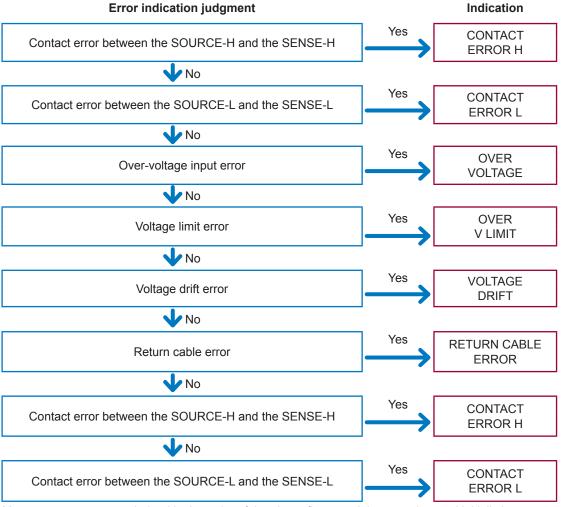
Return cable unconnected error (Indication: RETURN CABLE ERROR)

The probe's return cable is not properly connected. It may be disconnected or the wire connection may be wrong.

To reduce noise due to the electromagnetic induction, it needs the return cable where the current flows opposed to the measurement current. The return cable has a structure that short-circuits between the shield wire of the SOURCE-H and the shield wire of the SOURCE-L. (In the optional probe, the return cable short-circuits between the shield wire of the SOURCE-H and the shield wire of the SOURCE-L.)

When the measurement frequency is 1.06 kHz or higher, return cable disconnection error detection will not be performed.

Detection sequence of measurement abnormality



Measurement errors are judged in the order of the above figure and the error detected initially is displayed.

Abnormal measurement current is monitored during the following:

- · When trigger has been accepted until voltage measurement is executed
- · During impedance measurement

Temperature measurement indication

Temperature sensor unconnected (Indication: --.-°C)

The temperature sensor is not connected. Thus, the temperature measurement cannot be performed. When the temperature measurement is not necessary, there is no need for connection.

Overrange indication

Each parameter over-indicates due to causes listed below.

Parameters	Over indication	Cause				
R						
X	OverRange	The measurement value of Z exceeds the indication range of the present range.				
Z						
θ						
т	+Over°C	The measurement value is greater than 60.0°C.				
1	-Under°C	The measurement value is smaller than -10.0°C.				

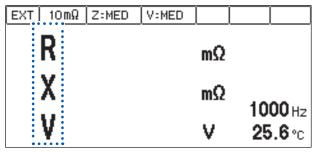
3.7 Basic Measurement Examples

In this section, setting the battery cell is explained as an example.

Examples of setting contents

Measurement functions		R, X, V, T	
Measurement Range		100 mΩ	
Measurement	Impedance measurement	FAST	
speed	Voltage measurement	SLOW	
Impedance measurement frequency		1 Hz	
Zero	adjustment	ALL	

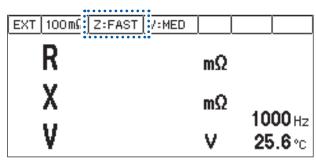
1 Set the measurement functions (R, X, V, T). (p. 23)



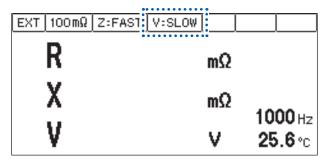
2 Set the measurement range at 100 m Ω . (p. 24)



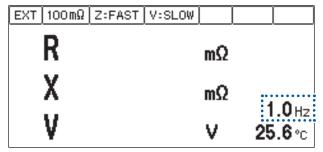
3 Set the measurement speed of impedance measurement (Z) at [FAST]. (p. 25)



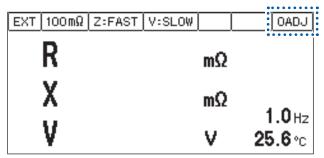
4 Set the speed of the voltage measurement (V) at [SLOW]. (p. 25)



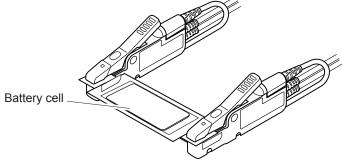
5 Set the measurement frequency of impedance at 1 Hz. (p. 26)



6 Connect the zero adjustment connection and then perform the all zero adjustment. (p. 28)



7 Connect the battery cell.



8 Press START/STOP to measure.



9 Check the measurement results.

EXT 100mΩ	Z:FAST V:SLOW	OADJ
R	$6.000~\text{m}\Omega$	
X	-0.500 mΩ	
٧	4.00000 v	1.0нz 25.6 °с

4

Customization of Measurement Conditions

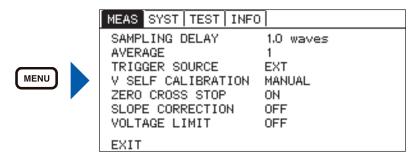
4.1 Setting the Measurement Starting Conditions (Trigger Functions)

There are two methods to set the measurement starting conditions, which are described below.

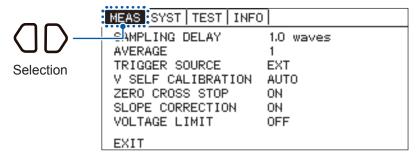
External trigger	When START/STOP (START/STOP) is pressed or the external trigger signal is input, the measurement starts.
Internal trigger	Trigger signals are automatically generated internally to perform the automatic-measurement.

Setting the trigger

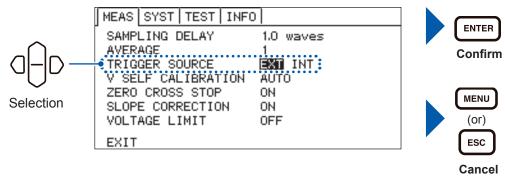
Press MENU). (The setting screen appears.)



2 Select [MEAS] tab.



3 Select [EXT] (external trigger) or [INT] (internal trigger).



Inputting the external trigger

- When inputting from the key
 On the measurement screen, press (START/STOP) to perform measurement once.
- When inputting from the EXT.I/O
 If the TRIG terminal of the EXT.I/O terminal is short-circuited to ISO_COM, the measurement is performed once. (p. 82)
- When inputting from the communication interface
 When the *TRIG command is received, measurement is performed once.

IMPORTANT

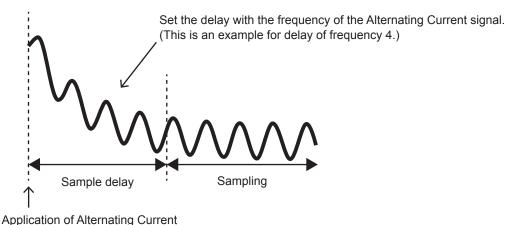
- When the function is set in the internal trigger, the input from the EXT.I/O and *TRG command
 are ignored, and the voltage limit function is enabled. If the measuring object continues to
 be connected with an internal trigger set, may cause continuous charging or discharging.
 Therefore, remove the measuring object from the instrument after measurement.
- Measurement will stop if START/STOP (START/STOP) is pressed during measurement.

4.2 Starting the Measurement After the Response of the Measuring Object is Stable (Sample Delay Function)

When measuring impedance, set the delay (delayed time) from applying AC to the start of the sampling. There are two methods to set the delay, one is to use the frequency of the Alternating Current signal for setting and the other is to use the deviation of the offset voltage fluctuation for setting.

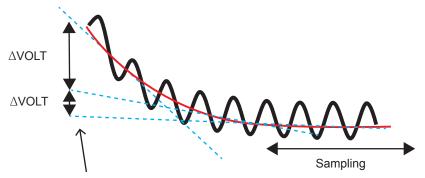
Settings based on waveform (WAVE)

Alternating Current response of the battery



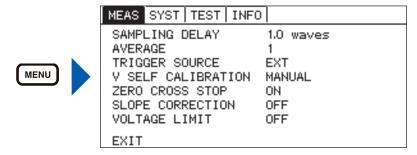
Setting with the deviation of voltage fluctuation (\(\Delta VOLT \)

Alternating Current response of the battery

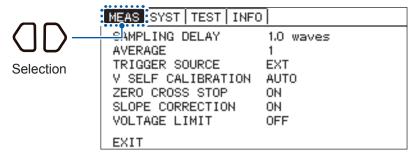


The slope of Alternating Current response is monitored and sampling is started when the slope of deviation (Δ VOLT) drops below the set value.

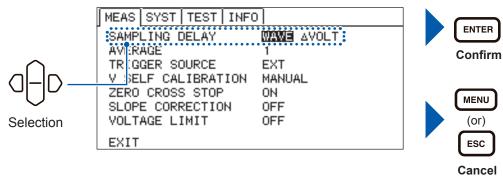
Press (MENU). (The setting screen appears.)



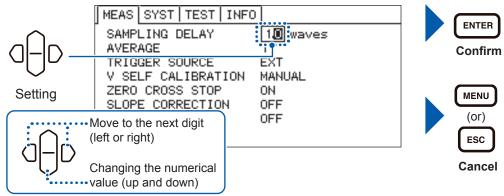
2 Select [MEAS] tab.



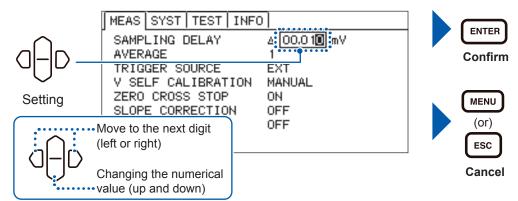
3 Select [WAVE] or [△VOLT].



When selecting [WAVE], set the wavenumber of delay. (0.0 waves to 9.0 waves)



When selecting [\(\Delta \bullet \text{OLT} \), set the voltage. (00.001 mV to 10.000 mV)



4.3 Maintaining Voltage Measurement Accuracy (Self-Calibration Function)

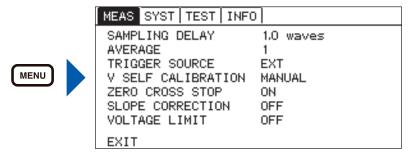
This function compensates the offset voltage and the gain drift in the internal part of the circuit, to improve the voltage measurement accuracy.

To satisfy the instrument's measurement accuracy, the self-calibration is required. Be sure to perform it. Be sure to perform the self-calibration especially after warming-up or when the ambient temperature has changed more than 2°C.

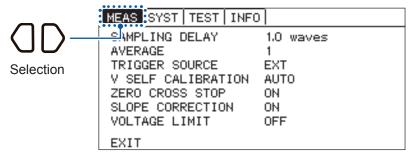
The methods for configuring self-calibration to run are as follows:

AUTO	Self calibration of 0.2 s is automatically executed before measuring the voltage. In the functions (R, X, T) and (Z, θ , T) where the voltage measurement is not performed, the self-calibration is not performed.
MANUAL	The self-calibration is performed from the input signal CAL of the EXT.I/O, or from the command. (Perform it under the TRIG waiting condition. When the signal is input, perform it after the measurement.)

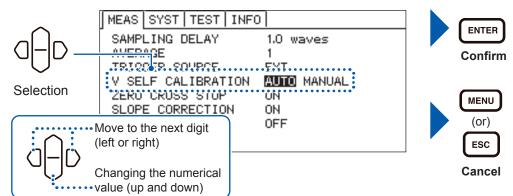
Press (MENU). (The setting screen appears.)



2 Select [MEAS] tab.

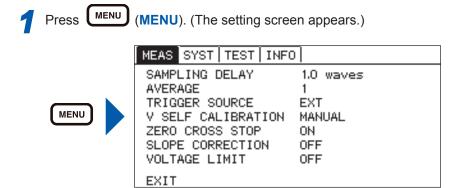


3 Select [AUTO] or [MANUAL].

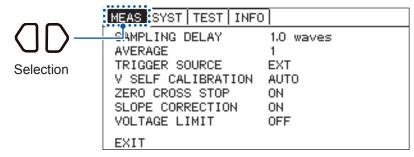


4.4 Stabilizing the Measurement Values (Average Function)

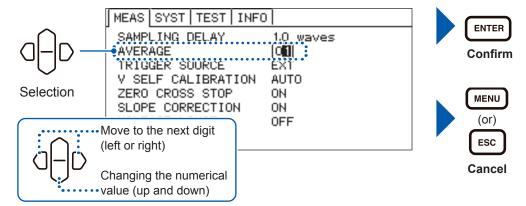
The arithmetic mean for the set number of measurement values will be displayed as the result. This function can reduce the fluctuation of the measurement values. This function can apply only to the impedance measurement.



2 Select [MEAS] tab.

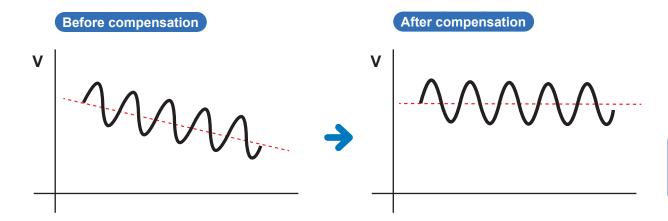


3 Sets the number of measured values to be used for averaging. (1 to 99)



4.5 Compensating the Potential Slope Due to Electric Discharge (Slope Correction Function)

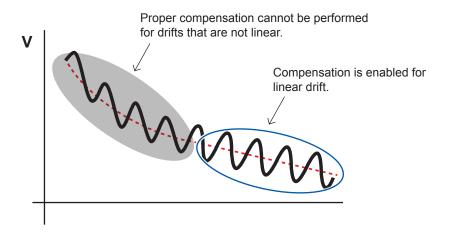
During impedance measurement, the measurement signal may drift due to characteristics of the battery and input impedance of the measuring instrument. This function performs compensation for linear drift.



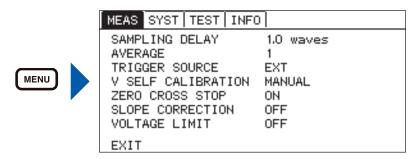
IMPORTANT

Compensation will be performed for linear drift.

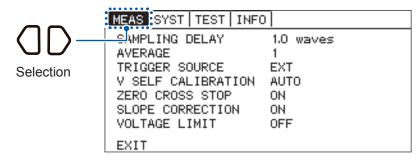
Proper compensation cannot be performed for fluctuations that are not linear as shown below. "Starting the Measurement After the Response of the Measuring Object is Stable (Sample Delay Function)" (p. 40) is used, and wait to measure until the measuring object's response time becomes stable.



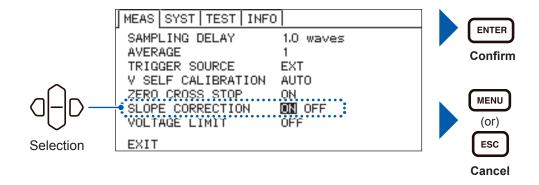




2 Select [MEAS] tab.



3 Select [ON] or [OFF].



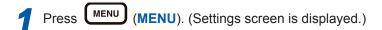
4.6 Preventing the Overcharge due to Measurement Signal (Voltage Limit Function)

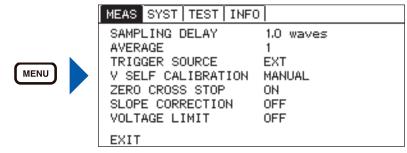
This function prevents the battery from getting overcharged due to the applied signal when measuring impedance. If the voltage of the object to be measured is higher compared to the set voltage, impedance will not be measured and the message [OVER V LIMIT] will be displayed.

A CAUTION

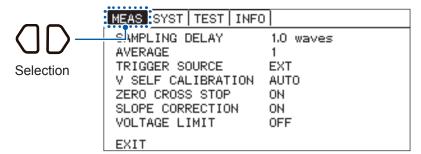


Set the voltage limit value lower than the voltage value of the measuring object's battery which will become overcharged. The battery may be overcharged, if the measurement is repeated at a high voltage value setting.

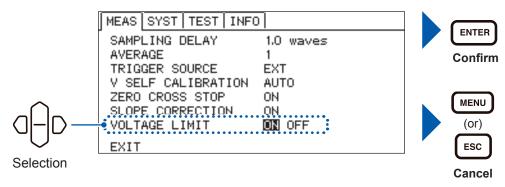




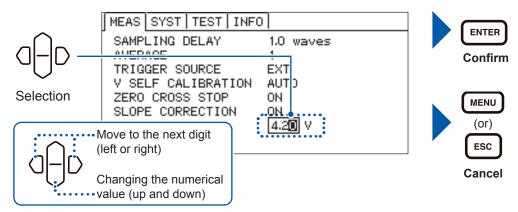
2 Select [MEAS] tab.



3 Select [ON] or [OFF].

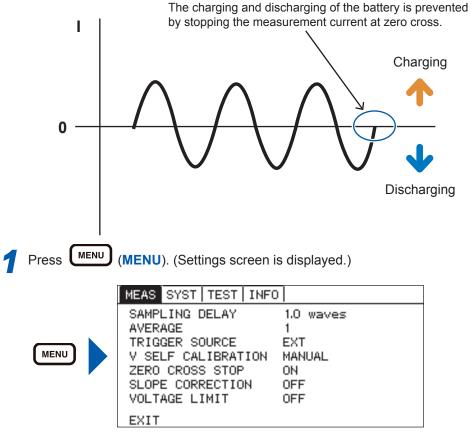


When selecting [ON], set the voltage. (0.01 V to 5.00 V)

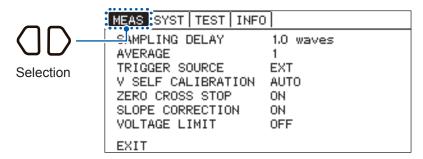


4.7 Prevents Charging and Discharging due to the Measurement Signal (Measurement Signal Zero Cross Stop Function)

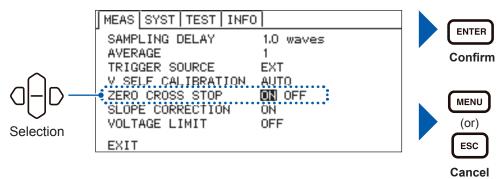
This function performs the process of stopping the applied measurement signal at zero cross during impedance measurement to prevent charging and discharging of the object to be measured. When the measurement signal zero cross stop function is enabled, the measurement time increases by approximately one cycle of measurement frequency. Measurement cannot be interrupted during the detection of zero cross stop.



2 Select [MEAS] tab.



3 Select [ON] or [OFF].



5

Judging Measurement Results (Comparator Function)

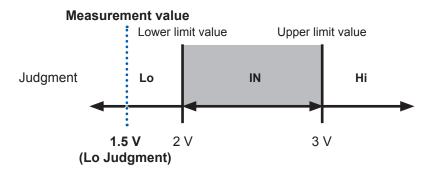
The function judges that the measured value is in the range of Hi (upper limit value < measured value), or IN (lower limit value ≤ measured value ≤ upper limit value), or Lo (measured value < lower limit value) compared to the preset upper and lower limit value.

Upper and lower limit values and absolute values (absolute values setting is for voltages [V] only)

Upper and lower limit values

The function judges whether the measurement value is in the Hi, IN, or Lo range for the upper and lower limit values set previously.

(Example: If the upper limit is 3 V, Lower limit is 2 V, and the measurement value is 1.5 V)

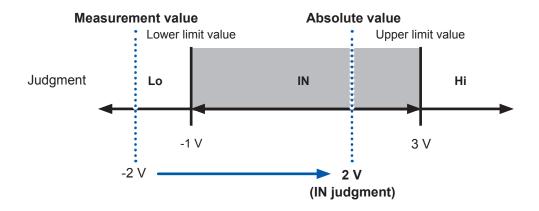


Absolute value

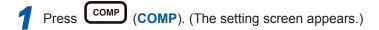
The function judges whether the absolute value of the measurement value is in the Hi, IN, or Lo range for the upper and lower limit values set previously.

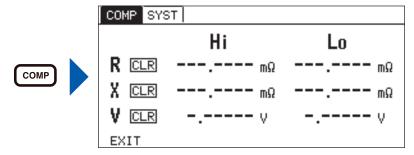
Even if wiring is connected in reversed polarity, judgment can be performed correctly.

(Example: If the upper limit 3 V, Lower limit is -1 V, and the measurement value is -2 V)

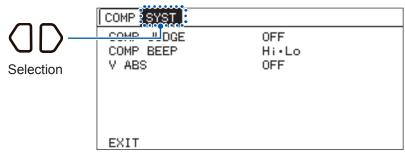


5.1 Turning the Comparator Function ON and OFF

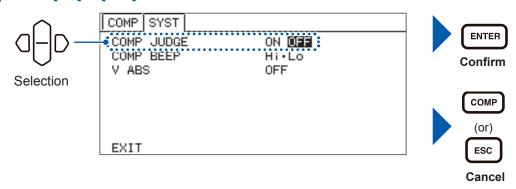




2 Select [SYST] tab.



3 Select [ON] or [OFF].



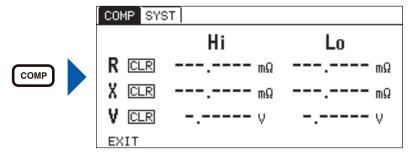
5.2 Setting the Upper and Lower Limit Value

When making the comparator function effective, set the upper and lower limit value, which are used for the judgment. The following describes the setting method, taking R, X, V as the examples.

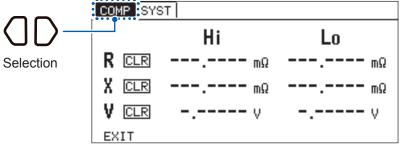
Setting examples

F	R	Upper limit value:	7.5 mΩ	Lower limit value:	7 mΩ
	X	No judgment			
\	V	Upper limit value:	5 V	Lower limit value:	4 V

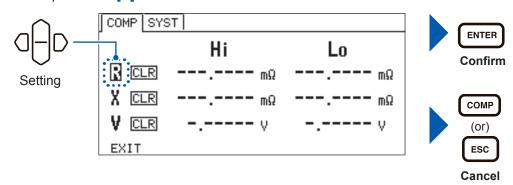
Press COMP (COMP). (The setting screen appears.)



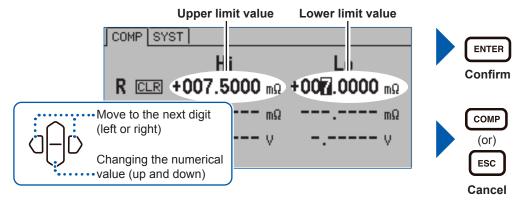
2 Select [COMP] tab.



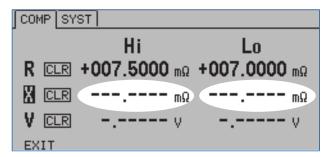
3 Select parameter [R].



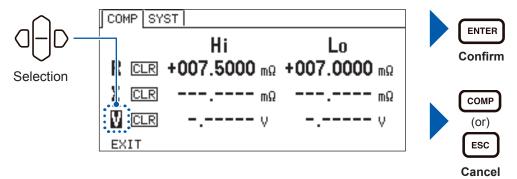
4 Set the upper limit value of [R] at 7.5000 mΩ, and the lower limit value at 7.0000 mΩ.



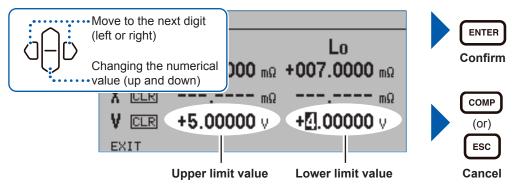
Since the parameter [X] is not used, the value is not set. ([---.--] display indicates disabled.)



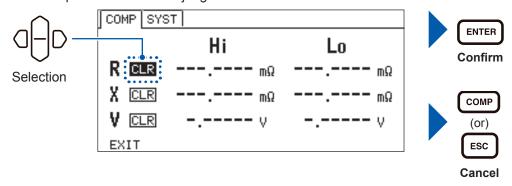
6 Select parameter [V].



Set the upper limit value of [V] at 5.00000 V, and the lower limit value at 4.00000 V.



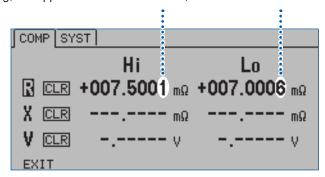
When **[CLR]** is selected and confirmed, the set value is displayed as **[-.---]** and is disabled. Disabled parameters are not judged.



When set to 100 m Ω range (Minimum resolution 0.001 m Ω)

Rounded off to the minimum digits set.

After rounding, the upper limit will be 7.500 m Ω , and the lower limit will be 7.001 m Ω .



Settable range

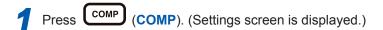
R	-003.0000 m Ω to +120.0000 m Ω		
Х	-120.0000 m Ω to +120.0000 m Ω		
Z	+000.0000 m Ω to +120.0000 m Ω		
θ	-180.000° to +180.000°		
V	-5.10000 V to +5.10000 V		
Common in all ranges			

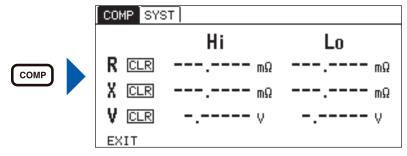
IMPORTANT

When the value of Hi is set smaller than the value of Lo, the value of Hi set is corrected to the value of Lo.

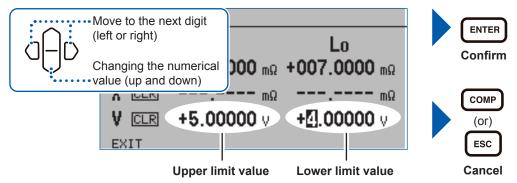
5.3 Voltage is Judged with the Absolute Value

The upper and lower limit of voltage is judged with the absolute values. (R, X, Z and θ cannot be set to be judged with absolute values.)

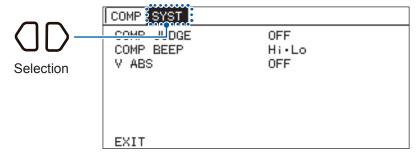




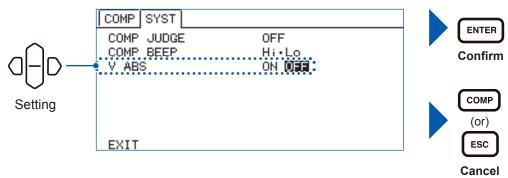
2 Sets the upper and lower limit values for [V]. (p. 53)



3 Select [SYST] tab.



4 Select [ON] or [OFF].



5.4 Checking the Judgment with Sound

Select whether to use a judgment sound of the measurement results.

OFF: The buzzer does not sound.

Hi • Lo : When the judgment result is Hi • Lo, the buzzer sounds (three short sounds).

IN : When the judgment result is IN, the buzzer sounds (long sound).

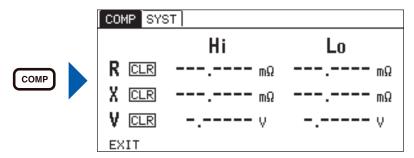
ALL: When the judgment result is Hi • Lo, the buzzer sounds (three short sounds).

When the judgment result is IN, the buzzer sounds (long sound).

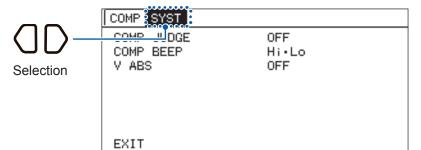
		Setting the sound					
Judgment result in measurement OFF		Hi • Lo	IN	ALL			
Hi — ✓ (three		✓ (three short sounds)	_	√ (three short sounds)			
IN	IN — —		✓ (long sound)	✓ (long sound)			
Lo — ✓ (three short sounds		_	✓ (three short sounds)				

—: No buzzer sound, \checkmark (long sound): Long buzzer sound, \checkmark (three short sounds): Three short buzzer sounds.

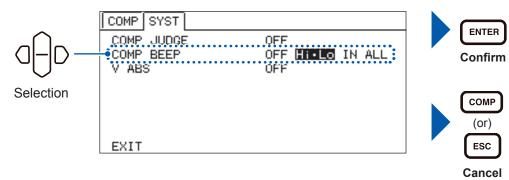
Press COMP). (The setting screen appears.)



2 Select [SYST] tab.



3 Select the buzzer sound from among [OFF], [IN], [Hi • Lo], [ALL].



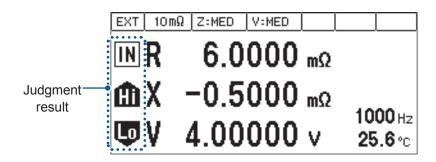
5.5 Checking the Judgment Result

The indicator appears at the left of the parameters on the measurement screen depending on the judgment result.

Each judgment result, and the comprehensive judgment result of all the parameters are output to the EXT.I/O.

PASS of the comprehensive judgment result is ON (FAIL is OFF) only when all the enabled parameters judged by the comparator are IN.

IN	When the measured value is smaller than the upper limit value and greater than the lower limit value.
â	When the measured value is greater than the upper limit value that is set.
<u> </u>	When the measured value is smaller than the lower limit value that is set.



Measurement result	Judgment	Output of EXT. I/O					
wieasurement result	result	Hi	IN	Lo	ERR	PASS	FAIL
Hi Set value < Measured value	Hi	ON	OFF	OFF	OFF	OFF	ON
Lo Set value ≤ Measured value ≤ Hi Set value	IN	OFF	ON	OFF	OFF	ON	OFF
Measured value < Lo Set value	Lo	OFF	OFF	ON	OFF	OFF	ON
OverRange	Hi	ON	OFF	OFF	OFF	OFF	ON
Measurement Error	No judgment	OFF	OFF	OFF	ON	OFF	OFF
During interruption of measurement	No judgment	OFF	OFF	OFF	OFF	OFF	OFF

6

Saving and Reading Measurement Conditions (Panel Saving and Loading)

The present measurement conditions are saved to the memory of the instrument (panel saving function), and the measurement conditions are read from the memory by the key operation, communication command transmission, and external control. (Panel loading function)

The instrument can save 126 panels of measurement conditions at a maximum. The measurement conditions that are saved are retained even if the power is turned off, which can be read by the panel loading function.

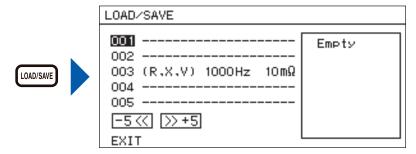
Items that can be saved by the panel saving

	Measurement functions	Measurement range	Measurement frequency
	Measurement speed of impedance	 Measurement speed of voltage 	Zero adjustment setting
Saving contents	Zero adjustment data	 Sample delay setting 	 Comparator setting
	Average	 Slope correction setting 	 Voltage limit
	Self -Calibration settings	 Measurement signal zero cross stop function 	Trigger source
Numbers of panel	126		

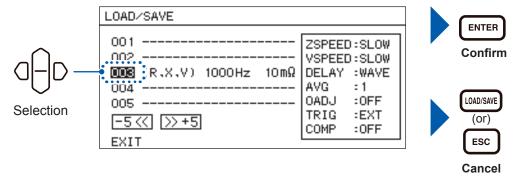
6.1 Saving the Setting Conditions (Panel Saving Function)

Saves the measurement conditions that are currently set.

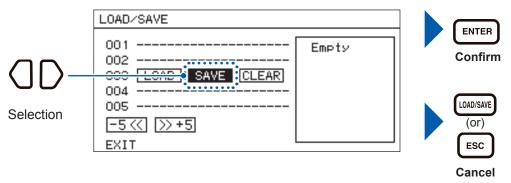




Select the number of the panel that will be saved.

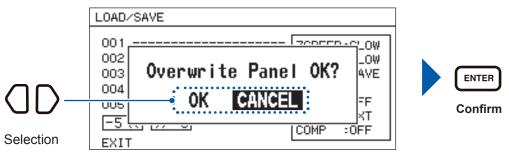


3 Select [SAVE].

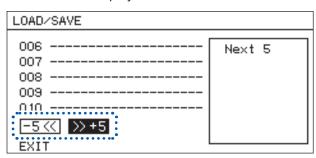


(When selecting the number of the panel that has been saved, the confirmation window will appear.)

OK: Overwriting CANCEL: Cancel



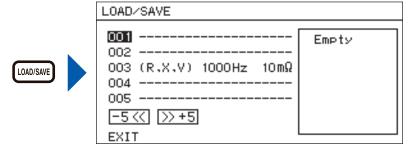
When **[+5]** is selected, the next 5 panel numbers are displayed. When **[-5]** is selected, the previous 5 panel numbers are displayed.



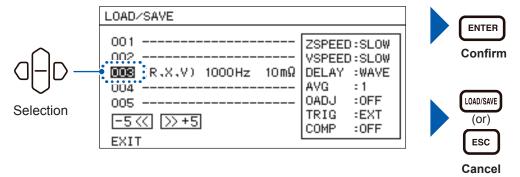
6.2 Reading the Setting Conditions (Panel Loading Function)

Reads the measurement conditions that are saved.

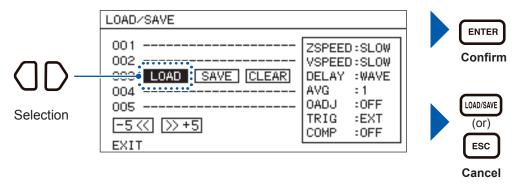




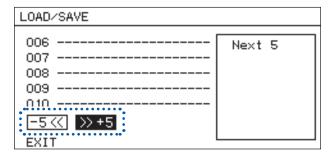
2 Select the number of the panel that will be read.



3 Select [LOAD].



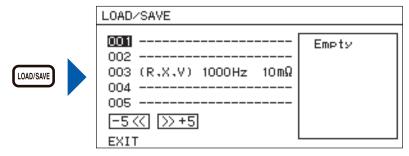
When [+5] is selected, the next 5 panel numbers are displayed. When [-5] is selected, the previous 5 panel numbers are displayed.



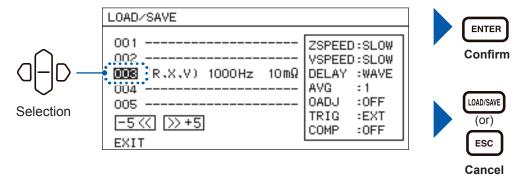
6.3 Deleting the Contents of the Panel

Deletes saved measurement conditions.

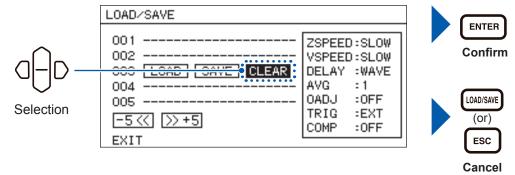
Press LOAD/SAVE). (Panel screen is displayed.)



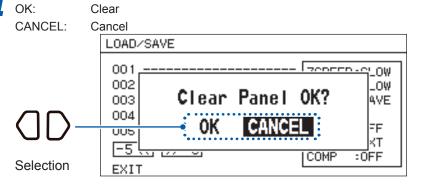
2 Select a panel number to be deleted.



3 Select [CLEAR].



Opens confirmation window.



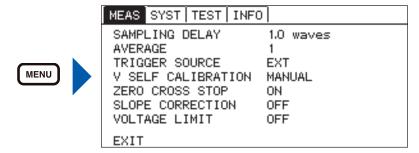
7 System Setting

7.1 Making the Key Operation Effective or Ineffective

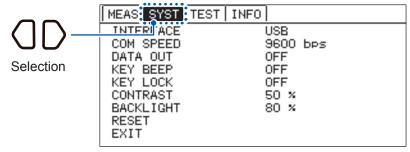
Makes the key operation except for START/STOP (START/STOP) ineffective.

Ineffective

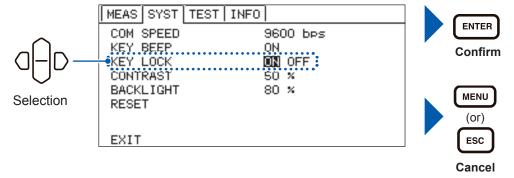
Press MENU (MENU). (The setting screen appears.)



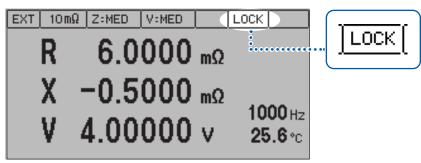
2 Select [SYST] tab.



3 Select [ON].

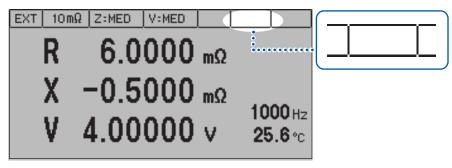


[LOCK] appears on the measurement screen, and the key operation becomes ineffective.



Effective

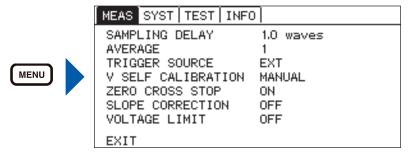
- 1 Press LocaL (LOCAL) and hold for at least 5 seconds.
- 2 [LOCK] disappears on the measurement screen, and the key operation becomes effective.



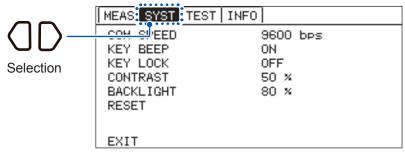
7.2 Setting the Sound of the Key Operation Effective or Ineffective

Make the sound of the key operation effective or ineffective.



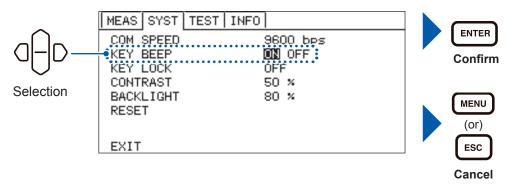


2 Select [SYST] tab.



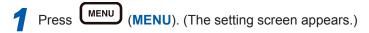
3 Select [ON] or [OFF].

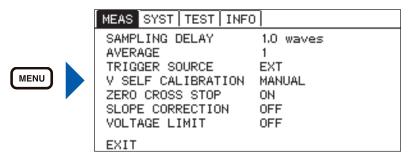
ON : The operation sound is beeped.
OFF : The operation sound is not beeped.



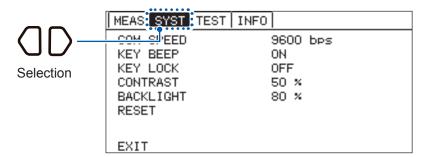
7.3 Adjusting the Contrast of the Screen

The visibility of the screen may not be clear at some ambient temperatures. The visibility of the screen can be adjusted by adjusting the screen contrast.





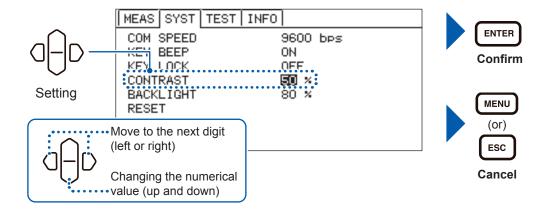
2 Select [SYST] tab.



3 Adjust the contrast of the screen.

: Increases the contrast.
: Decreases the contrast.

Setting range: 0% to 100%, steps of 5% (default setting: 50%)

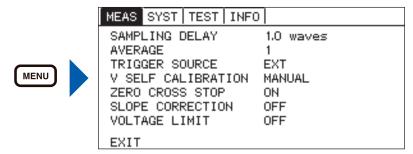


7.4 Adjusting the Backlight

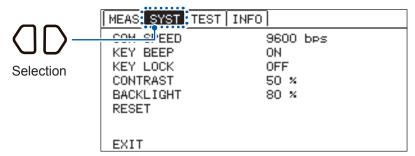
The brightness of the backlight can be adjusted for the illumination of the installation location.

When the trigger source is set from the external trigger, if the status with no operation continues for 1 minute, the brightness of the backlight will become dim automatically.

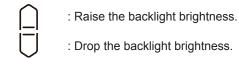
Press (MENU). (The setting screen appears.)



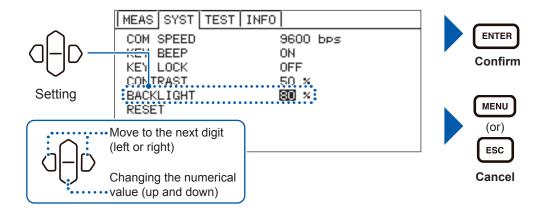
2 Select [SYST] tab.



3 Adjust the backlight.



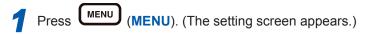
Setting range: 10% to 100%, steps of 5% (default setting: 80%)

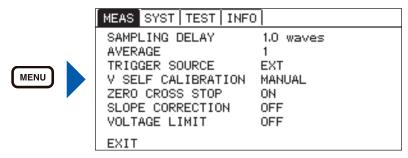


7.5 System Testing

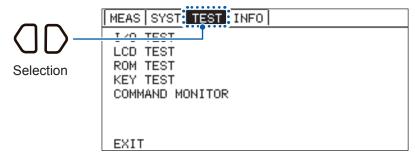
I/O TEST

The input and output test of the EXT. I/O can be performed. The ON and OFF of the output signal can be switched manually. In addition, the status of the input signal can be monitored on the screen.

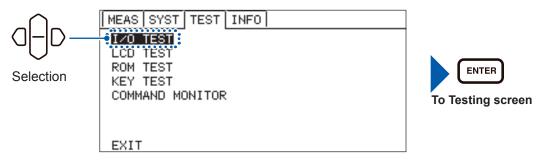




2 Select [TEST] tab.

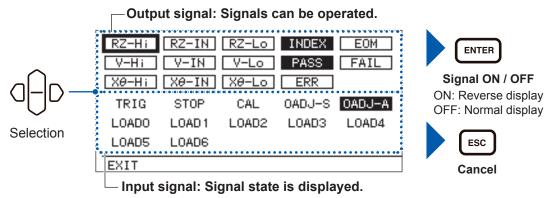


3 Select [I/O TEST].



Test I/O devices.

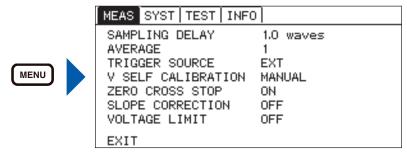
(Commands and queries due to communication could not be performed during I/O testing.)



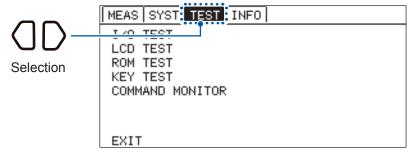
KEY TEST

This test can check that the key is not defective.

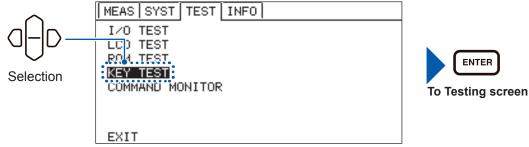
Press (MENU). (The setting screen appears.)



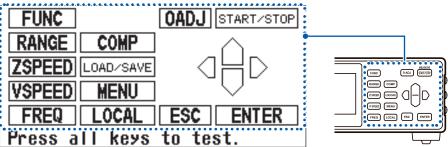
2 Select [TEST] tab.



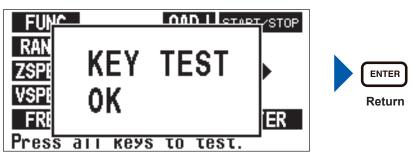
3 Select [KEY TEST].



Press the keys of the instrument to test the keys. (Check that all the key names on the screen are reversed.)

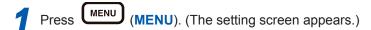


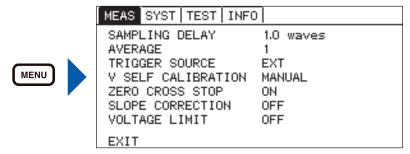
5 The screen returns to the key test screen.



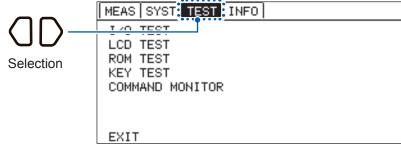
LCD TEST

This test can check that there is no dead pixel on the display screen.

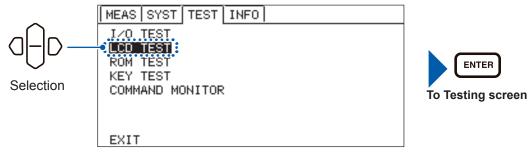




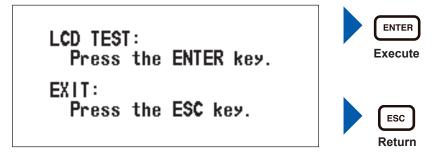
2 Select [TEST] tab.



3 Select [LCD TEST].



4 The explanation screen for test is displayed.



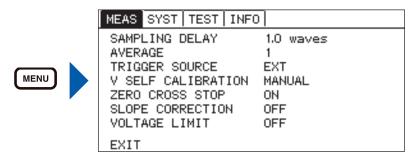
Press **ENTER**, and confirm that all screen indicators lights up and off repeatedly. (The display below shows that all screen indicators are lit off.)



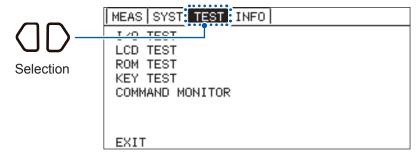
ROM TEST

This test can check that the program data of the instrument is normal.

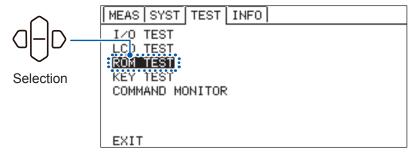
Press (MENU). (The setting screen appears.)



2 Select [TEST] tab.



3 Select [ROM TEST].

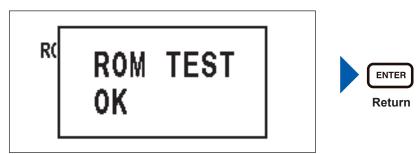




4 Test the ROM.

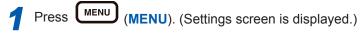


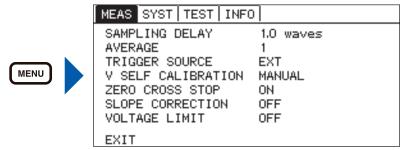
5 The screen returns to the ROM testing screen.



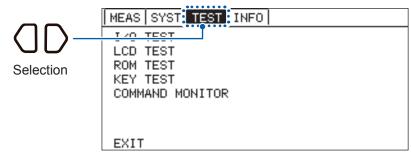
COMMAND MONITOR

Response of communications command and queries can be displayed on the screen.

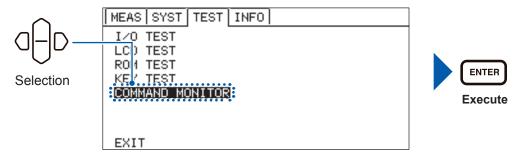




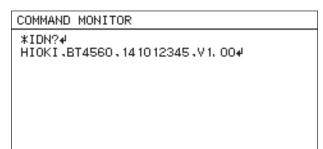
Select [TEST] tab.



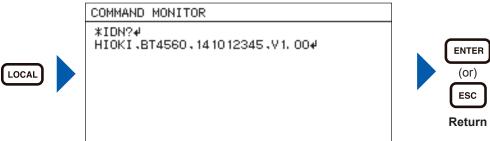
Select [COMMAND MONITOR].



Confirm the contents of the communication commands.

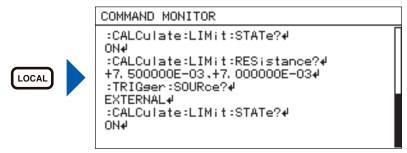


5 Press LOCAL (LOCAL). (Key operation is enabled.)

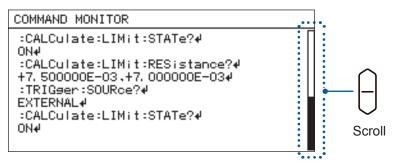


Scroll the screen if the confirmation screen becomes full.

1 Press Local (LOCAL). (Key operation is enabled.)



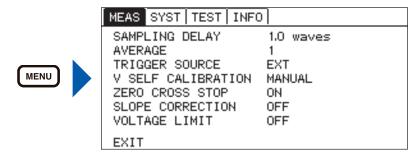
2 Scroll the screen.



7.6 Confirm Instrument Information

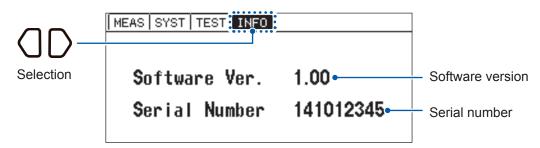
The software version and serial number are displayed.

Press MENU (MENU). (Settings screen is displayed.)



2 Select [INFO] tab.

(The software version and serial number will be displayed.)



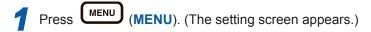
The 9-digit serial number indicates the year (first two digits) and the month of manufacture (next two digits).

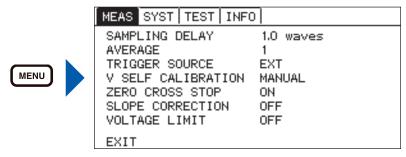
7.7 Initializing (Reset)

The reset function has three kinds of methods.

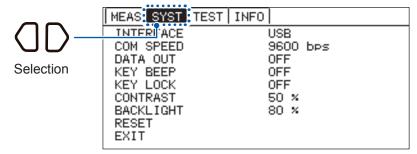
NORMAL	Initializing the settings to the factory default excluding the interface setting, zero adjustment values, and panel saving data.
SYSTEM	Initializing the settings to the factory default excluding the interface setting.
LAN	Resetting the LAN settings to the factory default.

For details of resetting items, refer to "Initial setting table" (p. 78).

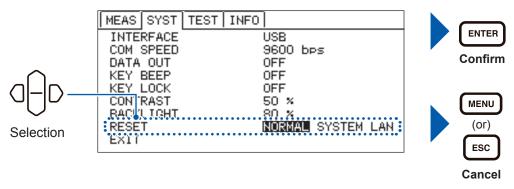




2 Select [SYST] tab.



3 Select the reset method.



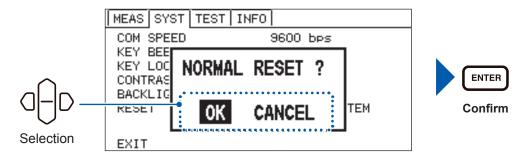


The confirmation window appears.

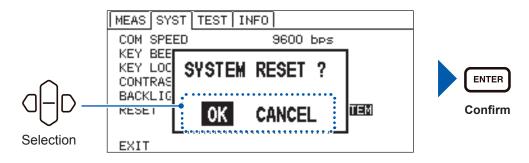
OK : Executes reset.

CANCEL: Returns to the measurement screen without execution.

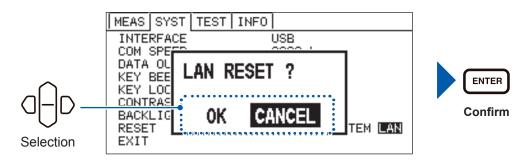
When NORMAL is selected



When SYSTEM is selected



When LAN is selected



5 The display returns to the measurement screen after the reset process is completed.

Initial setting table

ltem		Default setting	Initialization by normal reset (Communica- tion: *RST)	Initialization by system reset (Communication: SYSTem: RESet)	Returns to default when the power supply is turned ON	Panel Save/ Load
	Range	10 mΩ				
Mea	asurement frequency	1000 Hz				
Mea-	Voltage measurement	MED				
sure- ment speed	Impedance measurement	MED				
	Function	(R,X,V,T)				
	Trigger source	EXT				
	ON/OFF	OFF				
	Judgment buzzer beep	OFF				
	Voltage absolute value judgment	OFF	√			
	Upper limit value of R	OFF				
	Lower limit value of R	OFF				
Com-	Upper limit value of X	OFF				
parator	Lower limit value of X	OFF				
	Upper limit value of Z	OFF				
	Lower limit value of Z	OFF				
	Upper limit value of θ	OFF		√	_	_
	Lower limit value of θ	OFF		·		,
	Upper limit value of V	OFF				
	Lower limit value of V	OFF				
	Correction mode	OFF				
Zero	R Corrected value	0.0 mΩ				
Adjust- ment	X Corrected value	0.0 mΩ	_			
	V Corrected value	0.0V				
	Self -Calibration	AUTO				
	Delay mode	WAVE				
Sample	Delay time	1.0 wave				
delay	Acceptable range of deviation	10 μV				
Average		1	✓			
Measur	Measurement signal zero cross stop					
	Slope Correction					
Voltage	ON/OFF	OFF				
limit	Acceptable range	4.2 V				

Item		Default setting	Initialization by normal reset (Communica- tion: *RST)	Initialization by system reset (Communication: SYSTem:RESet)	Returns to default when the power supply is turned ON	Panel Save/ Load
	Screen contrast	50%			_	
5	Screen brightness	80%			_	
	Key-lock	OFF	v		✓	
Ke	ey operation buzzer	ON				
	Panel save	Not regis- tered	-	,	-	✓
	Continuous measurement (:INITiate:CONTinuous)	ON		~	✓	
	Response format for measurement value (:MEASure:VALid)	1 (Response for measure- ment value only)	√		-	
	Measured value output	OFF				
	Communication speed	9,600 bps				
	Header	OFF				
Interface	Status byte register	0			✓	-
	Event register	0				
	Enable register	0				
	Туре	USB	_	-		
	IP address	192.168.1.1				
	Subnet mask	255.255.0.0			_	
	Default gateway	OFF (0.0.0.0)				
	Port number	23				

✓: Applicable, -: Not applicable

Initializing (Reset)

8

External Control (EXT.I/O)

Using the EXT.I/O terminals on the rear of the instrument, the instrument can be controlled by external devices such as PLC.

The instrument can also be controlled by outputting the measurement ending signal and the judgment result signal, and by inputting the measurement starting signal by using the EXT.I/O connector on the rear. All of the signals are isolated from the measurement circuit and the ground. (The common terminals for input and output are shared.) The input circuit can be switched so as to correspond to the current sink output (NPN) or the current source output (PNP).

To use the instrument properly, confirm input/output ratings and the internal circuit configuration, and understand the safety precautions before connecting to a control system.



Signal input/output

Check the specifications of the controller's input/output.



Set the NPN/PNP switches of the instrument (p. 82).



Connect between the EXT.I/O connector of the instrument and the controller (p. 82).



Configure the instrument settings.

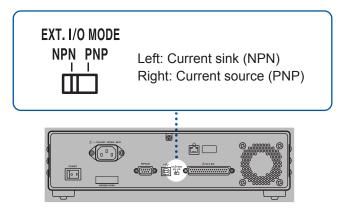
8.1 External Input/output Terminals and Signals

Switching the current sink (NPN) /the current source (PNP)

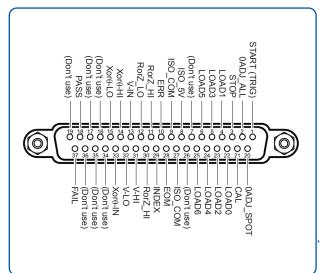
Before switching, be sure to read "Before switching the current sink (NPN) and the current source (PNP)" (p. 10).

The type of the PLC (programmable controller) that can be supported is changed by the NPN/PNP switch. The factory default is set to the NPN.

	NPN/PNP switch setting				
	NPN	PNP			
BT4560 input circuit	Corresponding to sink output	Corresponding to source output			
BT4560 output circuit	non-polarity	non-polarity			
ISO_5V output	+5 V output	-5 V output			



Arranging the usage connector and the signals



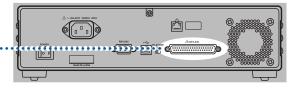
Usage connector

• 37-pin D-sub socket contact with #4-40 inch screws

Mating Connectors

- DC-37P-ULR (solder type)
- DCSP-JB37PR (compression contact type)
 Manufactured by Japan Aviation Electronics Industry, Ltd.

Other comparable products



Pin	Signal name	I/O	Function	Logic
1	START (TRIG)	IN	Starting the measurement (external trigger)	Edge
2	0ADJ_ALL	IN	All zero adjustment	Edge
3	STOP	IN	Stopping the measurement	Edge
4	LOAD1	IN	Loading number Bit 1	Level
5	LOAD3	IN	Loading number Bit 3	Level
6	LOAD5	IN	Loading number Bit 5	Level
7	(Don't use)	-	-	-
8	ISO_5V	-	Isolated power supply +5 V (-5 V) output	-
9	ISO_COM	-	Isolated power supply common	-
10	ERR	OUT	Measurement Error	Level
11	RorZ_HI	OUT	Resistance judgment result Hi, Impedance judgment result Hi	Level
12	RorZ_LO	OUT	Resistance judgment result Lo, Impedance judgment result Lo	Level
13	V_IN	OUT	Judgment result IN	Level
14	Xorθ_HI	OUT	Reactance judgment result Hi, Phase angle judgment result Hi	Level
15	Xorθ_LO	OUT	Reactance judgment result Lo, Phase angle judgment result Lo	Level
16	(Don't use)	-	-	-
17	(Don't use)	-	-	-
18	PASS	OUT	Judgment result PASS	Level
19	(Don't use)	-	-	-
20	0ADJ_SPOT	IN	Spot zero adjustment (SPOT)	Edge
21	CAL	IN	Performing Self-Calibration	Edge
22	LOAD0	IN	Loading number Bit 0	Level
23	LOAD2	IN	Loading number Bit 2	Level
24	LOAD4	IN	Loading number Bit 4	Level
25	LOAD6	IN	Loading number Bit 6	Level
26	(Don't use)	-	-	-
27	ISO_COM	-	Isolated power supply common	-
28	EOM	OUT	End of measurement	Edge
29	INDEX	OUT	Measurement reference number	Level
30	RorZ_HI	OUT	Resistance judgment result IN, Impedance judgment result IN	Level
31	V_HI	OUT	Voltage judgment result Hi	Level
32	V_LO	OUT	Voltage judgment result Lo	Level
33	Xorθ_IN	OUT	Reactance judgment result IN, Phase angle judgment result IN	Level
34	(Don't use)	-	-	-
35	(Don't use)	-	-	-
36	(Don't use)	-	-	-
37	FAIL	OUT	Judgment result FAIL	Level

IMPORTANT

The connector shell is conductively connected to the metal instrument chassis and the protective earth pin of the power inlet. Be aware that it is not isolated from ground.

Functions of each signal

Input signal

START (TRIG)	once on the	When START (TRIG) signal is switched from OFF to ON, measurement is performed once on the edge. This is only effective when TRIGGER SOURCE is set to the external [EXT] side.						
0ADJ_ALL		When the 0ADJ_ALL signal is switched from OFF to ON, all zero adjustment (p. 28) s performed once on the edge.						
STOP	When the Son the edge	-	l is switche	ed from OF	F to ON, t	he measur	ement is ir	nterrupted
0ADJ_SPOT	When the 0 (p. 28) is pe				m OFF to 0	ON, spot ze	ero adjustn	nent
CAL	setting, the the above is Self-calibra	When the CAL signal is switched from OFF to ON in the self-calibration manual setting, the self-calibration is started on the edge. When self-calibration is set to auto, the above is ineffective. Self-calibration takes approximately 210 ms. When a switch is input during measurement, self-calibration is performed after the measurement.						
LOAD0 to LOAD6	selected pa When the T ones, the pa is used, the	When the number of the panel to load is selected and the TRIG signal is input, the selected panel number is read and measured. LOAD0 is LSB and LOAD6 is MSB. When the TRIG signal is input, if LOAD0 to LOAD6 are the same as the previous ones, the panel load is not performed. In the above case, when the external trigger is used, the measurement is performed once as a normal TRIG signal. When the internal trigger is used, the input of LOAD0 to LOAD6 is ineffective.						
	Panel No.	LOAD6	LOAD5	LOAD4	LOAD3	LOAD2	LOAD1	LOAD0
	*	OFF	OFF	OFF	OFF	OFF	OFF	OFF
	1	OFF	OFF	OFF	OFF	OFF	OFF	ON
	2	OFF	OFF	OFF	OFF	OFF	ON	OFF
	3	OFF	OFF	OFF	OFF	OFF	ON	ON
	4	OFF	OFF	OFF	OFF	ON	OFF	OFF
	5	OFF	OFF	OFF	OFF	ON	OFF	ON
	6	OFF	OFF	OFF	OFF	ON	ON	OFF
	7	OFF	OFF	OFF	OFF	ON	ON	ON
	8	OFF	OFF	OFF	ON	OFF	OFF	OFF
	122	ON	ON	ON	ON	OFF	ON	OFF
	123	ON	ON	ON	ON	OFF	ON	ON
	124	ON	ON	ON	ON	ON	OFF	OFF
	125	ON	ON	ON	ON	ON	OFF	ON
	126	ON	ON	ON	ON	ON	ON	OFF
	*	ON	ON	ON	ON	ON	ON	ON
	* When turning all of the LOAD0 to LOAD6 to ON or OFF and then the START (TRIG) signal to ON, the panel loading is not performed.							
	 In the case of setting to the external trigger, the measurement is performed once after the completion of the loading. In the case of setting to the internal trigger, panel loading will not be performed. 							

Output signal

ERR	When a measurement error (p. 32) occurs, the output changes to ON. (In the case of the overrange, the output is OFF.) ERR is updated just before the EOM signal. When ERR is ON, all of the comparator judgment outputs become OFF. In the case of a measurement error: ERR output changes to ON In the case of a normal measurement: ERR output changes to OFF
PASS	When the results of the measurement parameters being judged are all IN, the PASS is ON. Example 1: When the functions (R, X, V, T) are set, if all of the measurement results of R, X, V are IN, the PASS is ON. Example 2: When the functions (V, T) are set, if the measurement result of V is IN, the PASS is ON.
EOM	EOM is end of measurement. When EOM changes to ON, the judgment result of the comparator and the ERR output have been determined.
INDEX	INDEX indicates that the A/D conversion has ended in the measurement circuit. When the signal changes from OFF to ON, the object being measured can be removed from the probe.
FAIL	It will be ON when the judgment results of comparator are Hi or Lo.
RorZ_HI	The RorZ_HI is the judgment result of the comparator for resistance or impedance.
RorZ_IN, RorZ_LO	The RorZ_IN and RorZ_LO are the judgment results of the comparator for resistance or impedance.
V_HI, V_IN, V_LO	They are the judgment results of the comparator for voltage.
Xorθ_HI, Xorθ_IN, Xorθ_LO	They are the judgment results of the comparator for reactant or a phase angle.

IMPORTANT

- The I/O signals cannot be used during changing the measurement conditions in the instrument.
- When the power supply is turned on, the EOM signal and the INDEX signal are initialized to ON.
- When it is not necessary to switch the measurement conditions, fix all of LOAD0 to LOAD6 at ON or OFF.
- To avoid misjudgment, check with both the PASS and FAIL signals for the judgment to the comparator.

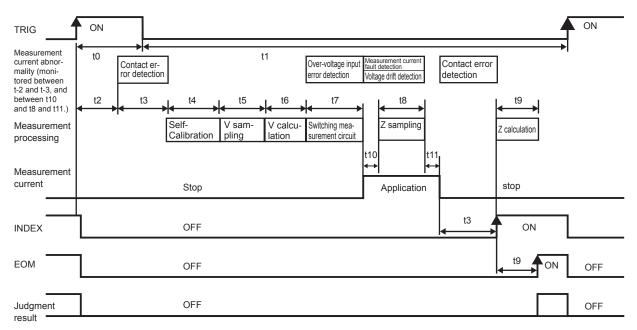
8.2 Timing Chart

The levels of each signal indicate the ON/OFF status of the contacts. In the case of the current source (PNP) setting, the signal levels are the same as the voltage level of the EXT.I/O terminals. In the case of the current sink (NPN) setting, the High and Low voltage levels are reversed.

Acquiring the judgment results after starting measurement

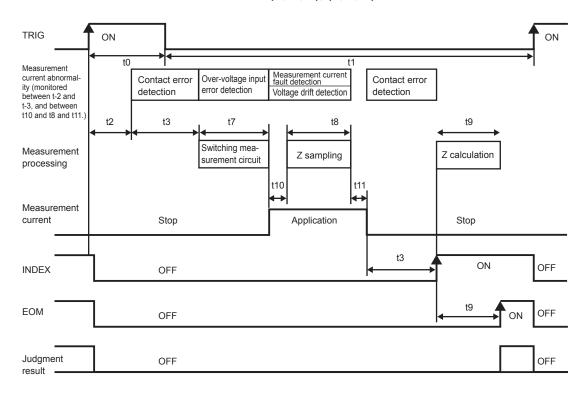
(1) When the external trigger [EXT] is set

In the case of measurement functions (R, X, V, T), (Z, θ , V, T)

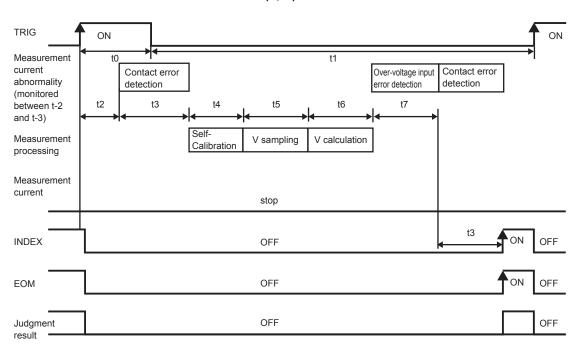


Judgment results: HI, IN, LO, PASS, FAIL, ERR

In the case of measurement functions (R, X, T), (Z, θ , T)



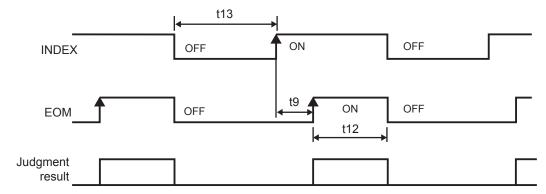
In the case of measurement functions (V, T)



- Do not input TRIG signal when measurement (INDEX signal is OFF) is in progress.
- When settings such as measurement frequency are changed, input the TRIG signal after the processing time (approx. 15 ms).
- The input signal is disabled when the measurement screen is not open, or when an error message is displayed.
- The output of the judgment result is determined before the EOM signal becomes ON. When the response of the controller input circuit is slow, a wait is required from when the EOM signal ON is detected until the judgment results are read.

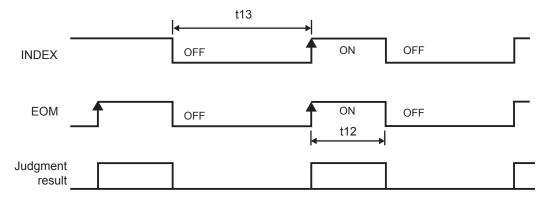
(2) When the internal trigger [INT] is set

In the case of measurement functions (R, X, V, T), (Z, θ , V, T), (R, X, T), (Z, θ , T)



Judgment results: HI, IN, LO, PASS, FAIL, ERR

In the case of measurement functions (V, T)



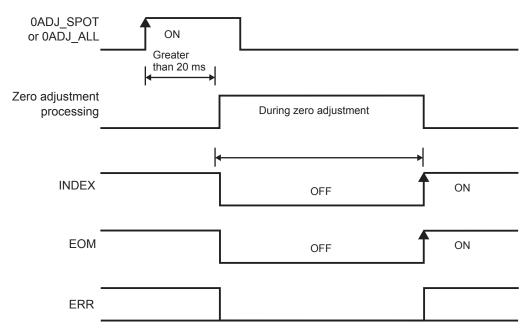
Timing chart interval descriptions

Item	Contents	Time (approximately)	Remarks
t0	Trigger pulse ON-time	0.1 ms or more	
t1	Trigger pulse OFF-time	1 ms or more	
t2	Response time	0.1 ms	
t3	Contact check time	10 ms	
t4	Self-Calibration time	210 ms	When self-calibration is set to AUTO, self-calibration is performed. In the case of the MANUAL setting, if the CAL signal is input, self-calibration is performed. For details, refer to p. 43.
t5	Voltage measurement sampling time	100 ms/400 ms/ 1 s	Measurement speed: FAST/MED/SLOW
t6	Voltage measurement calculation time	0.1 ms	
t7	Switching time of measurement circuit	58 ms	
t8	Impedance measurement sampling time	(1÷f)×N+T+0.016*	f: Measurement frequency, N: measurement wave number, T: Control time for sampling. The measurement wave number is determined by the measurement speed and the average number. For details, refer to p. 26, p. 44, and p. 109. Sampling control time differs due to the frequency. T=0.088÷ f (f: 0.1 Hz to 66 Hz) T=0.36÷ f (f: 67 Hz to 250 Hz) T=1.5÷ f (f: 260 Hz to 1050 Hz)

Item	Contents	Time (approximately)	Remarks
t9	Calculation time in impedance measurement	70 ms	Measurement frequency: 1 kHz, Z measurement speed: SLOW, Slope correction: representative value of ON
t10	Sample delay	(1÷f)×M* +0.005 s	f: Measurement frequency, M: Sample delay setting wave number For the setting wave number, refer to (p. 40).
t11	Measurement signal zero-cross detection	(1÷f) or less*	f: Measurement frequency To prevent charging and discharging the measuring object, the applied AC signal is processed to end at zero cross. It will be applied if the measurement signal zero cross stop function is ON. (p. 49)
t12	EOM pulse width in the internal trigger	100 ms	
		t2+t3×2+t4+t5+t6+t7+t8+t9 +t10+t11	In the case of the functions (Z,θ,V,T) or (R,X,V,T)
t13	Total measurement time	t2+t3×2+t7+t8+t9+t10+t11	In the case of functions (Z,θ,T) or (R,X,T)
		t2+t3×2+t4+t5+t6+t7	In the case of the functions (V,T)

* Unit is "s".

Timing of the zero adjustment



The ERR signal becomes ON or OFF dependent on the result of the zero adjustment. When the zero adjustment is performed normally, the ERR is OFF. When it is not performed normally, the ERR is ON synchronously with the EOM.

IMPORTANT

For signals 0ADJ_SPOT and 0ADJ_ALL, input when it is not in measurement state.

Timing of the self-calibration

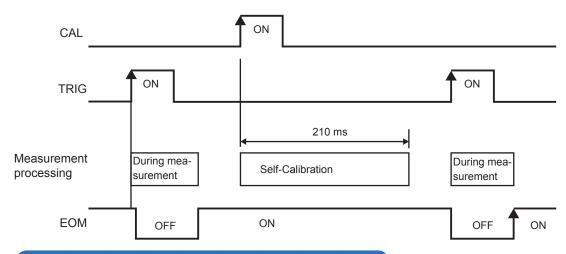
When the self-calibration setting is **[AUTO]**, the self-calibration always is performed before the voltage measurement. The self-calibration is performed to maintain the accuracy of the voltage calibration. In the case of the measurement functions (R, X, T) and (Z, θ , T) where the voltage measurement is not performed, the self-calibration is not performed. (Even if the CAL signal is input, the self-calibration is not performed.)

Operation when the self-calibration setting is [MANUAL]

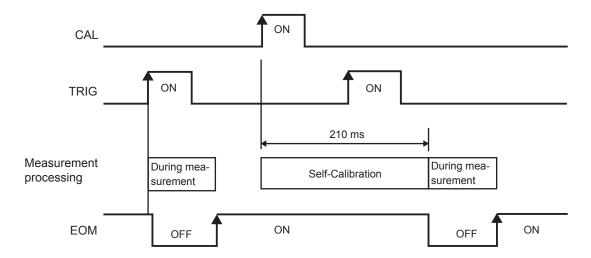
The CAL signal is input, and the self-calibration is started immediately.

Even if the TRIG signal is input during the self-calibration, the self-calibration is continued. In this case, the trigger signal is held and then the measurement is started after the completion of the self-calibration. When the CAL signal is input during the measurement, the CAL signal is held and then the self-calibration is started after the completion of the measurement.

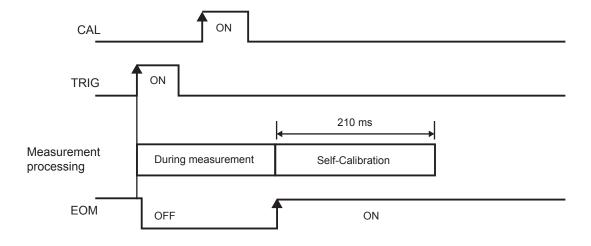
Normal usage



When the TRIG signal is input during the self-calibration

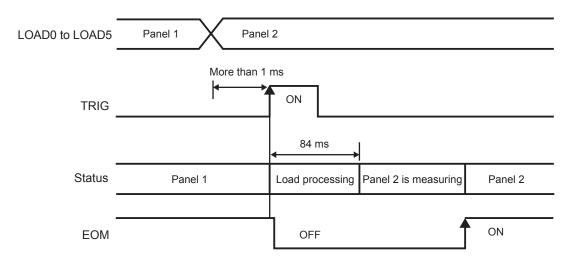


When the CAL signal is input during the measurement



Timing of the panel loading

When the TRIG signal is used

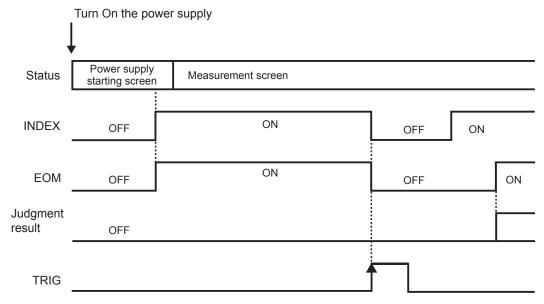


IMPORTANT

The timing to identify the panel number is not when trigger is input (TRIG:ON), but when it reads the LOAD signal right before the measurement starts. Fix the LOAD signal before the measurement (INDEX:OFF, EOM:OFF) starts.

Output signal status when turning ON the power supply

After turning on the power supply, when the screen changes from the start-up screen to the measurement screen, the EOM signal and the INDEX signal changes to ON.

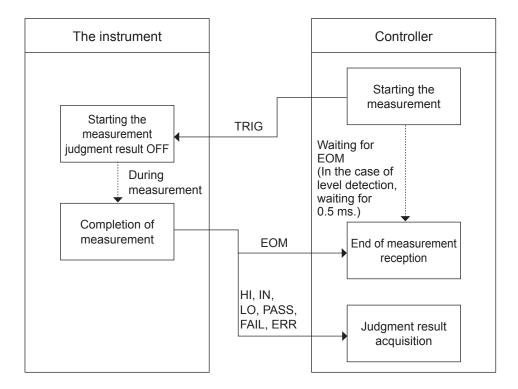


Judgment results: HI, IN, LO, PASS, FAIL, ERR

The above chart indicates the operation when the trigger source is set to the EXT.

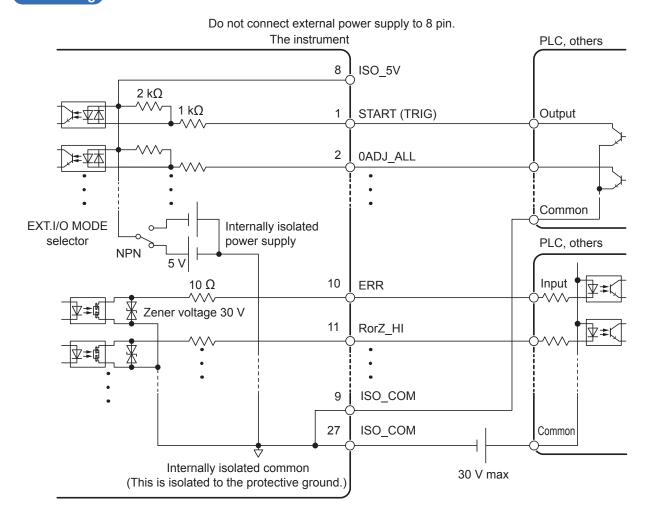
Taking-in flow with the external trigger

With the external trigger, the diagram indicates the flow from the starting of the measurement to the taking-in of the judgment result or the measured values. The instrument outputs the EOM signal immediately after the judgment results (HI, IN, LO, PASS, FAIL, ERR) have been determined. When the response of the controller's input circuit is delayed, it takes a waiting time from the detection of the EOM signal's ON status to the taking-in of the judgment results.

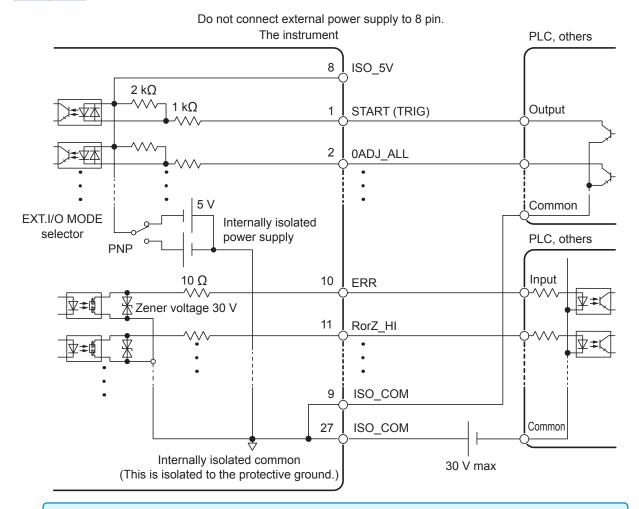


8.3 Internal Circuitry

NPN setting



PNP setting



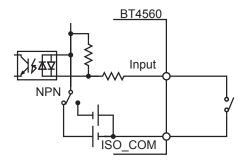
Share the ISO_COM for the common terminals of the input and the output signal.

Electrical Specifications

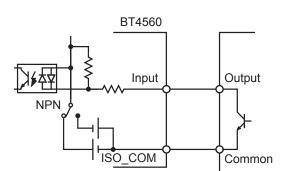
Input signal	Input type	Photo-coupler-isolated, non-voltage contact inputs (corresponding to current sink/source output)
	Input ON	Residual voltage 1 V (Input ON Current 4 mA (reference value))
	Input OFF	OPEN (Breaking current less than 100 μA)
Output signal	Output type	Photo-coupler-isolated open drain output (non-polarity)
	Maximum load voltage	30 V max DC
	Maximum output current	50 mA/ch
	Residual voltage	Less than 1 V (Load current 50 mA)/less than 0.5 V (Load current 10 mA) $$
Internally isolated power	Output voltage	Corresponding to sink output: +5.0 V±10%, Corresponding to source output: -5.0 V±10%
supply	Maximum output current	100 mA
	External power input	None
	Insulation	Floating from the protective grounding potential and the measurement circuit
	Insulation rating	Voltage to ground 50 V DC, 33 V AC rms, less than 46.7 Vpeak AC

Examples of connection

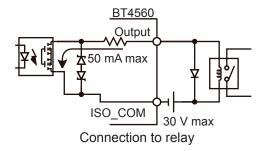
Examples of input circuit connection

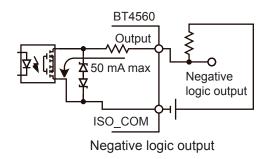


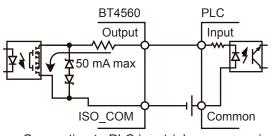
Connection to switch



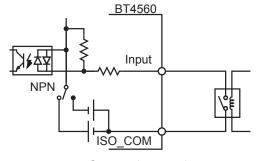
Connection to PLC output (NPN output)



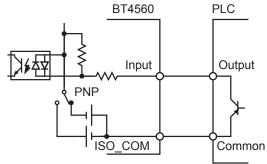




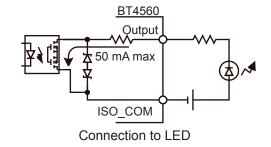
Connection to PLC input (plus common input)

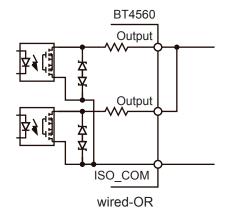


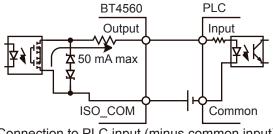
Connection to relay



Connection to PLC output (PNP output)







Connection to PLC input (minus common input)

8.4 Checking the External Control

Testing the inputs/outputs (EXT.I/O testing functions)

The output signal can be switched ON and OFF manually. In addition, the condition of the input signal can be monitored on the screen.

For details, refer to "I/O TEST" (p. 70).

Communication (RS-232C, USB, LAN)

9.1 Features of Interface

The communication interface can be used for the following.

- · Controlling the instrument using commands and acquiring data.
- · Using application software.

The command table and the application software can be downloaded from our website.

Only the BT4560-50 can communicate on a LAN.

Specifications

USB

Connector	Series B receptacle
Electrical Specifications	USB2.0 (pseudo COM port)
Class	CDC class (COM mode)
Transmission speed	9,600 bps, 19,200 bps, 38,400 bps
Data length	8 bit
Parity bit	None
Stop bit	1 bit
Message terminator (Delimiter)	When received: CR+LF, CR When transmitting: CR+LF

RS-232C

Transmission method	Communication method: Full duplex, Synchronous system: Asynchronous communication method		
Transmission speed	9,600 bps, 19,200 bps, 38,400 bps		
Data length	8 bit		
Parity bit	None		
Stop bit	1 bit		
Message terminator (Delimiter)	When receiving: CR+LF, CR When transmitting: CR+LF		
Flow control	None		
Electrical Specifications	Input voltage levels: 5 V to 15 V: ON, -15 V to -5 V: OFF		
	Output voltage levels: 5 V to 9 V: ON, -9 V to -5 V: OFF		
Connector	Layout of interface connector (D-sub9 pin, pin contact, mating fixed base screw #4-40)		
	The input/output connectors follow terminal (DTE) specifications.		
	Recommended cable: 9637 RS-232C cable (for computer)		

Code in use: ASCII code

LAN(BT4560-50 only)

Applicable standard	IEEE802.3	
Transmission method	10BASE-T / 100BASE-TX automatic recognition Half/Full Duplex, Auto MDI-X	
Protocol	TCP/IP	
Connector	RJ-45	
Communication description	ication description Setting and measured value acquisition by using communications commands	

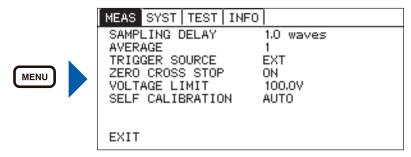
9.2 Connecting and Setting Method

The instrument cannot control USB and RS-232C communications simultaneously. When computers are connected to the BT4560 via both the USB and RS-232C ports, only USB communications are available.

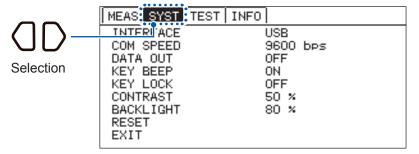
As for BT4560-50, the communications method selected under the procedure described in the section "Setting LAN communications" (p. 99) is available.

Selecting an interface

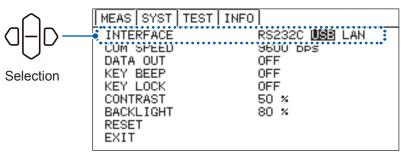
Press MENU (MENU). (The setting screen appears.)



2 Select [SYST] tab.



3 Select [INTERFACE] and select the interface to be used.



IMPORTANT

When you select LAN, set the IP address etc. on the Web browser.

For more information about how to access the instrument, see "Setting LAN communications" (p. 104).

Using the USB interface

When the instrument is first connected to a computer, it is necessary prepare the dedicated USB driver. If the driver has already been installed, for example, due to using products from other manufacturers, the following procedure is not necessary. The USB driver can be downloaded from our website.

Installation procedure

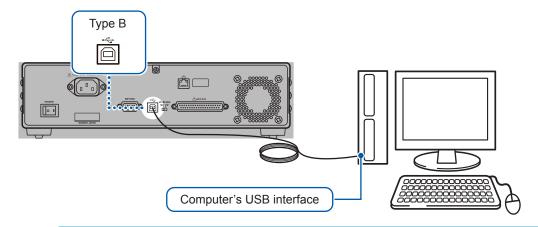
Perform the installation before connecting between the instrument and the computer with the USB cable. If they already connected, unplug the USB cable.

- 1 Log into the computer with administrative privileges such as "administrator".
- **2** Before installation, exit all applications that are running on the computer.
- 3 Run drivers install program.
 It may take some time until the dialog box appears, depending on the system environment.
 Wait for the dialog box.
- 4 After installation, when the instrument is connected to the computer via USB, the instrument is automatically recognized.
 - When the Hardware Wizard screen for new hardware appears, select "No, not this time" when "Windows Update" prompts to connect, and then select "Install the software automatically".
 - If an instrument with a different serial no. is connected, you may be notified that a new device has been detected. If this happens, install the device driver by following the instructions on the screen.

Uninstallation procedure (Uninstall the driver if you no longer need it.)

Using [Control Panel] - [Add or Remove Programs], delete PL-2303 USB-to-Serial.

Connect the USB cable



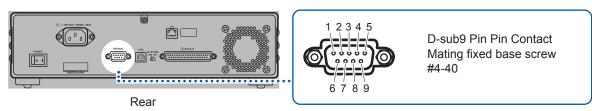
IMPORTANT

The instrument's USB port is a pseudo COM port. In the case of the communication, it is necessary to set the speed as well as the RS-232C. In the COM port setting, the COM port number that is allocated to the USB port varies with the computer in use. Check the COM port number that is allocated by the following method.

- 1. Open the device manager.
- 2. The "X" of Prolific PL2303GC USB Serial COM Port (COMX) under "Port (COM and LPL)" is the COM port number.

Using the RS-232C cable

Connect the RS-232C cable to the RS-232C Connector. When connecting the cable, be sure to fasten the screws.



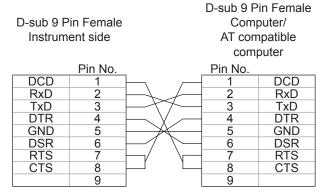
When connecting to the controller (DTE), prepare the <u>crossing cable</u> that is suited to both specifications of this instrument side and the controller side. Input/output cables are applied to Terminal (DTE) specifications. The instrument uses the pin numbers of 2, 3, and 5. The other pins are not used.

PIN No.	Signal name		e		
	Common use	EIA	JIS	Signal	Remarks
1	DCD	CF	CD	Career detection	Unconnected
2	RxD	BB	RD	Receive data	
3	TxD	ВА	SD	Transmit Data	
4	DTR	CD	ER	Data Terminal Ready	ON level (+5 V to +9 V) fixed
5	GND	AB	SG	Ground for signal	
6	DSR	CC	DR	Data Set Ready	Unconnected
7	RTS	CA	RS	Request to Send	ON level (+5 V to +9 V) fixed
8	CTS	СВ	CS	Clear to Send	Unconnected
9	RI	CE	CI	Calling Indicator	Unconnected

When connecting Instrument to computer

Use crossing cable of D-sub9 Pin Female - D-sub9 Pin Female.

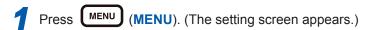
Cross connection

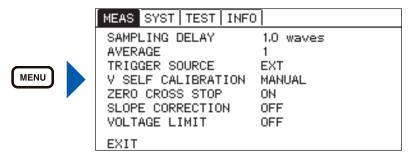


Recommended cable: Model 9637 RS-232C Cable (1.8 m) manufactured by HIOKI

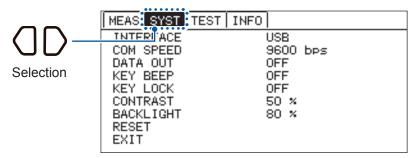
Setting the transmission speed (Common for USB, RS-232C)

The instrument sets the transmission speed (baud rate) of the interface. It is necessary to set the transmission speed when either the USB communication or the RS-232C communication is used.

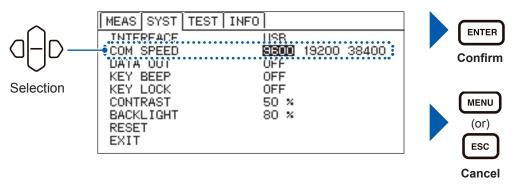




2 Select [SYST] tab.



3 Select [COM SPEED] and set SPEED.



Setting the controller (Computer or PLC)

Be sure to set to the following.

- Start-stop synchronization
- Transmission speed: 9,600 bps, 19,200 bps, 38,400 bps (Adjust to the instrument's setting.)
- Stop bit: 1
- Data length: 8
- · Parity check: Not provided
- · Flow control: Not provided

IMPORTANT

The fast transmission speed (baud rate) may not be used due to a large error caused by some computers. In that case, use with lower transmission speed.

Using the LAN interface

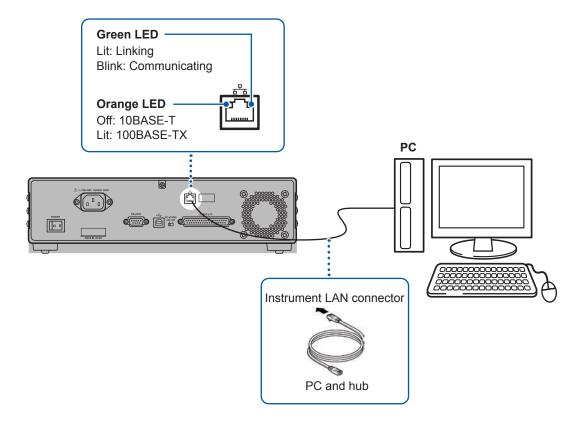
Connect a LAN cable to the LAN connector of the instrument.

A CAUTION



When connecting the instrument to your LAN using a LAN cable of more than 30 m or with the cable laid outdoors,take appropriate countermeasures that include installing a surge protector for LANs. Such signal wiring is susceptible to inducedlighting, which can cause damage to the instrument.

Recommended cable: Model 9642 LAN cable (optional)



Setting LAN communications

IMPORTANT

The settings differ between when the instrument and an external device are to be connected to an existing network and when the instrument and a PC are to be connected one-to-one to create a new network.

Check the connection method before configuring the settings.

Connecting the instrument to the existing network

The network administrator (department) needs to assign the following items in advance. Be sure to assign a unique address and port number that are different from any other devices.

Address settings of the instrument	
IP address:	
Subnet mask:	
Gateway	
Whether or not to use a gateway:	Use / Not use
IP address (if used):	(Set to 0.0.0.0 if not used)
Communication command port No. to be used:	(Default setting: 23)

Creating a new network using the instrument and a PC

(Using a local network that is not connected externally)

The addresses shown below are recommended if there is no administrator or you are responsible for setting.

IP address	Set sequential IP addresses as shown below.	
PC:	192.168.1.100	
First instrument:	192.168.1.1 (instrument's default setting)	
Second instrument:	192.168.1.2	
Third instrument:	192.168.1.3 ↓	
Subnet mask:	255.255.0.0 (instrument's default setting)	
Gateway:	OFF (instrument's default setting)	
Communication command port number:	23 (instrument's default setting)	

1 Start a web browser.

You can change the instrument's LAN interface settings using a web browser, such as Microsoft Edge.

The description below uses Microsoft Edge as an example.

- 1. Click the start button on the bottom-left corner of the computer screen, and then click [Microsoft Edge] in the menu
- 2. Enter the character string [http://] followed by the IP address or the computer name in the address bar. The default IP address is [192.168.1.1].



Example: If the instrument's IP address is 192.168.1.1, enter [http://192.168.1.1] in the address bar.

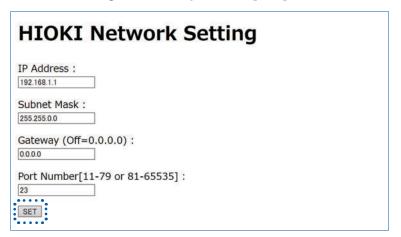
If you don't know the IP address, you can change the setting as follows.

Enter [http://hioki-] in the address bar, followed by the last six digits of the instrument's MAC address. You can find the MAC address on the sticker on the rear of the instrument.



Example: If the instrument's MAC address is 11-22-33-88-99-FF, enter [http://hioki-8899FF] in the address bar.

Configure settings of the instrument using the web browser. Enter the settings, and then press the [SET] button.

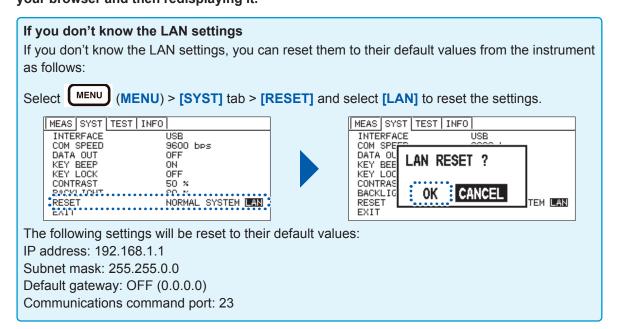


Setting items

- cttiiig itoiiio		
IP Address	The IP addresses are used to identify individual devices on the network. Assign a unique address different from that of other devices.	
Subnet Mask	The subnet mask divides the IP address into the network address and the host address. Configure the subnet mask settings in the same way as those of other devices on the network.	
Gateway	For network connection When the communication PC and the instrument are in different networks, specify the IP address of the device that becomes a gateway. If the PC is in the same network, set a gateway address that is the same as the default gateway in the general PC settings. For one-to-one connection between the instrument and PC or when no gateway is used Set the IP address to 0.0.0.0.	
Port Number	Specify the TCP/IP port number to use for communications command connections. Port 80 cannot be used.	

3 Cycle the instrument's power.

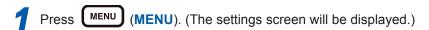
Cycle the instrument's power to accept its internal LAN setting and enable communications. You can check the instrument's setting by closing the tab showing the settings screen in your browser and then redisplaying it.

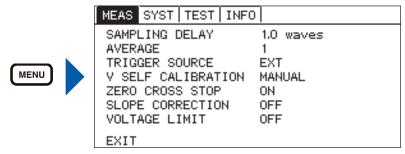


Outputting Measured Values after Measurement Completes

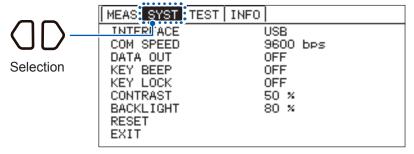
When measurement completes after being initiated with the **START/STOP** key or a communications command (*TRG) while using the external trigger setting, the measured values will be output to the selected interface. This function cannot be used when using the internal trigger setting. The response format is the same as for the measured value acquisition query (:FETCh?/:READ?). (Scan operation time can be reduced by using this function with the SW1001 Switch Mainframe.)

Before starting measurement, ensure the controller that will receive measured values can accept a string of text. Perform the desired processing once the controller receives the terminator characters (CR+LF), which indicate the end of the measured value string, for example to save the value to a file or display it, and then prepare the controller so that it can receive another string.

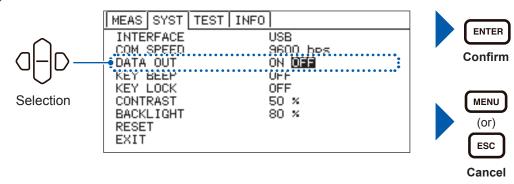




2 Select [SYST] tab.



3 Select [DATA OUT], set to [ON] or [OFF], and press the ENTER key to accept the setting.



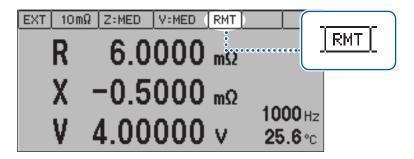
9.3 Controlling the Communication and Acquiring the Data

For the description (communication message reference) of the communication commands and queries, refer to the Communication Command Instruction Manual for the Application Software.

Remote state/Local state

During the communication, the instrument becomes the remote status, and **[RMT]** appears on the measurement screen. Then, the operation keys except for **LOCAL** key are ineffective.

Press LOCAL). Then, the remote status is released and the key operation is possible.



When the instrument indicates the setting screen, if it becomes the remote status, the screen automatically moves to the measurement screen.

10 Specifications

10.1 Specifications of Measurement Functions

Impedance measurement

Measurement signal	Constant current AC signal		
Measurement method	Four-terminal pair method		
Measurement terminal structure	BNC		
Measurement terminal	SOURCE-H terminal	Current generation terminal	
function	SOURCE-L terminal	Current detection terminal	
	SENSE-H terminal	Voltage detection terminal	
	SENSE-L terminal	Voltage detection terminal	
Measurement items	Impedance	(Parameter indication: Z)	
	Phase angle	(Parameter indication: θ)	
	Resistance	(Parameter indication: R)	
	Reactance	(Parameter indication: X)	
Range structure	3 mΩ/10 mΩ/100 mΩ		
Measurement speed setting	FAST/MED/SLOW		

Display range/Resolution

		3 mΩ range	10 mΩ range	100 mΩ range
Z	Display range	$0.0000~\text{m}\Omega$ to $3.6000~\text{m}\Omega$	0.0000 m Ω to 12.0000 m Ω	0.000 m Ω to 120.000 m Ω
	Resolution	0.1 μΩ	0.1 μΩ	1 μΩ
θ	Display range	-180.000° to 180.000°	-180.000° to 180.000°	-180.000° to 180.000°
	Resolution	0.001°	0.001°	0.001°
R Display range $-0.1000 \text{ m}\Omega \text{ to } 3.6000 \text{ m}\Omega$ Display range (BT4560-60) $-1.5000 \text{ m}\Omega \text{ to } 3.6000 \text{ m}\Omega$		-0.1000 m Ω to 3.6000 m Ω	-0.3000 m Ω to 12.0000 m Ω	
		-1.5000 m Ω to 3.6000 m Ω	-1.5000 m Ω to 12.0000 m Ω	-3.000 m Ω to 120.000 m Ω
	Resolution	0.1 μΩ	0.1 μΩ	1 μΩ
Х	Display range	-3.6000 m Ω to 3.6000 m Ω	-12.0000 m Ω to 12.0000 m Ω	-120.000 m Ω to 120.000 m Ω
	Resolution	0.1 μΩ	0.1 μΩ	1 μΩ

Frequency range	Frequency range	0.01 Hz to 1050 Hz	
		0.01 Hz to 10.00 kHz	(BT4560-60)

0.01 Hz to 0.99 Hz	0.01 Hz step
1.0 Hz to 9.9 Hz	0.1 Hz step
10 Hz to 99 Hz	1 Hz step
100 Hz to 1050 Hz	10 Hz step
100 Hz to 10.00 kHz	10 Hz step (BT4560-60)
±0.01% of setting or less	
	1.0 Hz to 9.9 Hz 10 Hz to 99 Hz 100 Hz to 1050 Hz 100 Hz to 10.00 kHz

Measuring current accuracy

Frequencies above 10.6 kHz are outside the accuracy specification range. (BT4560-60)

	3 mΩ range	10 mΩ range	100 mΩ range
Measurement current	1.5 A rms ±10%	500 mA rms ±10%	50 mA rms ±10%

DC load

(DC load is the offset current that is applied to the measuring object when measuring the impedance.)

	3 mΩ range	10 mΩ range	100 mΩ range	
DC load current	1 mA or less	0.35 mA or less	0.035 mA or less	

Measurement wave		FAST	MED	SLOW	Remarks
number	0.01 Hz to 66 Hz	1 wave	2 waves	8 waves	
	67 Hz to 250 Hz	2 waves	8 waves	32 waves	
	260 Hz to 1050 Hz	8 waves	32 waves	128 waves	
	260 Hz to 1.00 kHz	8 waves	32 waves	128 waves	
	1.01 kHz to 2.00 kHz	128 waves	128 waves	128 waves	
	2.01 kHz to 4.00 kHz	256 waves	256 waves	256 waves	BT4560-60
	4.01 kHz to 8.00 kHz	512 waves	512 waves	512 waves	
	8.01 kHz to 10.00 kHz	1024 waves	1024 waves	1024 waves	

The measurement frequency above 1.01 kHz is the same as SLOW.

Overrange indication OverRange

Voltage measurement

Measurement terminal structure	BNC	
Measurement terminal	SENSE-H terminal	Voltage detection terminal
function	SENSE-L terminal	Voltage detection terminal
Measurement items	Voltage (Parameter indication: V)	
Range structure	5 V (single range)	
Display range	-5.10000 V to 5.10000 V	
Resolution	10 μV	
Measurement speed setting	FAST/MED/SLOW	

Measurement time	FAST	0.1 s
	MED	0.4 s
	SLOW	1.0 s
	(When self calibration	is AUTO, 210 ms is added to the measurement time.)
Sampling period	6 kHz	
Overrange display	OVER VOLTAGE	

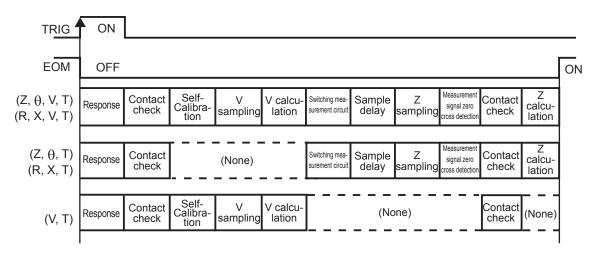
Temperature measurement

Measurement terminal structure	Four-terminal earphone jack φ3.5 mm		
Measurement items	Temperature (Parameter indication: T)		
Display range	-10.0°C to 60.0°C		
Resolution	0.1°C		
Sampling time	2.3 s		
Overrange indication	+Over°C, -Under°C		
Indication when unconnected	°C		

Function

Function structure $(R,\,X,\,V,\,T)/(Z,\,\theta,\,V,\,T)/(R,\,X,\,T)/(Z,\,\theta,\,T)/(V,\,T)$

Measurement sequence



The self-calibration is performed when the self-calibration setting is **[AUTO]**. Measurement signal zero cross detection is performed when the measurement signal zero cross stop function is **[ON]**.

Measurement time

Response time	0.1 ms	
Contact check time	10 ms	
Self-Calibration time	210 ms	
V Sampling time	0.1 s/0.4 s/1.0 s (FAST/MED/SLOW)	
V calculation time	0.1 ms	
Switching time of measurement circuit	58 ms	
Sample delay time	(1÷f) × M+5 ms (f: Measurement frequency, M: Set wave number)	
Z sampling time	(1÷f) × N+T+0.016 (f: Measurement frequency, N: Measurement wave number, T: Sampling control time) (Unit is "s") T=0.088÷f (f:0.01 Hz to 66 Hz) T=0.36÷f (f:67 Hz to 250 Hz) T=1.5÷f (f:260 Hz to 1050 Hz) T=1.5÷f (f:260 Hz - 10.00 kHz)(BT4560-60)	
Measurement signal zero cross detection	(1÷f) or less (f: Measurement frequency) (Unit is "s")	
Z calculation time	70 ms	

Total measurement time	Function (R, X, V, T)/(Z, θ , V, T) Response time + Contact checking time × 2 + (Self calibration time) + Self sampling time + V calculation time + Measurement circuit switching time + Sample delay time + Z sampling time + (Measurement signal zero cross detection time) + Z calculation time
	Function (R, X, T)/(Z, θ , T) Response time + Contact checking time × 2 + Measurement circuit switching time + Sample delay time + Z sampling time + (Measurement signal zero cross detection time) + Z calculation time
	Function (V, T) Response time + Contact checking time × 2 + (Self calibration time) + Self sampling time + V calculation time
	(Self calibration time is added when the self calibration is set to [AUTO] .) (Measurement signal zero cross detection time is added when the measurement signal zero cross stop function is [ON] .)

10.2 Additional Function

Measurement

Range setting

Function overview	Setting measurement range of impedance. (Voltage and temperature have no setting due to the single range.)	
Function setting	3 m Ω /10 m Ω /100 m Ω (AUTO setting is not provided.)	
Setting backup	Yes	

Frequency setting

Function overview	Setting the measurement frequency of impedance measurement.	
Function setting	0.01 Hz to 1050 Hz	
	0.01 Hz to 10.00 kHz	BT4560-60
Setting backup	Yes	

Measurement speed setting

Function overview	Setting impedance measurement, Setting measurement speed of voltage measurement.	
Function setting	Impedance measurement	FAST/MED/SLOW
	Voltage measurement	FAST/MED/SLOW
Setting backup	Yes	

Function setting

Function overview	Setting measurement functions.
Function setting	$(R,X,V,T)/(Z,\theta,V,T)/(R,X,T)/(Z,\theta,T)/(V,T)$
Setting backup	Yes

Setting trigger source

Function overview	Trigger settings for measurement start.		
Function setting	EXT/INT EXT: External trigger INT: Internal trigger (The voltage limit is turned ON when the internal trigger is set.)		
Setting backup	Yes		

Stopping the measurement

Function overview	Stopping the measurement.
Function setting	By pressing START/STOP key during measurement, measurement stops.

Indicating measurement status

Function overview	Indicating measurement in operation on the screen.	
Function operation	When measuring at 1 Hz or lower, the LCD screen will indicate that a measurement is in progress.	

Panel saving and loading

Function overview	Saves and reads measurement conditions.	
Adaptive conditions	Function, Range,Impedance measurement speed, Voltage measurement speed,Frequency,Comparator setting, Zero adjustment setting, Zero adjustment data, Sample delay setting, Average, Trigger source setting, Self calibration setting, Measurement signal zero cross stop setting, Slope correction setting, Voltage limit	
Numbers of panel	126	
Function setting	Save	Saving current measurement conditions
	Load	Reading saved measurement conditions
	Clear	Erases saved measurement conditions
	Detailed display	Displays saved measurement conditions (displays adaptive conditions)
Setting backup	Yes (Backs up panel data)	

Detecting the measurement error

Function overview	 Abnormal connection detection function for measurement terminals. 	
	Outputs an error when a resistance threshold for contact error output is exceeded.	

Malfunction detection contents

Detected contents	Detection timing	Indication
Measurement current error	Between trigger acceptance and voltage measurement Between sampling delay and measurement signal zero cross stop	
Contact error between SOURCE-H and SENSE-H	Before and after measurement	CONTACT ERROR H
Contact error between SOURCE-L and SENSE-L	Before and after measurement	CONTACT ERROR L
Voltage drift of the measuring object	During impedance measurement	VOLTAGE DRIFT
Over-voltage input error	When voltage is measured	OVER VOLTAGE
Voltage limit error	When voltage is measured	OVER V LIMIT
Return cable unconnected error	After impedance measurement	RETURN CABLE ERROR

Detection timing	Refer to "8.2 Timing Chart" (p. 86)
Measurement error display	Refer to "Error display and remedy" (p. 135)

Comparator

Comparator				
Function overview	Comparison functions of me	easuremer	t and reference values	
Function setting	ON/OFF (Setting each mea	surement	parameter)	
Adaptive measurement				
Setting the range for upper and lower limit values	θ : -180.000° to 180. R: -3.0000 mΩ to 120. X: -120.0000 mΩ to 120.	0000 mΩ 000° 0000 mΩ 0000 mΩ		
Buzzer mode	OFF/Hi • Lo/IN/ALL			
Buzzer operation	OFF		No buzzer sound	
	Hi • Lo		Short buzzer sound (three times)	
	IN		Long buzzer sound	
	ALL		In the case of Hi • Lo:	Short buzzer sound (three times)
	lute value ON/OFF		In the case of IN	Long buzzer sound
V absolute value judgment				
Judgment result	Hi/IN/Lo (impedance and vo	oltage are	ndependently judged)	
PASS/FAIL judgment	AND-operates the results of impedance outputs PASS/FAIL (EXT.I/O output)		ce judgment and voltage ju	dgment, and then

Judgment operation

Measurement Result	Judgment	Output of EXT. I/O					
Measurement Result	result	Hi	IN	Lo	ERR	PASS	FAIL
Hi Set value < Measured value	Hi	ON	OFF	OFF	OFF	OFF	ON
Lo Set value ≤ Measured value ≤ Hi Set value	IN	OFF	ON	OFF	OFF	ON	OFF
Measured value < Lo Set value	Lo	OFF	OFF	ON	OFF	OFF	ON
OverRange	Hi	ON	OFF	OFF	OFF	OFF	ON
Measurement Error	Will not judge	OFF	OFF	OFF	ON	OFF	OFF
During interruption of measurement	Will not judge	OFF	OFF	OFF	OFF	OFF	OFF

Setting backup Yes

Zero adjustment

Zero aujustilient			
Function overview	Removing the resid	ual components caused from offset and the measurement environment.	
Adaptive measurement	Impedance measurement, voltage measurement		
Function setting	ON/OFF		
Adjustment mode	SPOT/ALL		
	SPOT: Zero adjustments are performed for the frequency and voltage measurements within the range that is currently set.		
	ALL: Zero adjustment is prange that is current	performed for all the frequencies and voltage measurements within the tly set.	
Zero adjustment range	R	-0.1000 m Ω to 0.1000 m Ω (3 m Ω range) -1.5000 m Ω to 1.5000 m Ω (3 m Ω range, BT4560-60) -0.3000 m Ω to 0.3000 m Ω (10 m Ω range) -3.0000 m Ω to 3.0000 m Ω (10 m Ω range, BT4560-60) -3.000 m Ω to 3.000 m Ω (100 m Ω range)	
	X	-1.5000 m Ω to 1.5000 m Ω (Common for all ranges)	
	V	-0.10000 V to 0.10000 V	
	(BT4560-60)		
	Measurement Frequency	Reactance zero-adjust error is not judged for frequencies between 1.06 kHz and 10.00 kHz.	
	Measurement Abnormality Detection	Return cable disconnection error is not judged for frequencies above 1.06 kHz.	
Setting backup	Yes		

Self-Calibration

Function overview	Calibration of the voltmeter is performed using internal circuitry.
Function setting	AUTO/MANUAL

Execution timing AUTO		Always performed every voltage measurements.
	MANUAL	Executed with EXT.I/O or command. (Executed in the TRIG waiting state. The EXT. I/O or command will be executed after the completion of measurement if a signal is received when the measurement is in progress.)
Self-Calibration time	210 ms	
Setting backup	Yes	

Sample delay

Function overview	When the impedance measurement is performed, sets the number of waves to wait from applying AC to sampling start. (p. 40)	
Function setting	WAVE/Δ' WAVE: ΔVOLT:	VOLT Sampling is performed only for the set wavenumbers after the application of measurement signal. Set with 0 wave to 9 wave (Resolution 0.1 wave, default value: 1 wave) Sampling is performed after the deviation of the measurement signal slope drops below the set voltage. Setting with 0.001 mV to 10.000 mV
Setting backup	Yes	

Average (Only for impedance measurement)

	•
Function overview	Averaging specified times of impedance measurement values and then output.
Function setting	1 to 99 times
Averaging method	Simple average
	$R_{\text{avg}(n)} = \frac{1}{A} \sum_{k=(n-1)A+1}^{nA} R_k$
Setting backup	Yes

Slope correction of impedance measurements

Function overview	Compensating the slope of AC signal when the impedance measurement is performed. (p. 45)
Function setting	ON/OFF
Setting backup	Yes

Voltage limit

Function overview	Setting the upper limit value of the battery voltage that the impedance measurement is performed. When the battery voltage is higher than the set voltage, impedance measurement will not be performed. (p. 47)
Function setting	ON/OFF
Setting range	0.01 V to 5.00 V (Default setting: 4.20 setting based on absolute value)
Setting backup	Yes

Preventing charge and/or discharge when AC is applied

	•
Function overview	Prevents charging to and/or discharging from the battery by terminating the measurement AC signal at zero cross.
Function settings	ON/OFF
Accuracy	±80 μs



Interface setting

Function overview	Setting the communication interface.	
Function setting		RS-232C/USB/LAN (Manual selection)
	Transmission speed setting	9,600 bps/19,200 bps/38,400 bps
	(Transmission delimiter is fixe	d with CR+LF.)
Setting backup	Yes	

Display setting

Function overview	Adjusting the contrast of display and the backlight.
Auto-off	The brightness is reduced to 10% if a non-operational state continues for one minute in the case of an external trigger. The brightness can be returned to the previous status by the key operation on the front panel.
Contrast	0% to 100% (by 5%, initial value: 50%)
Brightness adjustment	10% to 100% (by 5%, initial value: 80%)
Setting backup	Yes

EXT.I/O setting

Function overview	Setting the output of EXT.I/O in the sink or the source.	
EXT.I/O setting	PNP/NPN	
Setting method	Switching with the rear switch	

Key-lock

Function overview	Disabling the key operations excluding trigger.
Function setting	ON/OFF (When ON is set, disables the key operations excluding trigger.)
Release method	Press and hold the LOCAL key for five seconds or more
Setting backup	No

Key operation buzzer

Function overview	When the key is operated, the buzzer is beeped.
Function setting	ON/OFF (When ON is set, the buzzer is beeped.)
Setting backup	Yes

Reset

Function overview	Cancels the settings	
Function operation	System reset	Initializing the settings to the factory default excluding communication setting.
	Normally reset	Initializing the settings to the factory default excluding the communication setting, zero adjustment values, and panel saving data.

Information

Function overview	Indicating the system information.
Indicating information Serial number, software version	

System test

Function overview	Shipping inspection and EXT.	I/O operation check.
Testing item	Key test, LCD test, ROM test, EXT.I/O test	
Function operation	Key test	Checks if the keys are operating correctly.
	LCD test	Checking the ON/OFF operation of LCD.
	ROM test	Checking that the contents of ROM are normal.
	EXT.I/O test	Check that the output signal is output normally from the EXT.I/O, and the input signal is read normally.
	Communication monitor	The command and the response for the query is displayed on the screen.

Error display

"Error display and remedy" (p. 135)

10.3 User Interface

Display

Monochrome graphic	LCD 240 × 110
Screen size	94 W × 55 H mm (View area)
Backlight	White LED
	Brightness adjustment range: 10% to 100% (in 5% steps)
Contrast	Adjustment range: 0% to 100% (in 5% steps)

10.4 External Interface

Communication Interface

Interface types	RS-232C / USB / LAN
	When communicating via RS-232C / USB / LAN, operations from the front panel are disabled in remote mode.
	Release Methods
	Operate using the LOCAL key
	Restart the power
	Use the SYSTem: LOCal command via USB / RS-232C / LAN

RS-232C

Communication contents	Remote control, measured value output
Transmission method	Start-stop synchronization system, full duplex
Transmission speed	9,600 bps/19,200 bps/38,400 bps
Data bit length	8 bit
Stop bit	1
Parity bit	None
Terminator	Sending: CR+LF Receiving: CR, CR+LF
Delimiter	Sending: CR+LF Receiving: CR, CR+LF
Handshake	X flow: Not provided, Hardware flow: Not provided
Protocol	Non-procedure system
Connector	D-sub9 pin, male, mating fixed base screw #4-40

USB

Communication	Remote control, measured value output
contents	

Electrical specifications	USB2.0 (pseudo COM port)	
Class	CDC class	
Connector	Series B receptacle	

LAN

Settings can be changed by accessing the instrument using a web browser.

Applicable standard	IEEE802.3			
Transmission method	10BASE-T/100BASE-TX automatic recognition Half/Full Duplex, Auto MDI-X			
Protocol	TCP/IP			
Connector	RJ-45			
Communication description	Setting and measure	ed value acquisition by using com	munications comma	ands
Settings	IP address:	XXX.XXX.XXXX *1	Default value	192.168.1.1
	Subnet mask:	XXX.XXX.XXXX *1	Default value	255.255.0.0
	Default gateway:	XXX.XXX.XXXX * ¹	Default value	OFF(0.0.0.0)
	Communications command port:	11 to 65535(Excluding 80)	Default value	23

^{*1.} xxx represents a numeral of 0 to 255.

EXT.I/O

Input signal

Input signal	• START (TRIG)	• STOP	• 0ADJ_SPOT
	• 0ADJ_ALL	• LOAD0 to LOAD6	• CAL
Photo-coupler insulation	Non-voltage contact inputs (corresponding to current sink/source output)		
Input ON	Residual voltage 1 V (Input ON Current 4 mA (reference value))		
Input OFF	OPEN (Breaking current less than 100 μA)		

Output signal

Output signal	• INDEX	• EOM	• ERR	• PASS	• FAIL
	• RorZ_HI	• RorZ_IN	• RorZ_LO	• Xor θ _HI	• Xorθ_IN
	• Xor θ _LO	• V_HI	• V_IN	• V_LO	
Photo-coupler insulation	Open drain outp	ut (non-polarity)			
Maximum load voltage	30 V max DC current 10 mA)	Residual voltage le	ess than 1 V (Load	current 50 mA)/less	s than 0.5 V (Load
Maximum output current	50 mA max /ch				

Service power supply output

Output voltage	Corresponding to sink output	5.0 V±10%, 100 mA max	
	Corresponding to source output	-5.0 V±10%, 100 mA max	
Insulation	Floating from the protective grounding potential and the measurement circuit.		
Insulation rating	Voltage to ground 50 V DC, 30 V AC rms, 42.4 V peak AC or less		

Structure

Connector	D-sub37Pin, Female, mating fixed base screw #4-40 Screw
Pin layout	"8.1 External Input/output Terminals and Signals" (p. 82)

10.5 Accuracy

Guaranteed accuracy conditions

Temperature and humidity range	23°C±5°C (73°F±9°F), less than 80% RH (no condensation)
Zero adjustment	After performing the zero adjustment
Measurement status	Measuring under the same conditions (probe shape, layout, measurement environment) as the zero adjustment. Unchanging of the probe's shape during the measurement.
Warm-up time	At least 60 minutes
Self-Calibration	Performing the self-calibration after warm-up. Maintaining the fluctuation of environment temperature after the self-calibration within ±2°C.

Impedance measurement accuracy

BT4560-50

+ 3 m Ω range (0.01 Hz to 100 Hz), 10 m Ω range, and 100 m Ω range

R accuracy= $\pm \left(0.004|R| + 0.0017|X|\right) \left[\text{m}\Omega\right] \pm \alpha$

X accuracy= $\pm (0.004|X|+0.0017|R|) \lceil m\Omega \rceil \pm \alpha$

(The units of R and X are [m Ω], α is as shown in the table below.)

Z accuracy= $\pm 0.4\%$ rdg. $\pm \alpha (|\sin \theta| + |\cos \theta|)$

 θ accuracy= $\pm 0.1^{\circ} \pm (57.3\alpha/Z) \times (|\sin \theta| + |\cos \theta|)$

(α is as shown in the table below.)

• 3 m Ω range (110 Hz to 1050 Hz)

R accuracy= $\pm \left(0.004 \left| R \right| + 0.0052 \left| X \right| \right) \left[\text{m}\Omega \right] \pm \alpha$

X accuracy= $\pm (0.004|X|+0.0052|R|)[\text{m}\Omega]\pm \alpha$

(The units of R and X are [m Ω], α is as shown in the table below.)

Z accuracy= $\pm 0.4\%$ rdg. $\pm \alpha \left(\left| \sin \theta \right| + \left| \cos \theta \right| \right)$

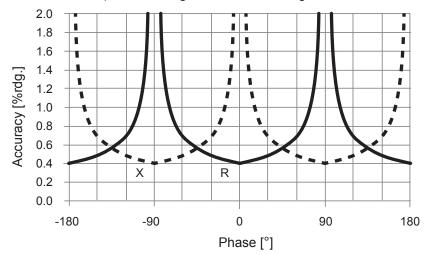
 θ accuracy= $\pm 0.3^{\circ} \pm (57.3 \alpha / Z) \times (|\sin \theta| + |\cos \theta|)$

(lpha is as shown in the table below.)

		3 mΩ range	10 mΩ range	100 mΩ range
	FAST	25 dgt.	60 dgt.	60 dgt.
α	MED	15 dgt.	30 dgt.	30 dgt.
	SLOW	8 dgt.	15 dgt.	15 dgt.

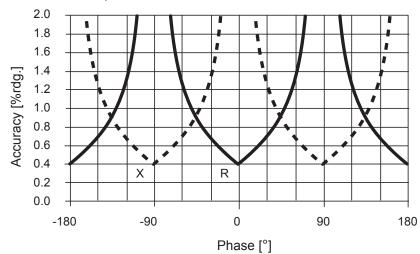
Accuracy graph

• 3 m Ω range (0.01 Hz to 100 Hz), 10 m Ω range, and 100 m Ω range



Impedance accuracy excluding α (0.004|R| + 0.0017|X|, 0.004|X| + 0.0017|R|)

• 3 m Ω range (110 Hz to 1050 Hz)



Impedance accuracy excluding α (0.004|R| +0.0052|X|, 0.004|X| +0.0052|R|)

```
BT4560-60

 3 mΩ range

(0.01 Hz to 100 Hz)
  Z accuracy= \pm 0.4\% reading \pm \alpha (|\sin\theta| + |\cos\theta|)
  \theta accuracy= \pm 0.1^{\circ} \pm 57.3\alpha / Z ( |\sin\theta| + |\cos\theta| )
  R accuracy= \pm ( 0.004|R| + 0.0017|X| ) \pm \alpha [ m\Omega ]
  X accuracy= \pm ( 0.004|X| + 0.0017|R| ) \pm \alpha [ m\Omega ]
(110 Hz to 1.05 kHz)
  Z accuracy= \pm 0.4\% reading \pm \alpha (|\sin\theta| + |\cos\theta|)
  \theta accuracy= \pm 0.3^{\circ} \pm 57.3\alpha / Z ( |\sin\theta| + |\cos\theta| )
  R accuracy= \pm ( 0.004|R| + 0.0052|X| ) \pm \alpha [ m\Omega ]
  X accuracy= \pm ( 0.004|X| + 0.0052|R| ) \pm \alpha [ m\Omega ]
(1.06 \text{ kHz to } 5.00 \text{ kHz}, Z > 1 \text{ m}\Omega)
  Z accuracy= \pm 4\% reading \pm \alpha ( |\sin\theta| + |\cos\theta| )
  \theta accuracy= \pm 15^{\circ} \pm 57.3\alpha / Z (|\sin\theta| + |\cos\theta|)
  R accuracy= \pm ( 0.040|R| + 0.262|X| ) \pm \alpha [ m\Omega ]
  X accuracy= \pm ( 0.040|X| + 0.262|R| ) \pm \alpha [ m\Omega ]
(5.01 \text{ kHz to } 10.00 \text{ kHz}, Z > 1 \text{ m}\Omega)
  Z accuracy= \pm 10\% reading \pm \alpha ( |\sin\theta| + |\cos\theta| )
  \theta accuracy= \pm 25^{\circ} \pm 57.3\alpha / Z ( |\sin\theta| + |\cos\theta| )
  R accuracy= \pm ( 0.100|R| + 0.436|X| ) \pm \alpha [ m\Omega ]
  X accuracy= \pm ( 0.100|X| + 0.436|R| ) \pm \alpha [ m\Omega ]
• 10 m\Omega range
(0.01 Hz to 1.05 kHz)
  Z accuracy= \pm 0.4\% reading \pm \alpha (|\sin\theta| + |\cos\theta|)
  \theta accuracy= \pm 0.1^{\circ} \pm 57.3\alpha / Z ( |\sin \theta| + |\cos \theta| )
  R accuracy= \pm ( 0.004|R| + 0.0017|X| ) \pm \alpha [ m\Omega ]
  X accuracy= \pm ( 0.004|X| + 0.0017|R| ) \pm \alpha [ m\Omega ]
(1.06 \text{ kHz to } 5.00 \text{ kHz}, Z > 1 \text{ m}\Omega)
  Z accuracy= \pm 4\% reading \pm \alpha (|\sin\theta| + |\cos\theta|)
  \theta accuracy= \pm 15^{\circ} \pm 57.3\alpha / Z (|\sin\theta| + |\cos\theta|)
  R accuracy= \pm ( 0.040|R| + 0.262|X| ) \pm \alpha [ m\Omega ]
  X = \pm (0.040|X| + 0.262|R|) \pm \alpha [m\Omega]
(5.01 \text{ kHz to } 10.00 \text{ kHz}, Z > 1 \text{ m}\Omega)
  Z accuracy= \pm 10\% reading \pm \alpha ( |\sin\theta| + |\cos\theta| )
  \theta accuracy= \pm 25^{\circ} \pm 57.3\alpha / Z (|\sin\theta| + |\cos\theta|)
  R accuracy= \pm ( 0.100|R| + 0.436|X| ) \pm \alpha [ m\Omega ]
  X accuracy= \pm ( 0.100|X| + 0.436|R| ) \pm \alpha [ m\Omega ]
• 100 m\Omega range
(0.01 Hz to 1.05 kHz)
  Z accuracy= \pm 0.4\% reading \pm \alpha (|\sin\theta| + |\cos\theta|)
  \theta accuracy= \pm 0.1^{\circ} \pm 57.3\alpha / Z ( |\sin\theta| + |\cos\theta| )
  R accuracy= \pm ( 0.004|R| + 0.0017|X| ) \pm \alpha [ m\Omega ]
```

X accuracy= \pm (0.004|X| + 0.0017|R|) \pm α [$m\Omega$]

(1.06 kHz to 5.00 kHz, Z > 10 m Ω)

Z accuracy= $\pm 4\%$ reading $\pm \alpha$ ($|\sin\theta| + |\cos\theta|$)

 θ accuracy= $\pm 15^{\circ} \pm 57.3\alpha$ / Z ($|\sin\theta| + |\cos\theta|$)

R accuracy= \pm (0.040|R| + 0.262|X|) \pm α [m Ω]

X accuracy= ± (0.040|X| + 0.262|R|) ± α [$m\Omega$]

(5.01 kHz to 10.00 kHz, Z > 10 m Ω)

Z accuracy= $\pm 10\%$ reading $\pm \alpha$ ($|\sin\theta| + |\cos\theta|$)

 θ accuracy= $\pm 25^{\circ} \pm 57.3\alpha$ / Z ($|\sin\theta| + |\cos\theta|$)

R accuracy= \pm (0.100|R| + 0.436|X|) \pm α [m Ω]

X accuracy= \pm (0.100|X| + 0.436|R|) \pm α [m Ω]

Measurement of α

Frequency	Measurement Speed	3 mΩ range	10 mΩ range	100 mΩ range
	FAST	25 digit	60 digit	60 digit
0.01 Hz to 1.05 kHz	MEDIUM	15 digit	30 digit	30 digit
	SLOW	8 digit	15 digit	15 digit
	FAST			
1.06 kHz to 10.00 kHz	MEDIUM	40 digit	90 digit	90 digit
	SLOW			

Common to both BT4560-50 and BT4560-60

	R: ± R accuracy×0.1 / °C
	X: ± X accuracy×0.1 / °C
Temperature coefficient	Z: ± Z accuracy×0.1 / °C
	θ: ±θ accuracy×0.1 / °C
	Applied in the range (0°C to 18°C, 28°C to 40°C)

Voltage measurement accuracy

Voltage measurement

V	Display range	-5.10000 V to 5.10000 V	
V	Resolution	10 μV	
	FAST	±0.0035% rdg.±5 dgt.	
Voltage accuracy	MED	±0.0035% rdg.±5 dgt.	
	SLOW	±0.0035% rdg.±5 dgt.	
Temperature coefficient	±0.0005% rdg.±1 dgt./°C (Applied in the ranges of 0°C to 18°C, and 28°C to 40°C		

Temperature measurement accuracy

Temperature measurement (BT4560 only)	±0.1°C Temperature coefficient: ±0.01°C/°C (applied to the range of 0°C to 18°C, 28°C to 40°C)
Temperature measurement (BT4560+Z2005)	±0.5°C (Measured temperature: 10.0°C to 40.0°C) ±1.0°C (Measured temperature: -10.0°C to 9.9°C, 40.1°C to 60.0°C)

Combination Influence Using SW9002

Range	0.01 Hz to 100 Hz	110 Hz to 1050 Hz	1060 Hz to 10.00 kHz	Conditions /Remarks
3 mΩ Range	R: ±0.05%f.s. X: ±0.1%f.s.	R: ±0.1%f.s. X: ±1.0%f.s.		
10 mΩ Range	R: ±0.015%f.s. X: ±0.03%f.s.	R: ±0.03%f.s. X: ±0.3%f.s.	(Measurement accuracy of this device) ×1	1060 Hz to 10.00 kHz: Applicable to BT4560-60
100 mΩ Range	R: ±0.01%f.s. X: ±0.015%f.s.	R: ±0.01%f.s. X: ±0.03%f.s.		
V all ranges		±5 μV	After temperature stabilization in the operating environment. Within 1 minute after contact closure.	

Example of accuracy calculation

(Rounded down to the displayed digit)

1 Impedance measurement accuracy

<Measurement condition 1>

Measurement range: 3 m Ω range, Measurement speed: SLOW, Frequency: 0.01 to 100 Hz, Measuring object: R=1 m Ω , X=-0.5 m Ω

R accuracy

- $\pm (0.004 \times |1 \text{ m}\Omega| + 0.0017 \times |-0.5 \text{ m}\Omega|) \pm 8 \text{ dgt.}$
- = $\pm (0.004 \times |1 \text{ m}\Omega| + 0.0017 \times |-0.5 \text{ m}\Omega|) \pm 0.0008 \text{ m}\Omega$
- = $\pm 0.00565 \text{ m}\Omega$ (Rounded down to the displayed digit $\pm 0.0056 \text{ m}\Omega$)

X accuracy

 $\pm (0.004 \times |-0.5 \text{ m}\Omega| + 0.0017 \times |1 \text{ m}\Omega|) \pm 8 \text{ dgt.}$

- $= \pm (0.004 \times [-0.5 \text{ m}\Omega] + 0.0017 \times [1 \text{ m}\Omega]) \pm 0.0008 \text{ m}\Omega$
- = $\pm 0.00450 \text{ m}\Omega$ (Rounded down to the displayed digit $\pm 0.0045 \text{ m}\Omega$)

<Measurement condition 2>

Measurement range: 100 m Ω range, Measurement speed: FAST, Frequency: 0.01 to 1050 Hz, Measuring object: Z=60 m Ω . θ=-20°

Z accuracy

```
\pm 0.4\% rdg. × 60 m\Omega \pm 60 dgt. × {|cos (-20°) |+|sin (-20°) |}
```

- $= \pm 0.240 \text{ m}\Omega \pm 0.060 \text{ m}\Omega \times (|0.940|+|-0.342|)$
- = $\pm 0.3169 \text{ m}\Omega$ (Rounded down to the displayed digit $\pm 0.316 \text{ m}\Omega$)

θ accuracy

```
\pm 0.1^{\circ} \pm 57.3^{\circ} \times 60 \text{ dgt.} \div 60 \text{ m}\Omega \times \{|\cos (-20^{\circ})| + |\sin (-20^{\circ})|\}
```

- $= \pm 0.1^{\circ} \pm 57.3^{\circ} \times 0.060 \text{ m}\Omega \div 60 \text{ m}\Omega \times (|0.940|+|-0.342|)$
- = ±0.1734° (Rounded down to the displayed digit ±0.173°)

<Measurement condition 3>

Measurement range: 3 m Ω range, Measurement speed: SLOW, Frequency: 0.01 to 100 Hz, Measuring object: R=1 m Ω , X=-0.5 m Ω , Instrument's ambient temperature: 15°C

R accuracy

```
\pm (0.004 \times |1 \text{ m}\Omega| + 0.0017 \times |-0.5 \text{ m}\Omega|) \pm 8 \text{ dgt.}
```

- $+\{\pm (0.004 \times |1 \text{ m}\Omega|+0.0017 \times |-0.5 \text{ m}\Omega|) \pm 8 \text{ dgt.}\} \times 0.1/^{\circ}\text{C} \times (|18^{\circ}\text{C} 15^{\circ}\text{C}|)$
- = $\pm 0.00565 \text{ m}\Omega + (\pm 0.00565 \text{ m}\Omega) \times 0.1/^{\circ}\text{C} \times 3^{\circ}\text{C}$
- = $\pm 0.00735 \text{ m}\Omega$ (Rounded down to the displayed digit $\pm 0.0073 \text{ m}\Omega$)

X accuracy

```
\pm (0.004 \times |-0.5 \text{ m}\Omega| + 0.0017 \times |1 \text{ m}\Omega|) \text{ m}\Omega \pm 8 \text{ dgt}.
```

- $+ \{\pm (0.004 \times | -0.5 \text{ m}\Omega | + 0.0017 \times | 1 \text{ m}\Omega |) \text{ m}\Omega \pm 8 \text{ dgt.}\} \times 0.1/^{\circ}\text{C} \times (|18^{\circ}\text{C} 15^{\circ}\text{C}|)$
- = $\pm 0.0045 \text{ m}\Omega + (\pm 0.0045 \text{ m}\Omega) \times 0.1/^{\circ}\text{C} \times 3^{\circ}\text{C}$
- = $\pm 0.00585 \text{ m}\Omega$ (Rounded down to the displayed digit $\pm 0.0058 \text{ m}\Omega$)

2 Voltage measurement accuracy

<Measurement condition 1>

Measurement range: arbitrary, Measurement speed: arbitrary, Frequency: arbitrary, Measuring object: R=arbitrary, X=arbitrary, V=3.6 V

V accuracy

±0.0035% rdg. × 3.6 V ±5 dgt.

- = ±0.000126 V ±0.00005 V
- = ±0.000176 V (Rounded down to the displayed digit ±0.00017 V)

<Measurement condition 2>

Measurement range: arbitrary, Measurement speed: arbitrary, Frequency: arbitrary, Measuring object: R=arbitrary, X=arbitrary, V=3.6 V, Instrument's ambient temperature: 15°C

V accuracy

```
\pm 0.0035\% rdg. \times 3.6 V \pm 5 dgt. + (\pm 0.0005\% rdg./°C \times 3.6 V \pm 1 dgt./°C) \times (|18^{\circ}\text{C} - 15^{\circ}\text{C}|)
```

- $= \pm 0.000176 \text{ V} + (\pm 0.000018 \text{ V/°C} \pm 0.00001 \text{ V/°C}) \times 3^{\circ}\text{C}$
- = $\pm 0.000260 \text{ V}$ (Rounded down to the displayed digit $\pm 0.00026 \text{ V}$)

3 Temperature measurement accuracy

<Measurement condition 1>

Combination of this instrument and Z2005, Measured temperature: T=35°C, Instrument's ambient temperature: 0°C

T accuracy

```
±0.5°C ±0.01°C/°C × ( |18°C - 0°C|)
```

= ± 0.68 °C (Rounded down to the displayed digit ± 0.6 °C)

10.6 General Specifications

Operating temperature and humidity	0°C to 40°C (32°F to 104°F), 80% RH or less (no condensation)			
Storage temperature and humidity	-10°C to 50°C (14°F to 122°F), 80% RH or less (no condensation)			
Accuracy guarantee for temperature and humidity range	23°C±5°C (73.4°F±9°F), 80% RH or less (no cond	lensation)		
Guaranteed accuracy period	1 year			
Product warranty period	3 years			
Operating environment	Indoors, Pollution degree 2, altitude up to 2000 m ((6562 ft.)		
Rated supply voltage	100 V AC to 240 V AC (Considers ±10% voltage fluctuation against rated supply voltage) Anticipated transient overvoltage 2500 V			
Rated supply frequency	50 Hz/60 Hz			
Maximum rated power	80 VA			
Normal power consumption (reference value)	$37~W$ Conditions: Supply voltage 264 V/60 Hz, $3~m\Omega$ range (measurement current 1.5 A rms), frequency 1050 Hz			
Maximum input voltage	±5 V (Between H terminal and L terminal)			
Maximum voltage to ground	±5 V DC (Between H terminal and chassis) 0 V DC (Between L terminal and chassis) (The L terminal is virtually grounded in the internal must not be input.)	circuit. Thus, the voltage to ground		
Open-circuit terminal voltage	50 mV or less (When not measured) 15 V or less (When measured)			
Dielectric strength	Between power supply terminal lump and protective ground	1.62 kV AC, Cut-off current 10 mA for 1 minute		
Dimensions	Approx. 330 W × 80 H × 293 D mm (13.0"W × 3.1"H × 11.5"D) (excluding projections)			
Weight	Approx. 3.8 kg (134.0 oz.)			

Standards

Safety	EN61010	
EMC	EN61326 Class A	
	Effect of radiated radio-frequency electromagnetic field	For a frequency range of 80 MHz to 1 GHz, the accuracy is specified in an electromagnetic field of 10 V/m. For a frequency range of 1 GHz to 6 GHz, the accuracy is specified in an electromagnetic field of 3 V/m. Impedance measurement ±5%f.s. Voltage measurement ±2%f.s.
	Effect of conducted radio-frequency electromagnetic field	At 10 V, Impedance measurement ±2%f.s.
	Effect of external magnetic field	In a magnetic field of 400 A/m, 50/60 Hz Impedance measurement ±6%f.s.

Accessories		• • • • • • • •	 • • • • • • • •	• • • • • • • •	 • • • • • •
Refer to p. 1.					
Options	• • • • • • • • •				
Refer to p. 2.					

Maintenance and Service

11.1 Troubleshooting

- If damage is suspected, check the "Troubleshooting" section before contacting your authorized Hioki distributor or reseller.
- When sending the instrument for repair, pack carefully to prevent damage in transit. Include cushioning material so the instrument cannot move within the package. Be sure to include details of the problem. Hioki cannot be responsible for damage that occurs during shipment.
- The fuse is housed in the power unit of the instrument. If the power does not turn on, the fuse may be blown. If this occurs, a replacement or repair cannot be performed by customers. Please contact your authorized Hioki distributor or reseller.

Q&A (Frequent inquiries)

General items

No.	Trouble	Confirm		Possible causes → Solution	Ref.
			OFF	Power is not supplied. → Turn ON the main power switch (rear).	p. 21
				Power is not supplied. → Check the conduction of power cables. → Check if the breaker for the equipment is turned ON.	p. 21
1-1	Power is still OFF (nothing is displayed).	Main power switch (rear)	ON	Power voltage and/or frequency are different. → Check the power rating. (100 V to 240 V, 50/60 Hz)	-
				The screen is dark. → Adjust the backlight brightness and contrast. → External trigger setting automatically reduces the backlight brightness if a non-operation state continues for 1 minute.	p. 68
1.2	Keys cannot be operated.	Dienlay	[LOCK] is dis- played.	The key is locked. → Release the keylock.	p. 65
1-2		rated.	[RMT] is dis- played.	The instrument is in remote state. → Release the remote state.	p. 108
			are dis- played.	Comparator function is OFF. → Turn the function ON.	p. 52
1-3	Judgment results are not displayed.	Measurement values	are not dis- played. (Non- values are dis- played)	When measurement values are not displayed, judgment is not done and the indicator is not displayed.	-
1-4	Buzzer cannot be	Key operation tone is set to	OFF	Key operation tone is set to OFF. → Turn the function ON.	p. 67
1-4	heard.	Judgment tone is set to	OFF	Judgment tone is set to OFF. → Turn the function ON.	p. 57

No.	Trouble	Confirm	Possible causes → Solution	Ref.
1-5	Adjusting buzzer volume	The buzzer volume cannot be	e adjusted for this instrument.	-

Concerning measurement items

No.	Trouble	Confirm		$\textbf{Possible causes} \rightarrow \textbf{Solution}$	Ref.
	The measurement values have		ON	Zero adjustment is not correct. → Adjust zero adjustment again by setting the wiring shape of the probe to a shape closer to the actual measuring state.	p. 28
2-1	deviated from the expected values.	Zero adjustment	OFF	The impact of the wiring shape has not been removed. → Adjust zero adjustment again by setting the wiring shape of the probe to a shape closer to the actual measuring state.	p. 28
		The shape of the measurement	Varies for each mea- suring object.	The impact of the wiring shape has not been removed. → Adjust zero adjustment again by setting the wiring shape of the probe to a shape closer to the actual measuring state.	p. 28
		probe	The loop of SENSE-H and L is large.	Electromagnetic field affects the measurement values. → Decrease the loop area formed by SENSE-H and SENSE-L wiring.	p. A4
		The measurement probe is	self fab- ricated.	Measurement value changes depending on the measurement position. → Measure after correctly adjusting the probing positions. → Separate the probing positions of SENSE and SOURCE as far as possible. → Use a probe with a point contact (Crown type will result in multi-point contact, which is poor in repeatability.)	p. A4
2-2	Measurement values are not stable.		pro- vided probe	Measurement value changes depending on the measurement position. → Measure after correctly adjusting the probing positions.	_
			Tem- perature is not stable.	Characteristics have changed depending on the temperature. → Measure after the temperature change becomes small.	_
		Measuring object	Heat capacity is small.	The measuring current is causing the measuring object to heat up. → Reduce the range of the measurement current.	-
			Dis- charge capacity is small.	Discharge is caused by DC load current. → Reduce the range of the measurement current.	_
		Temperature sensor	is not inserted all the way in.	Temperature sensor is not correctly connected. → Insert the temperature sensor all the way in.	_

No.	Trouble	Confirm	Possible causes → Solution	Ref.
2-3	Zero adjustment is	Measurement values before zero adjustment is not within the acceptable range.	The impact of the wiring shape is too large. → Reduce the loop area formed by the return cable and the measuring object. → Reduce the loop area formed by SENSE-H and SENSE-L.	-
2-0	not possible.	Measurement error is displayed.	There is a problem with the wiring. → Adjust again with the correct wiring. When the resistance value is high due to self fabricated cables, zero adjustment cannot be performed. Reduce the wiring resistance in such cases.	p. 32

Concerning EXT.I/O items

No.	Trouble	Confirm	Possible causes → Solution	Ref.
3-1	The instrument does not operate at all.	IN and OUT displayed in the EXT.I/O test of the instrument does not match with the controller.	Wiring etc. is incorrect. → Check EXT.I/O again. • Loose connection between connectors • Is the pin number correct? • Wiring of ISO_COM terminals • NPN/PNP settings • Contact (or Open collector) control (Not voltage control) • Power supply to the controller (Power supply to the instrument is not required.)	p. 82
	3-2 TRIG is not applied.	Trigger source is internal trigger (INT).	TRIG signal cannot apply a trigger with internal trigger setting. → Set an external trigger.	p. 39
3-2		ON time of TRIG is less than 0.1 ms.	ON time of TRIG is short. → Ensure that ON time is 0.1 ms or more.	-
		ON time of TRIG is less than 1 ms.	OFF time of TRIG is short. → Ensure that OFF time is 1 ms or more.	-
3-3	Does not LOAD.	Panel has not been saved in the loaded panel number.	Panel that is not saved cannot be loaded. → Change the LOAD signal, or save the panel again so it matches the LOAD signal.	p. 84
3-4	FOM is not output	Measurement values are not updated.	Confirm Q&A in 3-2.	-
3-4	EOM is not output.	EOM signal logic	The EOM signal will be ON once the measurement is completed.	p. 85
3-5	HI, IN, and LO signals are not output.	Judgment results are not displayed on the instrument screen.	Confirm Q&A in 1-3.	p. 131

Concerning communication items

The operation can be checked smoothly by using the communication monitor (p. 74).

No.	Trouble	Con	ıfirm	Possible causes \rightarrow Solution	Ref.
4-1	There is no response at all.	Display	[RMT] is not displayed.	Connection cannot be established. → Check the connector insertions. → Check that the settings of the interfaces are correct. → Do not insert a USB cable when RS-232C is used. → When using the USB, install drivers on control instruments. → Use the cross cable when RS-232C is used. → Check the COM port number of the control instrument. → Match the communication speeds of the instrument and the control instrument.	p. 97
			[RMT] is displayed.	Commands are not accepted. → Check the delimiter of the software.	p. 97
		Display	results in a command error.	Commands do not match. → Check the spelling of the commands (space is x20H.) → Do not add "?" to commands with no query. → Match the communication speeds of the instrument and the control instrument.	-
4-2	Result becomes			Input buffer (256 bytes) overflow. → Ensure waiting until the received character string is processed. Example: Insert a dummy query for sending several lines of commands such as *OPC? Sending → "1" reception.	-
	an error.		results in an execution error.	Not in the state in which execution is possible, though the command character string is correct Example: Spelling mistake in data part : SAMP:RATE SLOW2 → Check each command specification.	1
				Input buffer (256 bytes) overflow. → Ensure waiting until the received character string is processed. Example: Insert a dummy query for sending several lines of commands such as *OPC?Sending → "1" reception.	-
4-3	An answer to the query is not returned.	On the communication monitor	response present.	The program is not correct. → The instrument is returning the query. Check the receiving part of the program.	-

Error display and remedy

When an error is displayed on the LCD screen, repair is necessary. Please contact your authorized Hioki distributor or reseller.

Display	Error No.	Cause	Countermeasures
OverRange	None	The measurement value exceeds the impedance measurement range.	Set the correct range.
+Over°C	None	The measurement value exceeds the temperature measurement range. The measurement voltage range is -10.0°C to 60.0°C.	The measured temperature is too high and cannot be measured by this instrument.
-Under°C	None	The measurement value lowers the temperature measurement range. The measurement voltage range is -10.0°C to 60.0°C.	The measured temperature is too low and cannot be measured by this instrument.
°C	None	The temperature sensor is not connected.	Connect the temperature sensor to the instrument.
	None	The measurement current cannot be applied.	 Check that the probe is in secure contact with the object being measured. Check that the cable is not disconnected and/or the probe is not worn. The measurement range may not be suitable. Select a larger measurement range. When the measurement probe is self-made, some of the wiring resistance may be too high. Make the wire diameter larger and wire length shorter to reduce the wiring resistance. When the measurement probe has a long wire, consider making measurements with the four-terminal method. Contact your authorized Hioki distributor or reseller for four-terminal converters. Check that the measuring object is ungrounded.
RETURN CABLE ERROR	None	The return cable is not connected.	 Connect the return cable. (The return cable connects the shields of SOURCE-H and SOURCE-L.) Check that the wire connection of the probe is correct. If the error does not go off even if the return cable is connected, the instrument may be malfunction. Request repairs.
CONTACT ERROR H	None	It is not properly connected between SOURCE-H and SENSE-H.	 Check that the probe is in secure contact with the object being measured. Check that the cable is not disconnected and/or the probe is not worn.

Display	Error No.	Cause	Countermeasures
CONTACT ERROR L	None	It is not properly connected between SOURCE-H and SENSE-H.	 Check that the probe is in secure contact with the object being measured. Check that the cable is not disconnected and/or the probe is not worn.
OVER VOLTAGE	None	The voltage of the measuring object exceeds the measurable range. The measurable voltage range is -5.10000 V to 5.10000 V.	The voltage of the measuring object is too high and cannot be measured by this instrument.
OVER V LIMIT	None	The voltage of the measuring object exceeds the voltage limit. It may be overcharged by applying the AC voltage. Lower the battery voltage to measure it. (For the setting method of the voltage limit, refer to p. 47).	Discharge the battery to a safety voltage, and then measure it.
DRIFT VOLTAGE	None	The voltage of the measuring object considerably fluctuates during the measurement.	The instrument cannot measure it.
0ADJUST ERROR	ERR:01	The proper zero adjustment is not performed.	Perform the zero adjustment with a proper method so that the zero adjustment data becomes within the full scale of the range. (p. 28)
COMMAND ERROR	ERR:30	The command is not correct.	Check that the command is correct.
EXECUTION ERROR	ERR:31	The parameter part of the command is not correct.	Check that the parameters are proper.
OVERHEAT ERROR	ERR:60	The internal temperature of the instrument increases.	 Check that the power switch of the instrument is turned off. Ensure that there is no clogging in the vent holes.
SUM ERROR	ERR:90	The internal data is corrupt.	The device fails. Request repairs.
CALIB ERROR	ERR:91	The adjustment data is corrupt.	The device fails. Request repairs.
ROM ERROR	ERR:92	The ROM data is corrupt.	The device fails. Request repairs.
A/D ERROR	ERR:93	The A/D converter cannot communicate.	The device fails. Request repairs.
VREF ERROR	ERR:94	The voltage calibration cannot be performed.	The device fails. Request repairs.
FAN STOP ERROR	ERR:95	The fan does not rotate.	The device fails. Request repairs.
OVER CURRENT ERROR	ERR:96	The internal circuit is broken.	The device fails. Request repairs.
VREF B ERROR	ERR:97	The built in battery of the instrument has to be replaced.	Please contact your authorized Hioki distributor or reseller.

11.2 Inspection, Repair and Cleaning

MARNING



Touching any of the high-voltage points inside the instrument is very dangerous. Customers are not allowed to modify, disassemble, or repair the instrument. Doing so may cause fire, electric shock, or injury.

Calibrations

The calibration period varies with the conditions and environment of use. It is recommended to determine a calibration period based on those factors and to have the instrument regularly calibrated by Hioki. Please contact your Hioki distributor to have your instrument periodically calibrated.

Replaceable parts and operating lifetimes

The characteristics of some of the parts used in the product may deteriorate with extended use. To ensure the product can be used over the long term, it is recommended to replace these parts on a periodic basis. When replacing parts, please contact your authorized Hioki distributor or reseller. The service life of parts varies with the operating environment and frequency of use. Parts are not guaranteed to operate throughout the recommended replacement cycle.

Part name	Recommended replacement cycle	Remarks/conditions
Electrolytic capacitors	Approx. 3 years	The circuit board on which the corresponding part is mounted will be replaced.
LCD backlight (Brightness half life)	Approx. 6 years	When the backlight is used for 365 days with using 24 hours/day,
Fan motor	Approx. 7 years	When the backlight is used for 365 days with using 24 hours/day,
Lithium battery	Approx. 10 years	

Precautions during transportation of the instrument

Pack the instrument so that it will not sustain damage during shipping, and include a description of existing damage. We do not take any responsibility for damage incurred during shipping.

Cleaning

- · To clean the instrument, wipe it gently with a soft cloth moistened with water or mild detergent.
- Wipe the LCD gently with a soft, dry cloth.
- Clean the vents periodically to avoid blockage.
 If vents become clogged, the instruments internal cooling is impeded, and damage may result.

IMPORTANT

Never use solvents such as benzene, alcohol, acetone, ether, ketones, thinners or gasoline, as they can deform and discolor the case.

11.3 Discarding the Instrument

The instrument uses the CR2032 Coin-shaped lithium battery. Handle and dispose of the instrument in accordance with local regulations.

Lithium battery removal

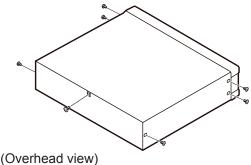
MARNING



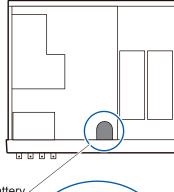
To avoid electric shock, turn off the power switch and disconnect the power cord and measurement cables before removing the lithium battery.

Required tools

- One Philips screwdriver (No.1)
- A pair of tweezers (to remove the lithium battery)



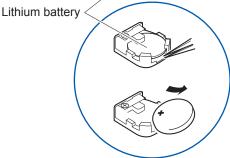
- Verify that the power is off, and remove the connection cables and power cord.
- Remove the six screws from the sides and one screw from the rear.



- Remove the cover.
- Insert the tweezers between the battery and battery holder as shown in the diagram and lift up the battery.

IMPORTANT

Take care not to short the + and -. Doing so may cause sparks.



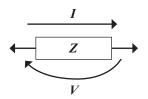
CALIFORNIA, USA ONLY

This product contains a CR Coin Lithium Battery which contains Perchlorate Material - special handling may apply. See https://dtsc.ca.gov/perchlorate/

Appx. 1 Measurement Parameters and Calculation Formula

In general, the impedance ${\it Z}$ is used to evaluate the characteristics of, for example, circuit components.

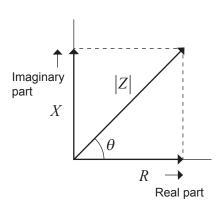
This instrument measures the voltage vectors of the object being measured against measurement current vectors, and then determines the impedance Z and the phase difference θ from these values. From the values of the impedance Z and the phase difference θ , the values of the resistance and the reactance can be calculated using the following formula. These values are illustrated on the complex plane are illustrated in the diagram below.



$$Z = R + jX$$

$$\theta = \tan^{-1} \frac{X}{R}$$

$$|Z| = \sqrt{R^2 + X^2}$$



Z: Impedance (Ω)

 θ : Phase angle (deg)

R: Resistance (Ω)

X: Reactance (Ω)

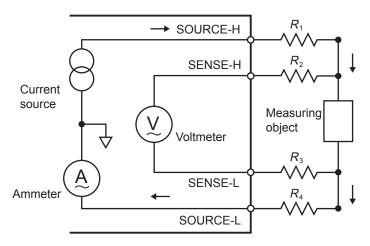
|Z|: Absolute value of impedance (Ω)

Appx. 2 Four-terminal Pair Method

This instrument uses the four-terminal pair method as the measurement method. In addition to the characteristics of the AC four-terminal method, which is unaffected by the contact resistance, this is a more accurate method that is unaffected by the magnetic field caused by the measuring current.

The principles of the AC four-terminal method and the four-terminal pair method are described below.

AC four-terminal method

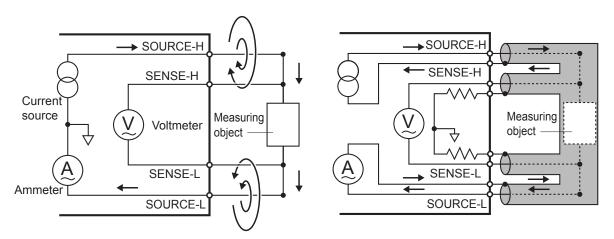


 R_1 to R_4 : Resistances of measurement probes and contact resistances of contact portions

This method is unaffected by the wiring resistance of the measurement probes and the contact resistance between the measurement probe and the object being measured, and is suitable for low resistance measurement. This method uses the measuring current between the SOURCE terminals to measure the voltage of the object being measured at the SENSE terminals.

The current flowing through the voltmeter can be ignored because of the voltmeter's high impedance. The voltage actually generated in the object being measured can thus be measured because the voltage drops due to the resistance of the wiring and the resistance of contact can be ignored even if there is wiring resistance or contact resistance in the portions corresponding to R_2 and R_3 .

Four-terminal pair method



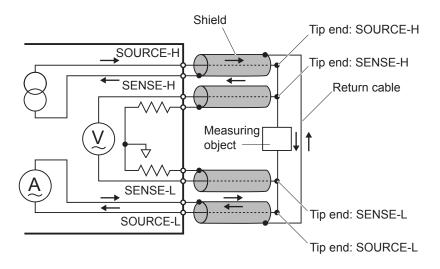
The AC four-terminal method is suitable for a low resistance measurement because it is affected by the resistance of the wiring and the contact resistance. The magnetic field of the measuring current produces an induced electromotive force that affects the SENSE terminals.

In the four-terminal pair method, the current flows backward (current returns) with the same magnitude as the measuring current in the shields of the SOURCE cables, and then cancels the magnetic field of the measuring current. This method suppresses the induced electromotive force induced at the SENSE terminals, and detects the voltage actually generated in the object being measured.

Four-terminal pair method when using the optional probe

When the optional probe L2002 or L2003 of the instrument is used, the four-terminal pair method is structured as described below.

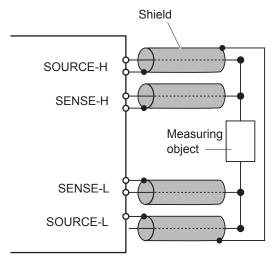
It is necessary that the measuring current and the return current flow in close proximity to each other. This structure enables the return cables to be easily brought close to the object being measured. It is important that the shape of the return cable, which affects the magnetic field, is not changed.



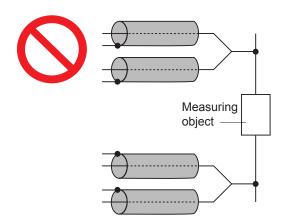
Appx. 3 Cautions When Making Your Own Measurement Probe

Observe the following precautions when making your own measurement probe.

- You must connect the shields of the SOURCE-H and the SOURCE-L. If the shields are not connected, the impedance cannot be measured.
- When the probe is connected to the object being measured, place the SOURCE-H and the SOURCE-L at the outer side and the SENSE-H and the SENSE-L at the inner side in relation to the object being measured. If you do not connect the probes in this fashion, the correct measurement values may not be obtained.
- A coaxial cable is recommended when self fabricating the measurement probe.
- <Recommended coaxial cable specifications>
- Conductor resistance: 150 mΩ/m or less
- Capacitance: 150 pF/m or less (Example: RG58A/U, etc.)

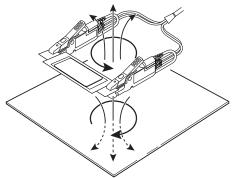


• If you connect the cables together so as to measure the object being measured using the two-terminal connection, you will not be able to obtain the correct measurement values.

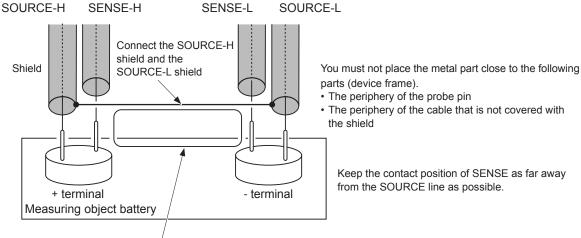


four-terminal pair structure away from metal bodies. An eddy current produced in a metal body may cause a large error in the measurement value. For details, refer to "Influence of the Eddy Current" (p. A8).

· You must not place the measurement probes near a metal body. In particular, move any portion other than the



• For the shape and position of the measurement probe, give attention to the points in the Figure shown below. Eddy currents from adjacent metal bodies or exogenous inductive noise may cause errors and variations in the measurement value and worsen the repetitive accuracy. (The following measures can be used to reduce these effects.)

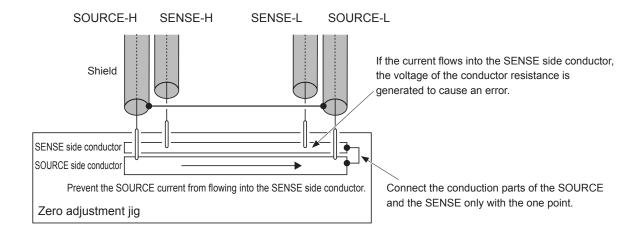


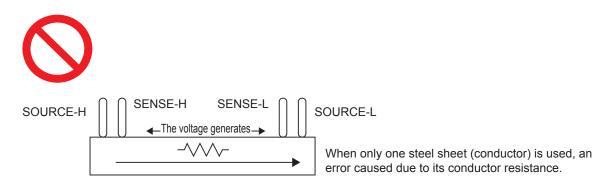
- · Make the loop area between the SOURCE shield and the measurement battery as small as possible.
- Set the loop shape and the wiring position (a distance to the metal part of the surrounding inspection device) in the normal condition.
- The wiring cable should be of minimum length. (less than 4 m) A longer wiring cable is easily affected by exogenous inductive noise. The return wiring resistance and the contact resistance must be less than the allowable values respectively.
- Perform zero adjustment before measurement. Perform zero adjustment using the zero adjustment board that corresponds to the terminal spacing.
- You must not use a metal plate (short bar) as the zero adjustment jig. If a metal plate is used, the correct zero adjustment cannot be performed and then a large error will occur in the measurement. For details, refer to "Zero Adjustment" (p. A8).

Set the following to the same conditions as those when measuring.

- Loop area
- · Loop shape
- · Probe spacing
- Wiring position (distance to the surrounding metal part of a device)

Appx





IMPORTANT

- When making the measurement probe by yourself, you must be careful to not cause the short circuit of any signal wire and the short circuit between the core wire and the shield wire.
- To prevent a short circuit, connect the probe terminal to the instrument and then connect the battery.

Appx. 4 Measurement Probe Structure and Extension

We can fill requests for probe extensions as a special order. Contact the distributor (store) from which you purchased the instrument or your nearest Hioki sales office.

Observe the following precautions when extending the measurement probes by yourself.

- Use a thicker lead wire and a minimum length that you can prepare and implement as the extension.
- Extend the measurement probe with the four-terminal pair structure that is unchanged. In the case of the twoterminal structure, the measurement value may be affected by the resistance of wiring and the contact, and the inductive voltage. In the case of the four-terminal structure, the measurement value may be affected by the inductive voltage.
- In parts other than the four-terminal pair structure, use an extension of as small a length as possible.
- Prepare shapes that are as similar as possible during the zero adjustment and the measurement.
- When extended, the measurement probe will have a greater voltage drop in the lead wire. The resistance of the lead wire, including the resistance of the contact, must be kept within the allowable value.
- Keep the measurement probe away from metal parts. When the measurement probe is placed close to a metal body, the measurement may not be correctly done due to the influence of eddy currents.
- After extending the measurement probe, check the operation and the following:
- 1. By measuring the zero adjustment board, zero-point accuracy appears.
- 2. By measuring the master work (non-defective sample product) and comparing with the management value, the measurement is done properly.

Reduction method of inductive voltage

This instrument is subject to the influence of the inductive voltage because of the measurement of a micro resistance using AC. This inductive voltage means the voltage that is generated by the magnetic induction of the measurement current flowing in the lead wire which may affect the signal system of the measurement. The inductive voltage has a phase difference of 90° from the AC current (reference signal), which can be removed in the synchronous detection circuit theoretically. However, when the inductive voltage is excessive, the signal is distorted, so that the inductive voltage cannot be removed in the synchronous detection circuit.

To reduce the inductive voltage, it is important that the measurement probe is as short as possible. It is very effective to shorten the part where the four-terminal pair is not structured.

Appx. 5 Measurement Value in the Four-terminal Measurement (Difference in Measurement Value Due to the Measurement Probe)

For some measuring objects, different measurement values may be obtained depending on the measurement probes used.

These differences between the measurement values are caused by the shapes of the tip and the dimensions of the four-terminal probes used. Accordingly, each of the different measurement values is correct when the corresponding probe is used.

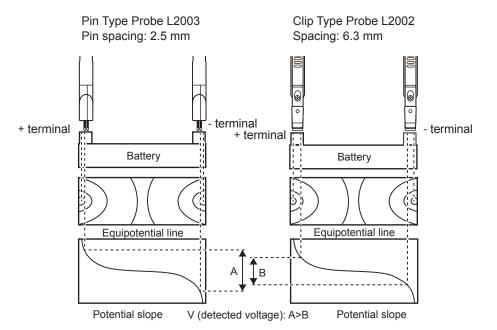
You must use the same measurement probe when comparing the measurement values.

Explanation

The differences between the measurement values depend on the differences between the distances (dimensions) of the pins to which the current is applied, and between the pins that voltage is detected of the measurement probes.

The difference between the measurement values increases as the resistance of the battery terminals increases in comparison to the battery internal resistance.

The figure below shows, as an example, the difference between the detection voltages that are caused by the differences in the space of the probe pins when a large capacity battery was measured.



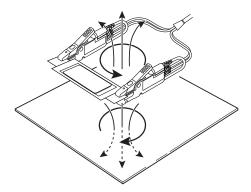
Appx. 6 Influence of the Eddy Current

Measurement close to the metal body causes an eddy current to flow due to the dynamic magnetic field that is generated by the measurement current of the instrument.

This eddy current generates an inductive voltage with a phase opposite to the measurement current in the measurement probe. The inductive voltage generated cannot be removed even in the synchronous detection circuit. Therefore, it may cause a measurement error.

Thus, the measurement instrument using the AC signals needs to take into account the influence of the eddy current

To suppress the influence of the eddy current, you must not bring the measurement probe without a four-terminal pair structure close to a metal body.



Appx. 7 Zero Adjustment

Zero adjustment is a function that compensates for the value remaining when a resistance 0 Ω is measured and then adjusts the zero-point. Thus, zero adjustment must be carried out under conditions where a resistance of 0 Ω is connected. However, It is very difficult and impractical to connect a sample that has a zero resistance value.

Accordingly, zero adjustment is actually carried out to adjust the zero-point by creating conditions where a pseudo resistance of 0 Ω is connected.

To create the conditions where a pseudo resistance of 0 Ω is connected:

When the ideal resistance of 0 Ω is connected, from the relational expression of Ohm's law $E=I\times R$, the voltage between SENSE-H and SENSE-L becomes 0 V. That is, if the voltage between the SENSE-H and the SENSE-L is made to be 0 V, the same conditions as when a resistance of 0 Ω is connected can be created.

When performing zero adjustment with this instrument:

This instrument monitors the condition of the spaces of the four measurement terminals by the measurement fault detection function. Accordingly, zero adjustment needs to be properly connected to each space of the terminals. (Figure. Conditions Where a Pseudo Resistance of 0 Ω is Connected)

First, create a short-circuit between SENSE-H and SENSE-L to cause the voltage between SENSE-H and SENSE-L to be 0 V. If the wiring resistance of the cable being used $R_{\text{SEH}}+R_{\text{SEL}}$ is less than several Ω , the resistance of the wiring can be ignored. The explanation is as follows. The SENSE terminals are the voltage measurement terminals, and thus the current I_0 is ignored. In the relational expression, $E=I_0\times(R_{\text{SEH}}+R_{\text{SEL}})$, $I_0\approx0$. When the resistance of wiring $R_{\text{SEH}}+R_{\text{SEL}}$ is several Ω , the voltage between SENSE-H and SENSE-L becomes almost zero.

Next, connect the spacing between SOURCE-H and SOURCE-L.

This prevents an error display when the measurement current cannot be flown. The wiring resistance of the cable used $R_{\text{SOH}} + R_{\text{SOL}}$ must be less than the resistance value with which the measurement current can flow. In addition, when monitoring the connection condition between SENSE and SOURCE, the spaces between SENSE and SOURCE must be connected. If the wiring resistance of the cable used R_{Short} is approximately several Ω , the cable is acceptable.

The above wiring makes the measurement current *I* that flows out from SOURCE-H flow into SOURCE-L, and thus prevents the measurement current that flows out from SOURCE-H from flowing into the wiring of SENSE-H and SENSE-L. Consequently, the voltage between SENSE-H and SENSE-L can be maintained accurately at 0 V and zero adjustment can be performed.

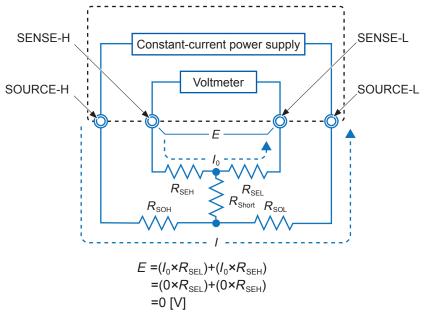


Figure. Conditions where a pseudo 0 Ω is connected

To properly carry out the zero adjustment:

"Table. Connection Method" illustrates the correct connection method and the incorrect connection method. The resistances in the figure show the wiring resistances, and these are ignored if they are less than several Ω respectively.

As shown in (a), when connecting respectively SENSE-H and SENSE-L, and SOURCE-H and SOURCE-L, and then connecting the SENSE and the SOURCE with one path, there is no voltage potential difference produced between SENSE-H and SENSE-L, and thus, a voltage of 0 V is applied. This connection method performs the correct zero adjustment.

However, as illustrated (b), when connecting respectively SENSE-H and SOURCE-H, and SENSE-L and SOURCE-L, and then connecting the Hi-side and the Lo-side with one path, there is a voltage potential difference of $I \times R_{\text{Short}}$ between SENSE-H and SENSE-L. Thus, the connection method does not create conditions where a pseudo resistance of 0 Ω is connected, and thus, does not perform the correct zero adjustment.

Table. Connection method

	Constant-current power supply Voltmeter SOURCE-H SENSE-H SENSE-L SOURCE-L R _{SCH} R _{SCH} R _{SCH} R _{SCH} (a) Connecting the spaces between SENSE and SOURCE with one point respectively	Constant-current power supply Voltmeter SOURCE-H SENSE-H SENSE-L SOURCE-L R _{SOH} R _{SH} R _{Short} (b) Connecting the spaces between the Hiside and the Lo-side respectively.
Resistance between SENSE-H and SENSE-L	R _{SEH} + R _{SEL}	$R_{\text{SEH}} + R_{\text{Short}} + R_{\text{SEL}}$
Path where the measurement current / flows	$R_{SOH}\! o\!R_{SOL}$	$R_{SOH} \! o \! R_{Short} \! o \! R_{SOL}$
Voltage produced between SENSE-H and SENSE-L	0	I × R _{Short}
As the connection method when performing the zero adjustment	Correct	Incorrect

When performing zero adjustment using the zero adjustment board of an accessory:

When performing zero adjustment, you must not use a metal plate in substitution for the attached zero adjustment board. The zero adjustment board is structured to connect between the SENSE terminals and the SOURCE terminals with one point. When performing zero adjustment of the optional L2002 Clip Type Probe and the L2003 Pin Type Probe, the zero adjustment board is used.

The equivalent circuits when connecting to the zero adjustment board and to a metal plate are shown in Table. Connection method when performing zero adjustment. When connecting using the zero adjustment board, the connection is the same as shown in the Connection Method table (a). Thus, the voltage between SENSE-H and SENSE-L becomes 0 V. However, when connected using metal, the connection is the same as shown in the Connection Method table (b). The voltage between SENSE-H and SENSE-L is thus not 0 V.

(a) (b) L2002 L2002 Zero adjustment board Metallic plate 100 100 ⑱ Connection method L2003 L2003 Zero adjustment board Metallic plate 100 100 SENSE-H SENSE-L SENSE-H SENSE-L SOURCE-H SOURCE-L SOURCE-H SOURCE-L Equivalent circuit R_{SEH} R_{SEL} Constant-current power supply Constant-current power supply Voltmeter Voltmeter SENSE-I SOURCE-H SENSE-H SOURCE-H SENSE-H SENSE-L SOURCE-L Detailed equivalent circuit As the connection method when Correct Incorrect performing the zero

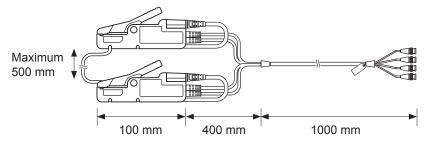
adjustment

Table. Connection method

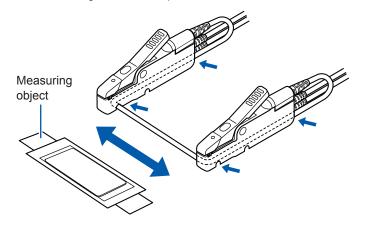
Appx. 8 Measurement Probe (Option)

L2002 Clip Type Probe

Total length: Approx. 1500 mm

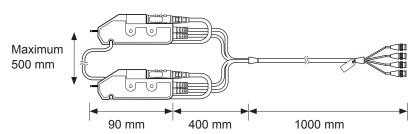


- 1. Arrange the probes so that the distance between the SENSE of the probes is the same as the actual object to be measured with the SENSE of the probes (both red and black) facing inwards.
- 2. Adjust the position of the probes such that the return cable between the probes does not sag, and fix by pushing the return cable into the grooves of the probes.

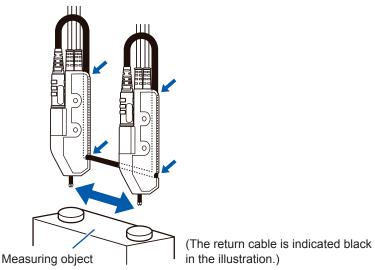


L2003 Pin Type Probe

Total length: Approx. 1490 mm



- 1. Arrange the probes so that the distance between the pin tips of the probe is the same as that between the terminals of the actual measuring object, with the SENSE sides of the probes (both red and black) facing inwards.
- 2. Adjust the position of the probes such that the return cable between the probes does not sag, and fix by pushing the return cable into the grooves of the probes.



Appx. 9 Precautions When Making the Switching Unit

When placing the switching unit between the instrument and the measuring object, you must make the switching unit with the four-terminal pair connection. Here, when making the switching unit, precautions including performing the four-terminal pair connection are described.

This instrument has the measurement terminals with the four-terminal pair connection structure. (Figure. Four-Terminal Pair Connection Structure) This four-terminal pair connection structure prevents the magnetic field created by the measurement current from generating and suppresses an inductive electromotive force to the voltage measurement terminals. The inductive electromagnetic force becomes noise to the measurement voltage, which must be suppressed as much as possible. The inductive electromagnetic force also must be suppressed in the switching unit.

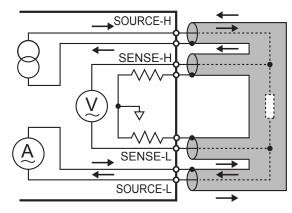


Figure. Four-terminal pair connection structure

Observe the following methods to suppress the inductive electromotive force.

- The loop area formed by the flow-out wire (core wire) and the flow-in wire (shield wire) of the SOURCE-H terminal must be as small as possible.
- The loop area formed by the flow-in wire (core wire) and the flow-out wire (shield wire) of the SOURCE-L terminal must be as small as possible.
- The loop area made by the detection wire (core wire) of the SENSE-H terminal and the detection wire (core wire) of the SENSE-L terminal must be as small as possible.
- The loop formed by the SOURCE wires and the loop formed by the SENSE wires must be kept away from each other.
- The loop formed by the SOURCE wires and the loop formed by the SENSE wires must not be face each other

The relays that are used in the switching unit must observe the following.

- For the relays, 2a or 2c contact type must be used, and the area of each loop must be as small as possible.
- The relays with the rated current that exceeds the measurement current of this instrument (the maximum current is 2.12 A at the measurement current 1.5 Arms) must be used to change over the SOURCE terminals.
- For changing over the SENSE terminals, the latching relays must be used to suppress the effect of the inductive electromagnetic force.
- Furthermore, for changing over the SENSE terminals, the relays with the Au clad cross-bar twin contact type or AgPd contact type must be used to ensure the reliability of the relay contacts.

Integrating the above points, the Pattern layout examples (in the case of the single-sided board) of the switching unit figure is shown. When designing the patterns with two or more layers, the loop can be minimized by layering a pair of patterns over it. (Figure. Pattern Layout Examples of the Switching Unit (in the case of the substrate with the two or more layers))

When wiring with electrical wires, the loop can be reduced by twisting a pair of electrical wires. (Figure. The Wiring Examples of the Switching Unit (when connecting using electrical wires))

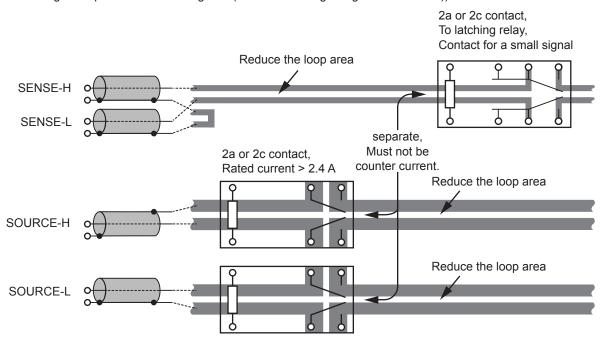


Figure. The pattern layout examples of switching unit (in the single sided board)

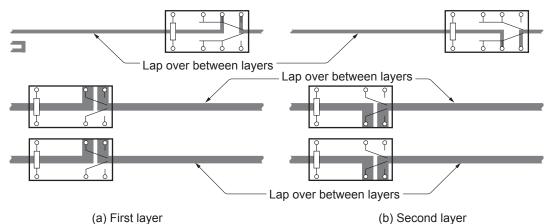


Figure. Pattern layout examples (in the case of the substrate with two or more layers)

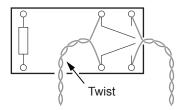
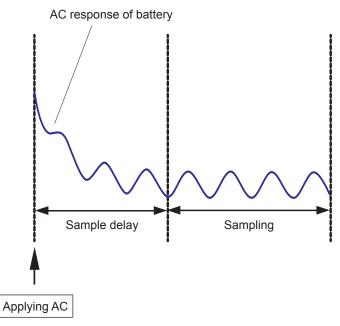


Figure. Wiring example of the switching unit (in the case of wiring the electrical wires)

Appx. 10 Precautions When Measuring the Battery

The stability of AC response

When measuring the impedance, the response may not stabilize immediately after AC is applied. The sampling using the sample delay function after the AC response is stabilized enables one to measure the impedance accurately.



Adjusting SOC (State Of Charge)

The impedance of the battery may vary depending on its SOC. The impedance has a remarkable tendency to vary when the measurement is performed at low frequency. Thus, the SOC must be adjusted. Generally, the proper SOC is within 30% to 80%.

Caution on connections

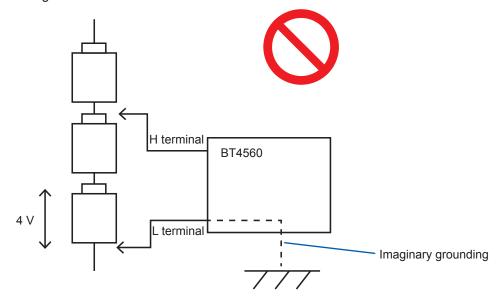
This L terminal of the instrument is controlled to keep its potential at the ground potential. (Imaginary grounding)

If applying an input to the L terminal which provides the L terminal has a potential to the ground, the circuit may be broken. Do not connect equipment other than the instrument during measurement. There is a risk of circuit damage due to improper grounding of equipment. Refer to the following figure.

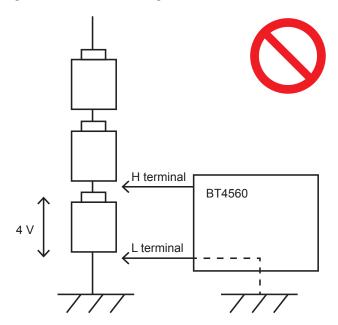
Appx.

Cases that cannot be measured

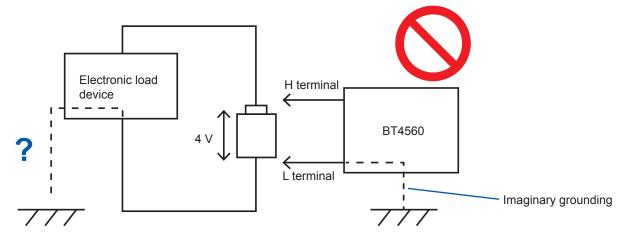
If the voltage exceeds 5 V



In case of measuring the cell that has been grounded



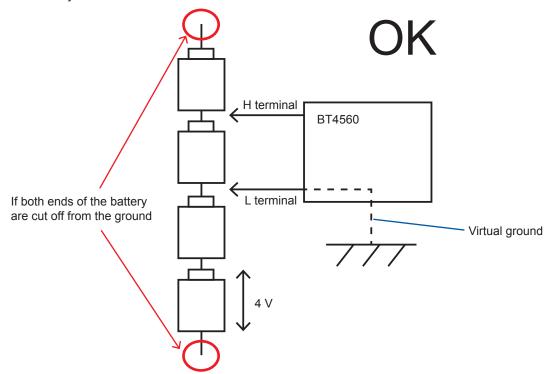
In case of connecting devices other than this instrument



When instruments to be grounded are internally grounded or when capacitance between groundings is large.

Cases that can be measured

If battery modules have not been connected



Appx. 11 Calibrating the Instrument

For the calibration environment, refer to the accuracy guarantee conditions (p. 123).

Calibrating impedance measurement

- Use a standard resistor with non-aged degradation and good temperature characteristics.
- Use a resistor that enables one to configure the four-terminal pair structure, to not be subject to the effect of the lead wires of the resistor.
- For connection between this instrument and the standard resistor, refer to the figure shown below.

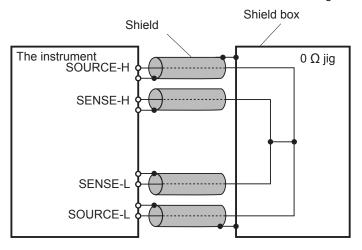


Figure. Calibrating 0 Ω

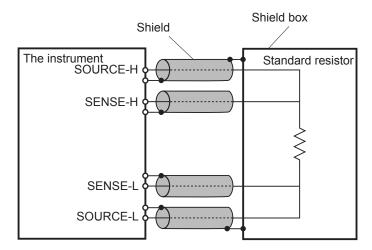


Figure. Connecting to the standard resistor

Calibrating voltage measurement

- Use a generator that can output 7 V DC.
- For the connection between this instrument and the generator, refer to Figure illustrated below.
- You must not input the AC current of this instrument to the generator. This may cause a malfunction of the generator.
- Use the generator with a low output impedance.
- Some of generators may not operate normally.

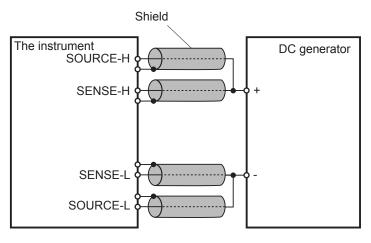


Figure. Connection to the generator

Calibrating temperature measurement

- Calibrate the standard resistor with Pt100 IEC Class A or equivalent.
- For the connection between this instrument and the generator, refer to Figure illustrated below.
- You must use the wiring resistance of both ways less than 10 Ω .
- Use the connection terminals of $\phi 3.5$ four-terminal structure (For the four-pole signal cable, refer to Figure illustrated below.)

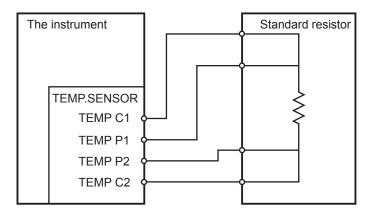


Figure. Connecting to the standard resistor

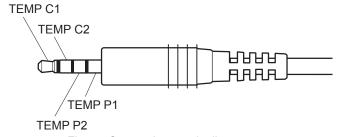


Figure. Connection terminal's structure

Appx.

Appx. 12 Rack Mounting

By removing the screws on the sides, this instrument can be installed in a rack mounting plate.

MARNING

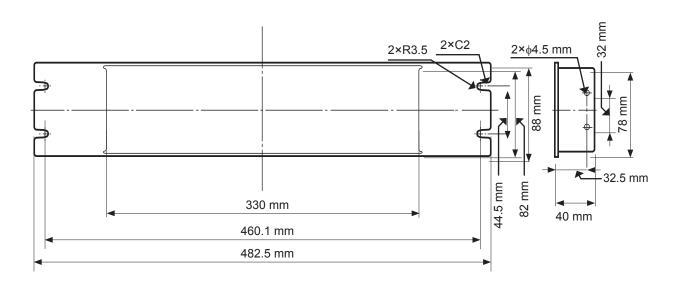


Use the screws that are mounted during shipment to avoid instrument damage and electric shock accidents. (Standard: M3 \times 6 mm, sides: M4 \times 6 mm, when installing rack mounting bracket: M4 \times 10 mm)

If screws are lost or damaged, contact your authorized Hioki distributor or reseller.

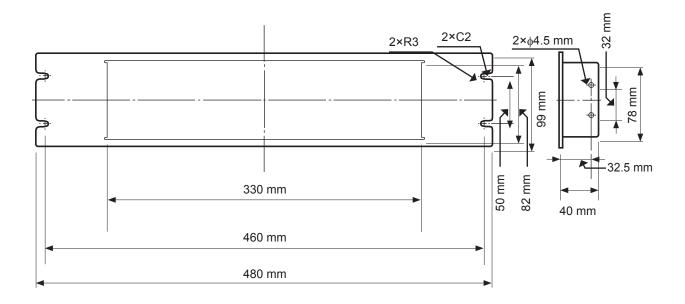
Rack Mounting Plate (EIA)

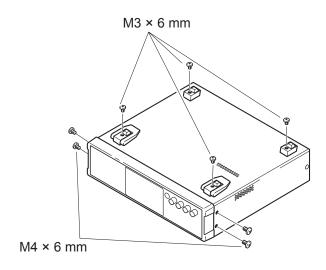




Rack Mounting Plate (JIS)

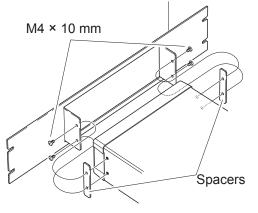






1 Remove the feed from the bottom of the instrument, and the screws from the sides (four near the front).

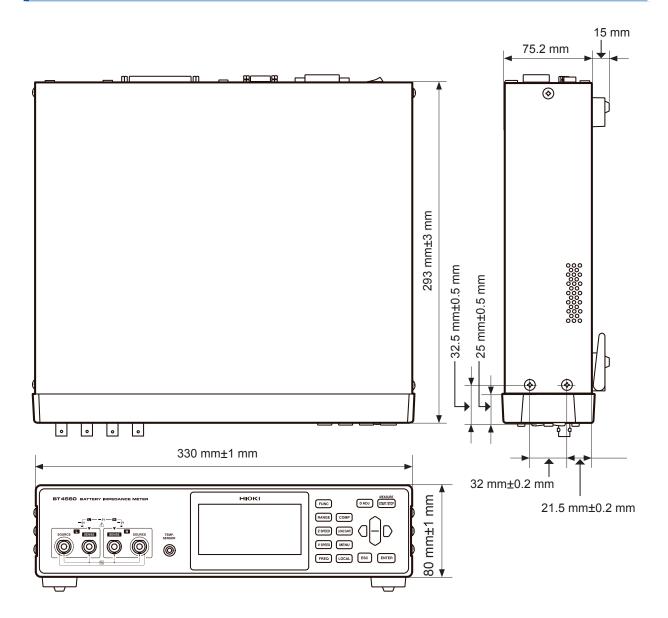


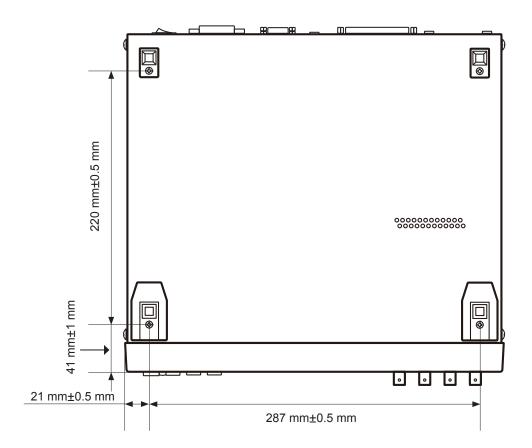


2 Installing the spacers on both sides of the instrument, affix the Rack Mounting Plate with the M4 × 10 screws.

- When installing into the rack, reinforce the installation with a commercially available support stand
- Ensure that the vents on the sides, rear, and bottom are not blocked.

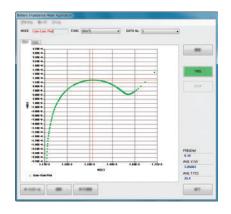
Appx. 13 Dimensional Diagram





Appx. 14 Creating Cole-Cole Plots Using PC Application Softwares

This application software can conduct measurement and draw Cole-Cole plots. Additionally, "ZView[®]" (trademark of another company) from Scribner Associates Inc. also provides detailed analysis based on equivalent circuit analysis.



(1) The application software

The application software creates Cole-Cole plots.

Measurement results can also be output in Excel and CSV files.



(2) The application software included with LabView driver*

The application software included with LabView driver compares multiple overlaid graphs.

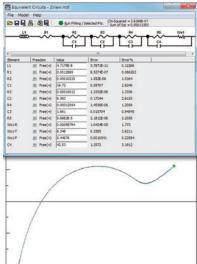
Equipped with a simple equivalent circuit analysis function, this application software also gives insight into electrolyte resistance and reaction resistance.

* The LabView driver can be downloaded from Hioki's website.

(3) AC impedance analysis software "ZView" - 18100 (2) "ZView" - 18100 (2) "ZView" "ZView" "ZView" "

AC impedance analysis software "ZView®" creates certain equivalent circuits based on CSV files output from the application software (1).

By quantifying each element, deteriorated portions in a battery can be analyzed.



Appx. 15 License Information

This instrument uses the following open source software.

Amazon FreeRTOS

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lwlp

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Warranty Certificate



Model	Serial number	Warranty period	
		Three (3) years from date of purchase (/)	
Customer name: Customer address:			

Important

- · Please retain this warranty certificate. Duplicates cannot be reissued.
- Complete the certificate with the model number, serial number, and date of purchase, along with your name and address. The personal information you provide on this form will only be used to provide repair service and information about Hioki products and services.

This document certifies that the product has been inspected and verified to conform to Hioki's standards. Please contact the place of purchase in the event of a malfunction and provide this document, in which case Hioki will repair or replace the product subject to the warranty terms described below.

Warranty terms

- 1. The product is guaranteed to operate properly during the warranty period (three [3] years from the date of purchase). If the date of purchase is unknown, the warranty period is defined as three (3) years from the date (month and year) of manufacture (as indicated by the first four digits of the serial number in YYMM format).
- 2. If the product came with an AC adapter, the adapter is warrantied for one (1) year from the date of purchase.
- 3. The accuracy of measured values and other data generated by the product is guaranteed as described in the product specifications.
- 4. In the event that the product or AC adapter malfunctions during its respective warranty period due to a defect of workmanship or materials, Hioki will repair or replace the product or AC adapter free of charge.
- 5. The following malfunctions and issues are not covered by the warranty and as such are not subject to free repair or replacement:
 - -1. Malfunctions or damage of consumables, parts with a defined service life, etc.
 - -2. Malfunctions or damage of connectors, cables, etc.
 - -3. Malfunctions or damage caused by shipment, dropping, relocation, etc., after purchase of the product
 - -4. Malfunctions or damage caused by inappropriate handling that violates information found in the instruction manual or on precautionary labeling on the product itself
 - -5. Malfunctions or damage caused by a failure to perform maintenance or inspections as required by law or recommended in the instruction manual
 - -6. Malfunctions or damage caused by fire, storms or flooding, earthquakes, lightning, power anomalies (involving voltage, frequency, etc.), war or unrest, contamination with radiation, or other acts of God
 - -7. Damage that is limited to the product's appearance (cosmetic blemishes, deformation of enclosure shape, fading of color, etc.)
 - -8. Other malfunctions or damage for which Hioki is not responsible
 - -9. After disassembly, such as opening the product, has been performed by the customer without permission by Hioki
- 6. The warranty will be considered invalidated in the following circumstances, in which case Hioki will be unable to perform service such as repair or calibration:
 - -1. If the product has been repaired or modified by a company, entity, or individual other than Hioki
 - -2. If the product has been embedded in another piece of equipment for use in a special application (aerospace, nuclear power, medical use, vehicle control, etc.) without Hioki's having received prior notice
- 7. If you experience a loss caused by use of the product and Hioki determines that it is responsible for the underlying issue, Hioki will provide compensation in an amount not to exceed the purchase price, with the following exceptions:
 - -1. Secondary damage arising from damage to a measured device or component that was caused by use of the product
 - -2. Damage arising from measurement results provided by the product
 - -3. Damage to a device other than the product that was sustained when connecting the device to the product (including via network connections)
- 8. Hioki reserves the right to decline to perform repair, calibration, or other service for products for which a certain amount of time has passed since their manufacture, products whose parts have been discontinued, and products that cannot be repaired due to unforeseen circumstances.

HIOKI E. E. CORPORATION 25-10 EN-3







All regional contact information

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